

§ 1.1 Systems of linear equations,

(1.)

Def: A linear equation in the variables $x_1, x_2, x_3, \dots, x_n$ is an equation of the form

$$a_1 x_1 + a_2 x_2 + \dots + a_n x_n = b$$

where $a_1, a_2, \dots, a_n, b$ are real or complex #'s

eg: $5x_1 + 3x_2 + 4x_3 = 7$ is linear

$5x_1^2 + 3x_2 + 4x_3 = 8$ is not linear.

Def: A system of linear equations is a collection of linear equations in the same variables

Example: A system of two linear equations:

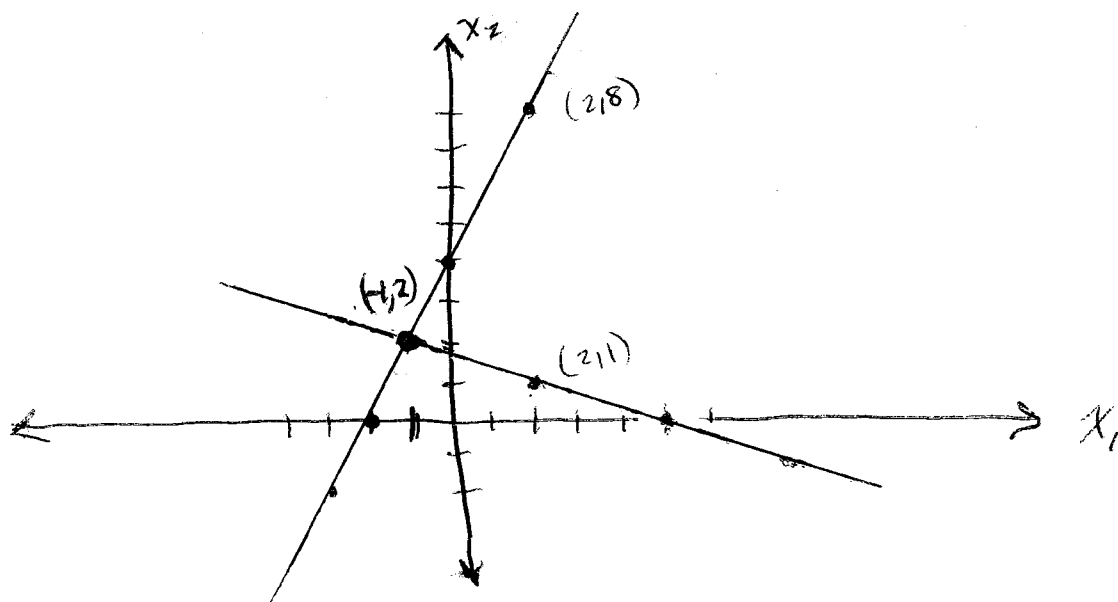
$$x_1 + 3x_2 = 5$$

$$2x_1 - x_2 = -4$$

Note: Solutions to the above system can be thought of as the intersection points of the two lines:

$$x_2 = -\frac{1}{3}x_1 + \frac{5}{3}$$

$$x_2 = 2x_1 + 4$$

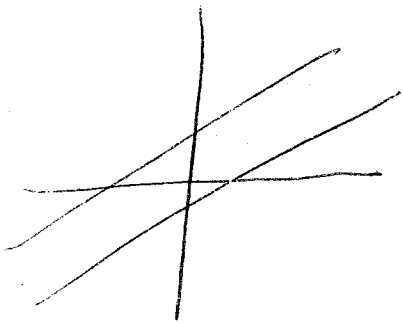


3 Possibilities for solution sets:

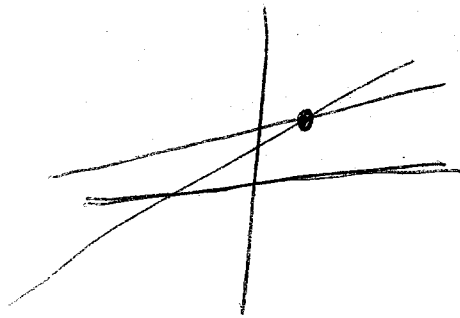
(2.)

