

Week 7 summary:

- A matrix  $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$  has an inverse iff  $\det A := a_{11}a_{22} - a_{12}a_{21} \neq 0$ .  
 The inverse of  $A$  is  $A^{-1} := \frac{1}{\det A} \begin{pmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{pmatrix}$ , and  
 $AA^{-1} = A^{-1}A = I := \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ .  
 The solution to the system  $A\vec{x} = \vec{b}$  is  $\vec{x} = A^{-1}\vec{b}$ .
- If  $A\vec{v} = \lambda\vec{v}$ , then  $\vec{v}$  is an eigenvector of  $A$  with eigenvalue  $\lambda$ .  
 To find  $\lambda$ , solve  $\det(A - \lambda I) = 0$  for  $\lambda$ .  
 To find  $v$ , solve  $(A - \lambda I)\vec{v} = 0$  for  $\vec{v}$ .  
Note:  $\det(A - \lambda I) = \lambda^2 - (\text{tr } A)\lambda + (\det A) = 0$ ,  $\text{tr } A := a_{11} + a_{22}$ .
- The system  $\dot{\vec{x}} = A\vec{x}$  has general solution  $\vec{x}(t) = C_1 e^{\lambda_1 t} \vec{v}_1 + C_2 e^{\lambda_2 t} \vec{v}_2$ , where  $\lambda_{1,2}$  are the eigenvalues of  $A$ , and  $\vec{v}_{1,2}$  are the eigenvectors.
- To solve  $\dot{\vec{x}} = A\vec{x} + \vec{b}$ , find the steady-state solution  $\vec{x}_{ss}(t)$  (set  $\dot{\vec{x}} = 0$ ), then solve the homogeneous system (set  $\vec{b} = 0$ ).  
 The general solution is  $\vec{x}(t) = \vec{x}_h(t) + \vec{x}_{ss}(t)$ .