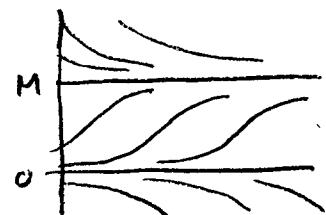
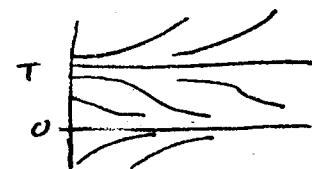


Week 4 summary

- Logistic equation: $y' = r(1 - \frac{y}{M})y$, $y(t) = \frac{M}{1 + Ce^{-rt}}$

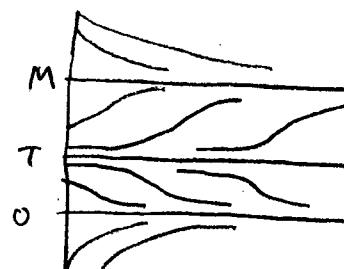


- "Threshold" equation: $y' = -r(1 - \frac{y}{T})y$, $y(t) = \frac{T}{1 + Ce^{-rt}}$



Put these together:

$$y' = -r\left(1 - \frac{y}{M}\right)\left(1 - \frac{y}{T}\right)y$$



- 2nd order linear ODEs: $y'' + p(t)y' + q(t)y = f(t)$

General solution: $y(t) = y_h(t) + y_p(t) = C_1 y_1(t) + C_2 y_2(t) + y_p(t)$.

- Constant coefficients: $y'' + py' + qy = 0$

Assume the soln has the form: $y(t) = e^{rt}$.

Plug back in; solve for r . Get $e^{rt}(r^2 + pr + q) = 0$

3 cases: (i) $r_1 + r_2$ real. $y(t) = C_1 e^{r_1 t} + C_2 e^{r_2 t}$

(ii) $r_1 = r_2$ $y(t) = C_1 e^{r_1 t} + C_2 t e^{r_1 t}$

(iii) $r_{1,2} = a \pm bi$ (Preview): $y(t) = e^{at}(A \cos bt + B \sin bt)$.

(Let's consider case (iii)): $y'' + py' + qy = 0$ and the roots are

$$r_{1,2} = a \pm bi.$$

We have 2 solutions, $y_1(t) = e^{(a+bi)t}$, $y_2(t) = e^{(a-bi)t}$

[2]

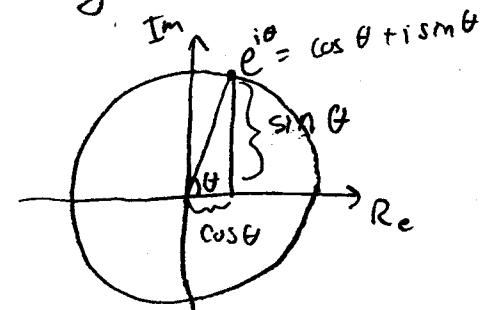
Thus, the general solution is $y(t) = C_1 e^{(a+bi)t} + C_2 e^{(a-bi)t}$.

What does these functions look like???

There's indeed a "better way" to write this general solution.

* Euler's formula: $e^{i\theta} = \cos \theta + i \sin \theta$

Recall: $\cos(-x) = \cos x$, $\sin(-x) = -\sin x$



$$y_1(t) = C_1 e^{(a+bi)t} = e^{at} e^{ibt} = e^{at} (\cos bt + i \sin bt)$$

$$\begin{aligned} y_2(t) &= C_2 e^{(a-bi)t} = e^{at} e^{-ibt} = e^{at} (\cos(-bt) + i \sin(-bt)) \\ &= e^{at} (\cos bt - i \sin bt) \end{aligned}$$

Recall: Since our ODE is linear & homogeneous, we can

- add two solutions
- multiply two solutions

... and still have a solution.

