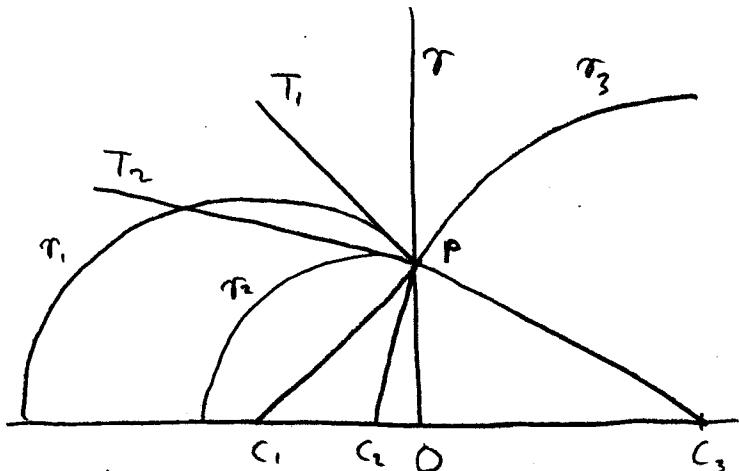


5. "Highschool" hyperbolic geometry

Prop (Stahl 6.1.6): Consider the following diagram, where τ has Euclidean center C_1 and T_i is the tangent line at P .

Then:



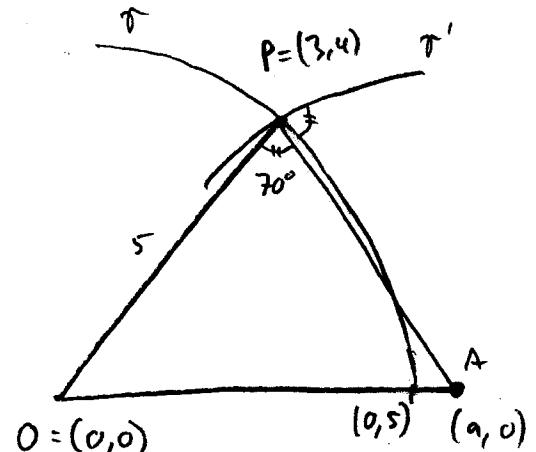
$$\alpha(\tau, T_1) = \alpha(DC_1, P) \quad \alpha(T_1, T_2) = \alpha(C_1, PC_2), \quad \alpha(T_3, \tau) = \pi - \alpha(C_3, PC_3).$$

Proof: Exercise (Hs geometry)

Applications!

Example (Stahl 6.1.2): Let $P = (3, 4)$, and let τ be the bowed geodesic through P centered at $(0, 0)$.

Goal: Construct a bowed geodesic τ' through P with angle 70° to τ .



$$\tan(\alpha AOP) = \frac{4}{3} \Rightarrow \alpha AOP \approx 53.1^\circ \Rightarrow \alpha PAO \approx 56.9^\circ$$

$$\text{Law of sines} \Rightarrow a = \frac{5 \sin 70^\circ}{\sin(\alpha PAO)} \approx 5.6$$

$$AP = \frac{5 \sin(\alpha AOP)}{\sin(\alpha PAO)} \approx 4.8.$$

$$\text{Now, } \alpha(\tau', \tau) = \alpha APO = 70^\circ.$$

(2)

Example (Stahl 6.1.3)

Consider the hyperbolic triangle

through $A = (0, 1)$, $B = (2, 1)$
and $C = (4, 1)$.

$$\begin{aligned} \text{Clearly, } \angle(AC, BC) &= \angle(AB, AC) \\ &= \angle PAR \quad (\text{Prop 6.1.1}) \end{aligned}$$

$$= \cos^{-1} \left(\frac{AP^2 + AR^2 - PR^2}{2 \cdot AP \cdot AR} \right) = \cos^{-1} \left(\frac{2+5-1}{2\sqrt{2}\sqrt{5}} \right) \approx 18.4^\circ$$

$$\begin{aligned} \text{Also by Prop 6.1.1, } \angle(CB, AB) &= \pi - \angle PBQ = \pi - \cos^{-1} \left(\frac{BP^2 + BQ^2 - PQ^2}{2 \cdot BP \cdot BQ} \right) \\ &= \pi - \cos^{-1} \left(\frac{2+2-4}{2\sqrt{2}\sqrt{2}} \right) = \pi - \cos^{-1}(0) = 90^\circ. \end{aligned}$$

Theorem (Stahl 6.1.4): Given any 3 angles whose sum is less than π , they are the angles of some hyperbolic triangle.

Proof: Suppose $\alpha + \beta + \gamma < \pi$ and wlog assume $\alpha < \frac{\pi}{2}$.

Let $A = (0, 1)$, $D = (d, 0)$ s.t. $\angle ADO = \alpha$.

