

§ 4.3 Linearly Independent Sets; Basis (73)

Def: $\nexists V$ is a vector space and $v_1, \dots, v_p \in V$. The set $\{v_1, \dots, v_p\}$ is Linearly Independent provided that the eq.

$$x_1 v_1 + \dots + x_p v_p = 0 \quad (*)$$

has only the trivial solution.

If the equation $(*)$ has non trivial solutions then $\{v_1, \dots, v_p\}$ is linearly dependent.

Theorem 4: $\nexists S = \{v_1, \dots, v_p\} \subseteq V; p \geq 2; v_i \neq 0$. Then S is L.D. iff there is some v_j which is a linear combination of the preceding vectors $v_1, v_2, \dots, v_{j-1}$.

Prf:

Example 1

$$\text{Let } S = \{x^2 + 2x + 3, x^3 + 1, x^3 + 2x^2 + 4x + 7\} \\ \subseteq P_3$$

Is S L.I. or L.D.?

Example 2: What about

$$S = \{\sin(x), \cos(x)\} \subseteq \left\{ f: [0,1] \rightarrow [0,1] : \begin{array}{l} f \text{ is cont.} \end{array} \right\} ?$$

• Def: $\mathcal{B}$ is an indexed set of vectors
 $\mathcal{B} = \{b_1, \dots, b_p\}$ in V is a basis for H
provided that

1.) $\mathcal{B}$ is L.I.

2.) $H = \text{span}(\mathcal{B})$,

• Note: H could be all of V .

• Example: Let $A = [\vec{a}_1, \dots, \vec{a}_n]$ be an
 $n \times n$ invertible matrix, what does the
Inv. Matrix Theorem say about $\{\vec{a}_1, \dots, \vec{a}_n\}$?

Example: $\{e_1, \dots, e_n\}$ is a basis for $\mathbb{R}^n$, why?

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Example: $\{1, x, x^2, \dots, x^n\}$ is a basis for $\mathbb{P}_n$, why?

Example:

$$\{v_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, v_3 = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}\}$$

Show that $\text{Span}(v_1, v_2, v_3) = \text{Span}(v_1, v_2)$

Theorem 5: Let $S = \{v_1, \dots, v_p\} \subseteq V$;

$$H = \text{Span}(v_1, \dots, v_p).$$

a) If $\exists v_k \in S$ which is a linear comb. of other vectors in S , then

$$H = \text{Span}(v_1, v_2, \dots, v_{k-1}, v_{k+1}, \dots, v_p)$$

b) If $H \neq \{0\}$ then some subset of S is a basis for H .

pt:

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- Bases for $\text{Nul}(A)$, $\text{Col}(A)$:

• Note: We already know how to find bases for $\text{Nul}(A)$ from the last section.

Example: Let

$$B = \begin{bmatrix} 1 & 3 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Find a basis for $\text{Col}(B)$.

Fact: If $A \sim B$ then the columns of A have exactly the same dependences as those of B . (77)

Pf:

Example:

Let $A = \begin{bmatrix} 1 & 3 & 0 & 2 & 0 \\ 0 & 0 & 1 & 5 & 1 \\ 0 & 0 & 1 & 5 & 1 \\ 1 & 3 & 1 & 7 & 1 \end{bmatrix}$

Find a basis for $\text{Col}(A)$.

Thm 6: The pivot columns of A
form a basis for $\text{Col}(A)$.

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Pf:

Note: A basis is...

- 1.) A spanning set that is
as small as possible.
- 2.) A L.I. set that is
as big as possible.

Example: which are bases for $\mathbb{R}^3$?

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} \right\}$$

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$$