Thus, $\frac{1}{2}(y_1(t) + y_2(t)) = e^{at} \cos bt$ is a solution

and $\frac{1}{2i}(y_1(t) - y_2(t)) = e^{at} \sin bt$ is a solution

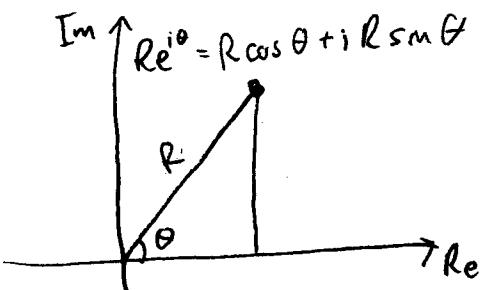
Conclusion: The general solution can be written as

$$y(t) = A e^{at} \cos bt + B e^{at} \sin bt, \text{ or } \boxed{y(t) = e^{at} (A \cos bt + B \sin bt)}$$

Review: Basic complex numbers & Euler's Formula.

In the complex plane, a point z at dist R from $\vec{0}$ & angle θ is

$$Re^{i\theta} = R \cos \theta + i R \sin \theta.$$



From this, it is "easy" to see that

$$\cos(-\theta) = \cos \theta \text{ and } \sin(-\theta) = -\sin \theta.$$

($\theta \mapsto -\theta$ is a reflection across the x-axis. This preserves the x-coordinate but flips the sign of the y-coordinate)

Euler's formula is $e^{it} = \cos t + i \sin t$, and it implies some neat facts: $\begin{cases} e^{it} = \cos t + i \sin t \\ e^{-it} = \cos t - i \sin t \end{cases} \Rightarrow \begin{cases} \frac{1}{2}(e^{it} + e^{-it}) = \cos t \\ \frac{1}{2i}(e^{it} - e^{-it}) = \sin t \end{cases}$

Also, $e^{i\pi} = -1$! Visually,



Another way to see Euler's formula, from Taylor series

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!}, \quad \cos x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!}, \quad \sin x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!}$$

$$e^{it} = 1 + it + \frac{(it)^2}{2!} + \frac{(it)^3}{3!} + \frac{(it)^4}{4!} + \frac{(it)^5}{5!} + \frac{(it)^6}{6!} + \frac{(it)^7}{7!} + \frac{(it)^8}{8!} + \dots$$

$$\cos t = 1 - \frac{t^2}{2!} + \frac{t^4}{4!} - \frac{t^6}{6!} + \frac{t^8}{8!} + \dots$$

$$\sin t = it - i \frac{t^3}{3!} + i \frac{t^5}{5!} - i \frac{t^7}{7!} + \dots$$

$$\Rightarrow e^{it} = \cos t + i \sin t.$$

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Inhomogeneous linear 2nd order ODE's: "forcing term"

$$y'' + p y' + q y = f, \quad p(t), q(t), f(t)$$

* Big idea: $y(t) = C_1 y_1(t) + C_2 y_2(t) + y_p(t)$, where y_1, y_2 are solns to the homogeneous equation, and $y_p(t)$ is any solution to the (inhomogeneous) ODE.

Proof: Suppose we have a particular sol'n $y_p(t)$.

Let $y(t)$ be any other solution. Then

$$\begin{aligned} & y'' + p y' + q y = f \\ & - (y_p'' + p y_p' + q y_p = f) \\ \hline & (y - y_p)'' + p \cdot (y - y_p)' + q \cdot (y - y_p) = 0 \end{aligned}$$

Thus, $y - y_p$ is a solution to the homogeneous equation,
i.e., $y - y_p = C_1 y_1 + C_2 y_2 \Rightarrow y = C_1 y_1 + C_2 y_2 + y_p$.

Method of undetermined coefficients:

- Works only when coefficients $p \neq q$ are constants.

* Big idea: Usually we can guess the form of a particular sol'n!

Example 1: $y'' - 5y' + 4y = e^{3t}$

First, solve the homog. eq'n: $y_h(t) = C_1 e^{4t} + C_2 e^t$.