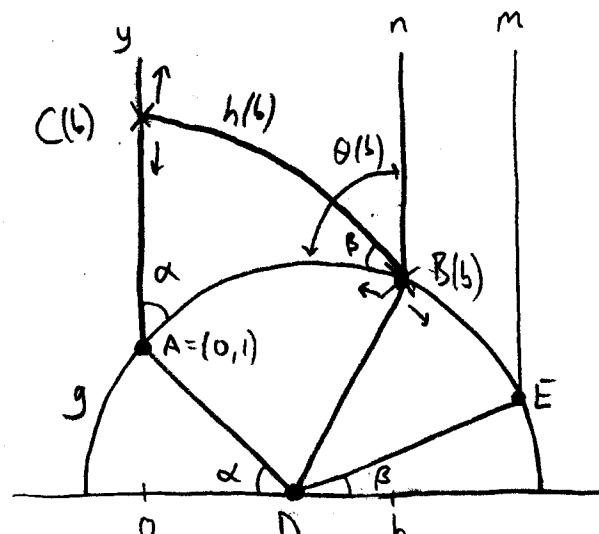
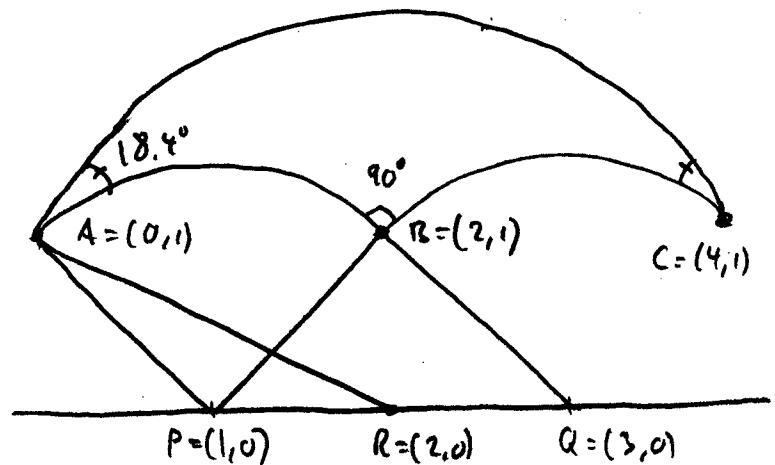
Let g be the geodesic through A centered at D .

Let E be the point on g s.t. $\angle(x\text{-axis}, DE) = \beta$.

Prop 6.1.1 $\Rightarrow \angle(g, y\text{-axis}) = \alpha$, $\angle(m, g) = \beta$.

Pick any $B = (b, -)$ on g between A & E .

Note: $\Theta(b) := \angle(n, g) = \angle(x\text{-axis}, DB(b))$ is a monotonically decreasing function of b , and $\beta < \Theta(b) < \pi - \alpha$.



[3]

Thus, for each b , there is a geodesic $h(b)$ to the y -axis such that $\alpha(h(b), g) = b$.

Let $C(b) = (0, c(b)) = h(b) \cap y\text{-axis}$, and let $\tau(b)$ be the corresponding angle. Note that $0 < \tau(b) < \pi - a$ and τ is continuous.

Since $\pi - a > \tau > 0$, $\exists b_0$ s.t. $\tau(b_0) = \pi$.

Triangle $ABC(b_0)$ is our desired triangle. \square

Next goal: Prove the aforementioned "3 reflection theorem" in H^2 , with relying on Euclid's postulates.

We'll first prove some elementary results in E^2 , and then make a clever argument to extend them to H^2 .

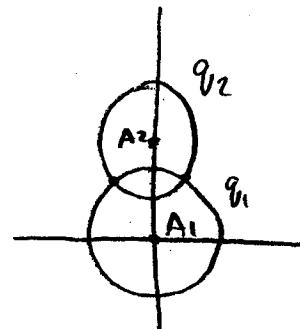
Theorem (Hsu 3.1.1): For $i=1,2$ let $A_i \in E^2$ and let q_i be the circle of center A_i and radius k_i . Let m be the line through A_1 & A_2 . There are 3 possibilities:

- (1) $q_1 \cap q_2 = \emptyset$
- (2) $q_1 \cap q_2$ is a point on m .
- (3) $q_1 \cap q_2 = \{B_1, B_2\}$ with $pm(B_1) = B_2$.

Proof: WLOG assume standard position.

$$A_1 = (0, 0), \quad A_2 = (0, a), \quad m = y\text{-axis}.$$

The circles are the points solving $q_1: x^2 + y^2 = k_1^2$
 $q_2: x^2 + (y-a)^2 = k_2^2$



[4]

Solve this system: $g_1 - g_2: \quad 2ay - a^2 = k_1^2 - k_2^2$

$$\Rightarrow y = \frac{k_1^2 - k_2^2 + a^2}{2a} \quad \text{and} \quad x^2 = k_1^2 - y^2.$$

3 cases: (1) $k_1^2 - y^2 < 0$ no solutions for x

(2) $k_1^2 - y^2 = 0$ one solution: $x = 0$

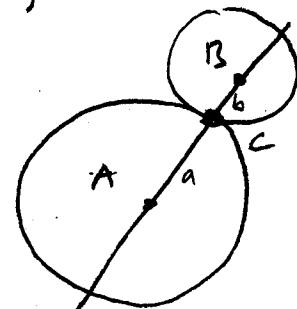
(3) $k_1^2 - y^2 > 0$ $x = \pm \sqrt{k_1^2 - y^2}$ (2 solutions)

It's clear in this case that $P_n(B_1) = B_2$. \square

Cor 3.1.2: let m be the line through $A, B \in \mathbb{E}^2$, and

(e.m.) let $a = d(A, C)$, $b = d(B, C)$.

