

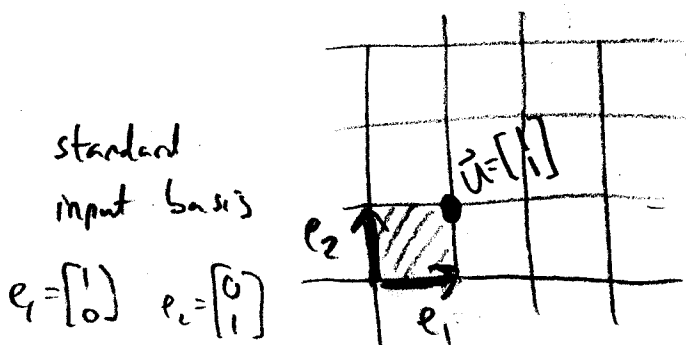
(7) Change of basis

□

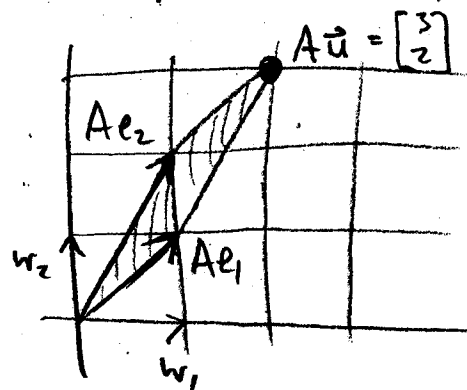
Big idea: $A = M^{-1} B M$
 ↖ "change of basis" matrix