Next, guess that $y_p(t) = ae^{3t}$ (Think: Why will this work??)

$$y_p'(t) = 3ae^{3t}, \quad y_p''(t) = 9ae^{3t}$$

Plug back in $\frac{1}{2}$, solve for a :

$$(9y'' - 5y' + 4y = e^{3t})$$

$$9ae^{3t} - 5(3ae^{3t}) + 4ae^{3t} = e^{3t}$$

Combine terms... $-2ae^{3t} = e^{3t} \Rightarrow a = -\frac{1}{2}$

Thus, $y_p(t) = -\frac{1}{2}e^{3t}$ and $y(t) = y_h(t) + y_p(t)$, so

$$\boxed{y(t) = C_1 e^{4t} + C_2 e^t - \frac{1}{2} e^{3t}}$$

Think: Why did this work?

* Because the forcing term $f(t)$ and its derivatives had the same form (up to constants).

Example 2: $y'' + 2y' - 3y = 5 \sin 3t.$ $y_h(t) = C_1 e^t + C_2 e^{-3t}$

Problem: If $y_p(t) = a \sin 3t$, $y_p'(t) = 3a \cos 3t$.

Not of the "same form" (so they won't cancel).

How do we fix this?

Ans: Consider a more general particular sol'n:

$$\left. \begin{array}{l} y_p(t) = A \cos wt + B \sin wt \\ y_p'(t) = -wA \cos wt + wB \sin wt \end{array} \right\} \text{have the same form!}$$

So, assume that there's a solution of the form

$$\boxed{y_p(t) = a \cos 3t + b \sin 3t}$$

$$y_p'(t) = -3a \sin 3t + 3b \cos 3t$$

$$y_p''(t) = -9a \cos 3t - 9b \sin 3t.$$

(6)

Plug back in:

$$\begin{aligned} y_p'' + 2y_p' - 3y_p &= (-9a \cos 3t - 9b \sin 3t) + (-6a \sin 3t + 6b \cos 3t) \\ &\quad - (3a \cos 3t + 3b \sin 3t) \\ &= \underbrace{(-12a + 6b)}_0 \cos 3t + \underbrace{(-6a - 12b)}_5 \sin 3t = \underbrace{5 \sin 3t}_{f(t)} \end{aligned}$$

Thus, we have $\begin{cases} -12a + 6b = 0 \\ -6a - 12b = 5 \end{cases} \Rightarrow a = -\frac{1}{6}, b = -\frac{1}{3}$

$$\Rightarrow y_p(t) = -\frac{1}{6} \cos 3t - \frac{1}{3} \sin 3t$$

The general solution is therefore

$$y(t) = y_h(t) + y_p(t) = \boxed{C_1 e^t + C_2 e^{-3t} + \left(-\frac{1}{6} \cos 3t - \frac{1}{3} \sin 3t \right)}.$$

Example 3: (polynomial forcing term).

$$y'' + 2y' - 3y = 6t^2 + t - 2. \quad \text{Again, } y_h(t) = C_1 e^t + C_2 e^{-3t}$$

Assume there's a particular sol'n of the form $y_p(t) = at^2 + bt + c$ Why?? (b/c $y_p'' + 2y_p' - 3y_p$ will also be a degree-2 poly.)So, all we have to do is find a, b, c .Plug back in: $y_p' = 2at + b, \quad y_p'' = 2a$

$$y'' + 2y' - 3y = (2a) + 2(2at + b) - 3(at^2 + bt + c) = 6t^2 + t - 2$$

$$\underbrace{(-3a)t^2}_6 + \underbrace{(4a - 3b)t}_1 + \underbrace{(2a + 2b - 3c)}_{-2} = 6t^2 + t - 2$$

$$\begin{cases} -3a = 6 \\ 4a - 3b = 1 \\ 2a + 2b - 3c = -2 \end{cases} \Rightarrow \begin{cases} a = -2 \\ b = -3 \\ c = -\frac{8}{3} \end{cases} \Rightarrow y_p(t) = -2t^2 - 3t - \frac{8}{3}$$

$$\boxed{y(t) = C_1 e^t + C_2 e^{-3t} - 2t^2 - 3t - \frac{8}{3}}$$

What could go wrong with this method?

What if the forcing term is a solution to the homogeneous eq'n?