1. No solutions
2. Exactly one solution
3. Infinitely many solutions.

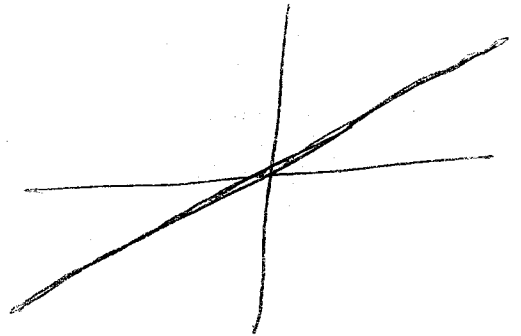
①



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Matrix Notation:

$$\begin{cases} x_1 + 3x_2 = 5 \\ 2x_1 - x_2 = -4 \end{cases}$$

has the coefficient matrix:

$$\begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix}$$

and the augmented matrix

$$\begin{bmatrix} 1 & 3 & 5 \\ 2 & -1 & -4 \end{bmatrix}$$

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Definition: We say a matrix is $m \times n$ provided that it has m rows and n columns.

Example:

$$\begin{bmatrix} 1 & 2 & 4 \\ 6 & 8 & 2 \end{bmatrix} \text{ is } 2 \times 3$$

$$\begin{bmatrix} 1 & 3 \\ 2 & 5 \\ 6 & 11 \end{bmatrix} \text{ is } 3 \times 2$$

Solving a system:

Example: Solve.
$$\begin{cases} x_1 + 3x_2 = 5 \\ 2x_1 - x_2 = -4 \end{cases}$$

$$\begin{bmatrix} 1 & 3 & 5 \\ 2 & -1 & -4 \end{bmatrix}$$

Note: The techniques used in the previous example correspond to the following operations on the augmented matrix.

Elementary Row Operations:

- 1.) (Replacement): Replace a row by the sum of itself and a multiple of another.
- 2.) (Interchange): Interchange two rows.
- 3.) (Scaling) Multiply a row by a non zero constant.

Example: Use elementary row operations to solve

$$\begin{cases} x_1 + 3x_2 = 5 \\ 2x_1 - x_2 = -4 \end{cases}$$

$$\begin{bmatrix} 1 & 3 & 5 \\ 2 & -1 & -4 \end{bmatrix}$$

Definition (1) Two linear systems are equivalent (5.) provided that they have the same solution set.

(2) Two matrices are row equivalent provided that one matrix can be transformed to the other by elementary row operations.

Fact: Two systems of linear equations are equivalent if and only if their augmented matrices are row equivalent.

Example: Solve

$$\begin{cases} x_1 - 3x_3 = 8 \\ 2x_1 + 2x_2 + 9x_3 = 7 \\ x_2 + 5x_3 = -2 \end{cases}$$

$$\begin{bmatrix} 1 & 0 & -3 & 8 \\ 2 & 2 & 9 & 7 \\ 0 & 1 & 5 & -2 \end{bmatrix} \rightarrow$$

Existence & Uniqueness

(6)

Fundamental Questions.

- 1) Is the system consistent?
That is, does a solution exist?
- 2) If a solution exists, is it unique (i.e. the only one)?

Example: We have seen that

$$\begin{cases} x_1 + 3x_2 = 5 \\ 2x_1 - x_2 = -4 \end{cases}$$

has exactly one solution.

That is, a solution exists and it is unique.

Example: solve

$$\begin{cases} x_2 - 4x_3 = 8 \\ 2x_1 - 3x_2 + 2x_3 = 1 \\ 5x_1 - 8x_2 + 7x_3 = 1 \end{cases} \quad \begin{bmatrix} 0 & 1 & -4 & 8 \\ 2 & -3 & 2 & 1 \\ 5 & -8 & 7 & 1 \end{bmatrix}$$

$$\rightarrow \dots \rightarrow \begin{bmatrix} 2 & -3 & 2 & 1 \\ 0 & 1 & -4 & 8 \\ 0 & 0 & 0 & 5/2 \end{bmatrix}$$

Thus the original system is equivalent to

$$\begin{cases} 2x_1 - 3x_2 + 2x_3 = 1 \\ x_2 - 4x_3 = 8 \\ 0x_1 + 0x_2 + 0x_3 = 5/2 \end{cases}$$

which clearly has no solutions.

Examples

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Solve

$$\begin{cases} x_1 + x_2 = 5 \\ 2x_1 + 2x_2 = 10 \end{cases}$$

$$\begin{bmatrix} 1 & 1 & 5 \\ 2 & 2 & 10 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 5 \\ 0 & 0 & 0 \end{bmatrix}$$

which is equivalent to

$$\begin{cases} x_1 + x_2 = 5 \\ 0 = 0 \end{cases}$$

This has infinitely many solutions;

Let x_1 be any thing you like and

take $x_2 = 5 - x_1$.

So, we see that solutions exist but
are not unique.