Then C is the only point at distance a from A and b from B .

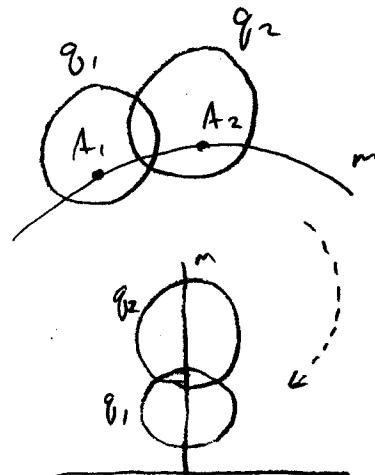


Proof: C is the intersection of circles with centers $A \neq B$, and radii $a \neq b$, and it's on m . Now apply Thm 3.1.1. \square

Theorem (Hsu 3.1.3): Theorem 3.1.1 holds in \mathbb{H}^2 .

Cor. (Hsu 3.1.4): Corollary 3.1.2 holds in \mathbb{H}^2 .

Proof: WLOG use standard position, so m is a vertical geodesic. Since hyperbolic circles are Euclidean circles, the Thm. & Cor. now follow from the Euclidean case (Thm 3.1.1 & Cor 3.1.2). \square



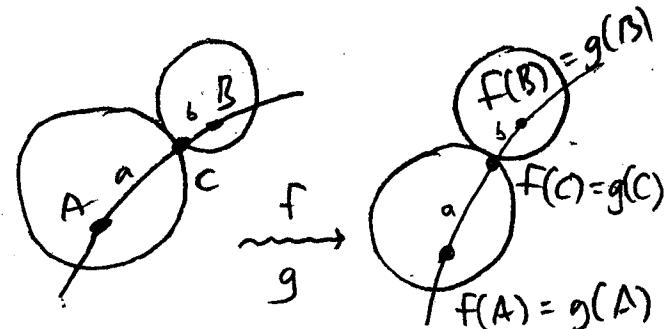
[5]

Prop (Hsu 3.2.1): If $f, g \in \text{Isom}(\mathbb{H}^2)$ agree at points $A, B \in \mathbb{H}^2$, then they agree on the geodesic m through $A \neq B$.

Proof: Let $a = h(A, C)$, $b = h(B, C)$,

where C is any point on m .

Since C is the unique point at distance a from A and b



from B (Cor 3.1.4), $f(C)$ is the unique point at distance a from $f(A) = g(A)$ and distance b from $f(B) = g(B)$.

Same is true for $g(C)$, and so by uniqueness, $f(C) = g(C)$. \square

Theorem (Hsu 3.2.2): Any 2 hyperbolic isometries f, g that agree at 3 noncollinear points are equal.

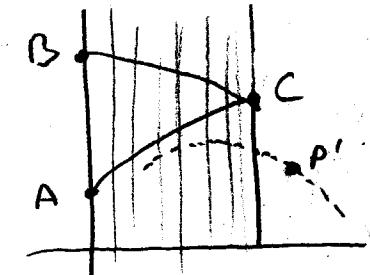
Proof: Let $A = (0, 1)$, $B = (0, t)$,

$C = (s, t)$ be 3 noncollinear points.

Idea: "Color in" all places where $f \neq g$ agree.

By Prop 3.2.1, we can color all vertical geodesics s.t. $0 \leq x \leq s$.

Also, every point P not in this strip has a bowed geodesic from it into the strip, so we can color that geodesic, and P , as well. Thus $f \neq g$ agree on all of \mathbb{H}^2 . \square



Remark: The same proof works for \mathbb{E}^2 as well. Recall that this result was an "absolute" theorem.

[6]

We can now prove the "3 reflections theorem".

The individual parts are left as an exercise (Hw 4).

Prop (Hsu 3.3.1): Given any $A, B \in \mathbb{H}^2$, there is a hyperbolic reflection taking A to B .

Proof: Exercise (Hw 4)

Prop (Hsu 3.3.2): Given $A \in \mathbb{H}^2$ and $B, C \in \mathbb{H}^2$ s.t. $h(A, B) = h(A, C)$, there is a hyperbolic reflection fixing A and taking B to C .

Proof: Exercise (Hw 4)

Theorem (Hsu 3.3.4): Suppose A, B, C and A', B', C' are noncollinear points in \mathbb{H}^2 with $h(A, B) = h(A', B')$, $h(A, C) = h(A', C')$, ϵ , $h(B, C) = h(B', C')$. Then there exists at most 3 hyperbolic reflections whose composition takes A, B, C to A', B', C' respectively.

Proof: Exercise (Hw 4).

Cor (Hsu 3.3.5): Any hyperbolic isometry is the composition of at most 3 reflections. \square