Example 4: $y'' - 3y' + 2y = e^{2t}$

Characteristic eq'n: $r^2 - 3r + 2 = (r-1)(r-2)$

$$\Rightarrow y_h(t) = C_1 e^t + C_2 e^{2t}$$

Assume there's a particular sol'n of the form $y_p(t) = ae^{2t}$.

$$y_p' = 2ae^{2t}, \quad y_p'' = 4ae^{2t}$$

Plug back in: $(4ae^{2t}) - 3(2ae^{2t}) + 2(ae^{2t}) = e^{2t}$

$$\Rightarrow 0ae^{2t} = e^{2t} \quad \text{No solution for } a!$$

What happened?

Note: ae^{2t} solves: $y'' - 3y' + 2y = 0$ (homog. eq'n),

thus it will never solve $y'' - 3y' + 2y = e^{2t} \neq 0$.

To "fix" this, assume instead that $y_p(t) = ate^{2t}$

$$y_p'(t) = 2ate^{2t} + ae^{2t}, \quad y_p''(t) = 4ate^{2t} + 4ae^{2t}$$

Plug back in: $(4ate^{2t} + 4ae^{2t}) - 3(2ate^{2t} + ae^{2t}) + 2(ate^{2t}) = e^{2t}$

$$\Rightarrow 0ate^{2t} + ae^{2t} = e^{2t}$$

$$\Rightarrow a = 1 \Rightarrow y_p(t) = te^{2t}$$

Thus, the general sol'n is $y(t) = y_h(t) + y_p(t)$

$$y(t) = C_1 e^t + C_2 e^{2t} + te^{2t}$$

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$$\text{Example 5: } y'' + 2y' - 3y = 5 \sin 3t + 6t^2 + t - 2 \quad (*)$$

$$\text{Again, } y_n(t) = C_1 e^t + C_2 e^{-3t}.$$

Recall that $-\frac{1}{6} \cos 3t - \frac{1}{3} \sin 3t$ solves $y'' + 2y' - 3y = 5 \sin 3t$ (Ex 2)

and $-2t^2 - 3t - \frac{8}{3}$ solves $y'' + 2y' - 3y = 6t^2 + t - 2$ (Ex 3)

Convince yourself that $y_p(t) = -\frac{1}{6} \cos 3t - \frac{1}{3} \sin 3t - 2t^2 - 3t - \frac{8}{3}$
solves (*).

Thus, the gen'l solution is $y(t) = y_n(t) + y_p(t)$, i.e,

$$y(t) = C_1 e^t + C_2 e^{-3t} - \frac{1}{6} \cos 3t - \frac{1}{3} \sin 3t - 2t^2 - 3t - \frac{8}{3}$$

In general: (Combination forcing terms).

* Suppose $y'' + py' + qy = f(t)$ has sol'n $y_f(t)$

and $y'' + py' + qy = g(t)$ has sol'n $y_g(t)$,

then $y'' + py' + qy = \alpha f(t) + \beta g(t)$ has sol'n $\alpha y_f(t) + \beta y_g(t)$.

Application: Harmonic Motion.

Recall mass-spring systems:

Let $x(t)$ = displacement of the mass.

Then $x(t)$ satisfies the following ODE: $mx'' + cx' + kx = f(t)$

(c = damping const, ω_0 = frequency, $f(t)$ driving force)

Most basic case: Simple harmonic motion (no damping or driving force).

$$x'' + kx = 0 \quad k = \omega^2 > 0 \quad (\text{Here, } \omega \text{ will be "frequency"})$$

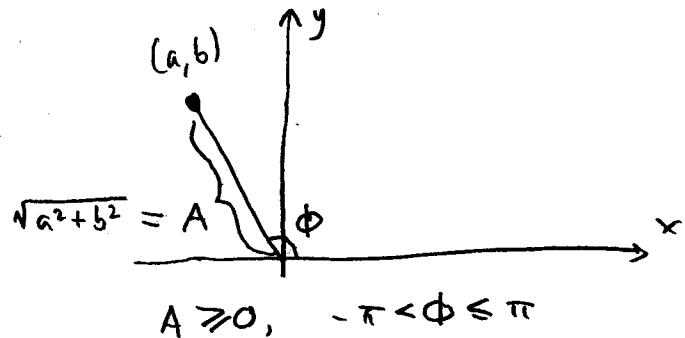
$$\boxed{x'' = -\omega^2 x} \Rightarrow \boxed{x(t) = a \cos \omega t + b \sin \omega t}$$

(What does this function "look like"?)

Here's a trick: we can actually write it as a single cosine wave!

let's switch to polar coordinates:

$$*(a, b) = (\sqrt{a^2 + b^2} \cos \phi, \sqrt{a^2 + b^2} \sin \phi)$$



Sneaky little trick:

$$x(t) = \boxed{a} \cos(\omega t) + \boxed{b} \sin(\omega t)$$

$$= A \cos \phi \cos(\omega t) + A \sin \phi \sin(\omega t)$$

$$= A \cos(\phi - \omega t) \quad \text{Try identity: } \cos(x - y) = \cos x \cos y + \sin x \sin y$$

$$= A \cos(\omega t - \phi).$$

Big idea: Any function $x(t) = a \cos(\omega t) + b \sin(\omega t)$ can be written as a single cosine wave, with:

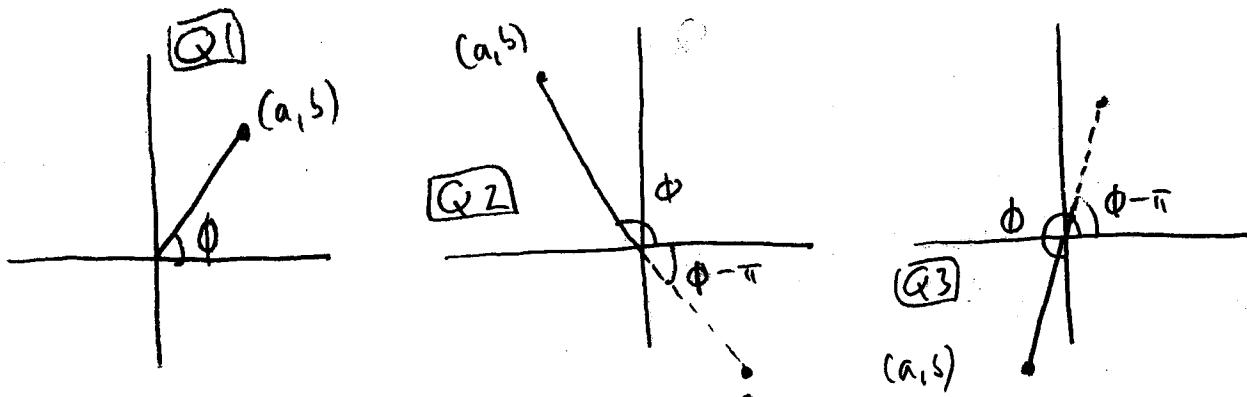
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* amplitude $A = \sqrt{a^2 + b^2}$

* phase shift $\frac{\phi}{\omega}$, where " $\phi = \tan^{-1}(b/a)$ ".

$$\text{So, } x(t) = A \cos(\omega t - \phi) = \boxed{A \cos(\omega(t - \frac{\phi}{\omega}))}$$

Note: Since $-\frac{\pi}{2} < \phi < \frac{\pi}{2}$, $\phi = \begin{cases} \arctan(b/a) & Q 1, 4 \\ \arctan(b/a) + \pi & Q 2 \\ \arctan(b/a) - \pi & Q 3 \end{cases}$

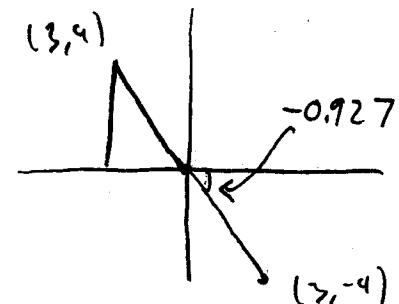


what your calculator would say
(a, b) is.

Example: $x(t) = -3 \cos t + 4 \sin t$

$$A = \sqrt{3^2 + 4^2} = 5$$

$$\arctan(-4/3) = -0.927$$



according to your calculator

$$\text{So } \phi = -0.927 + \pi$$

$$\Rightarrow x(t) = 5 \cos[t - (-0.927 + \pi)]$$