Example: Consider $A = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$

wrt input basis $v_1 = e_1, v_2 = e_2$
 output basis $w_1 = e_1, w_2 = e_2$



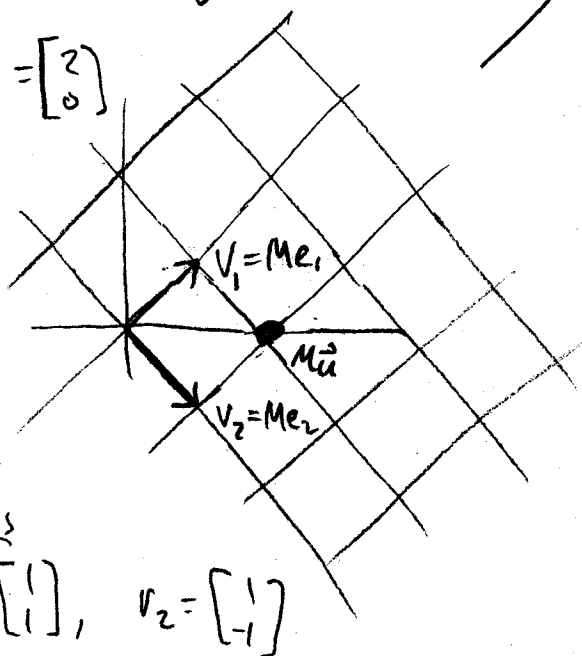
A



Say $u = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

M

$$Mu = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$



new

input basis

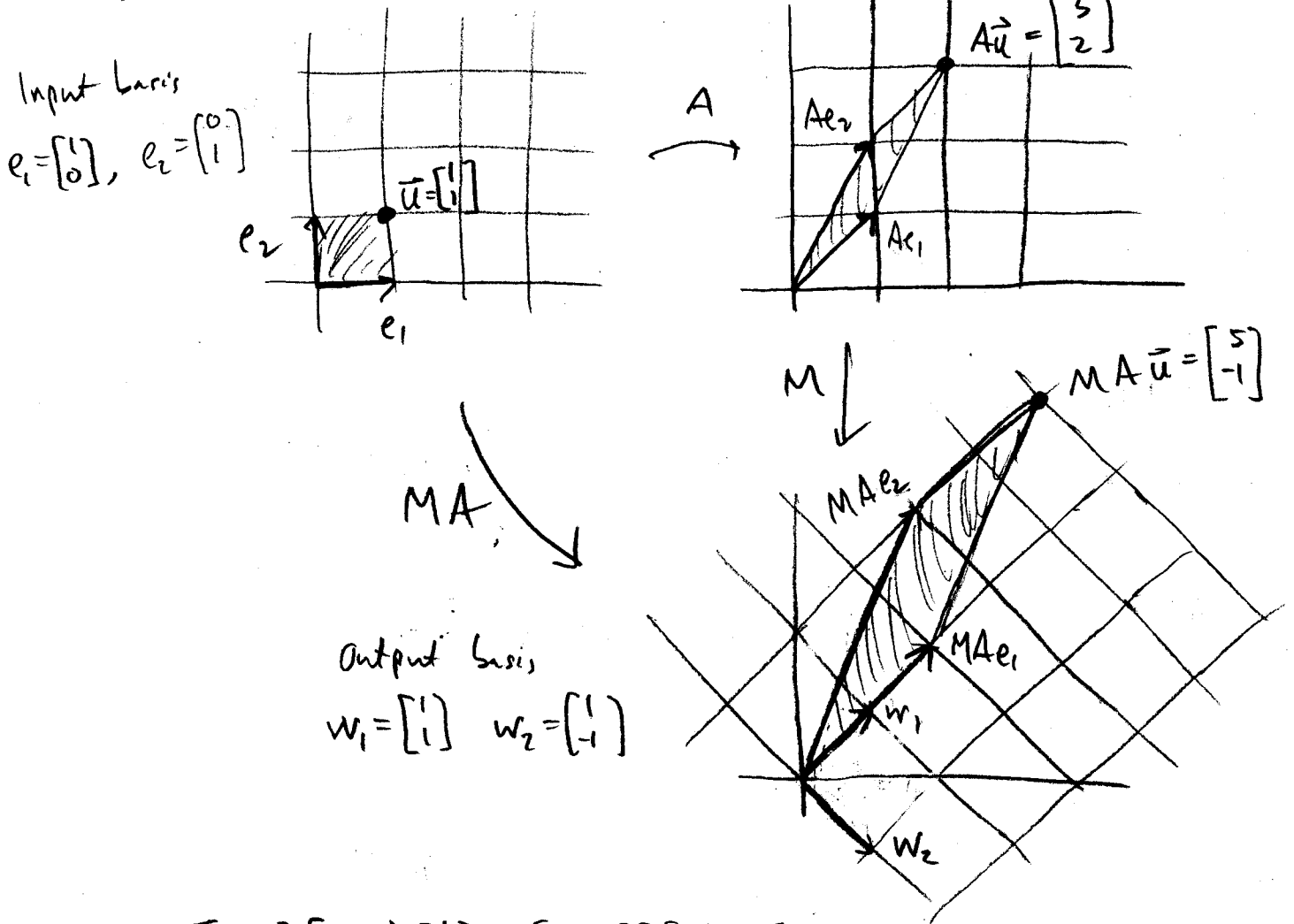
$$v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$A M^{-1}$

standard output basis
 $w_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, w_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

2

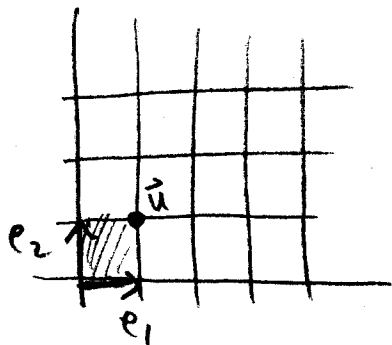
Now, let's see what happens if we change the output basis instead.



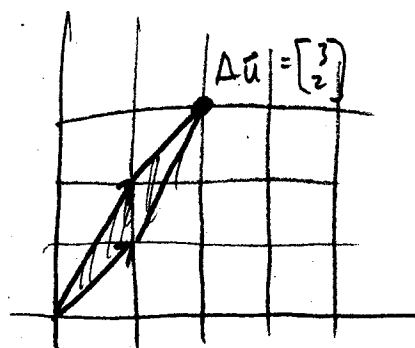
$$MA\vec{u} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ -1 \end{bmatrix}$$

Also, $MA\vec{e}_1 = \begin{bmatrix} 2 & 3 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$, $MA\vec{e}_2 = \begin{bmatrix} 2 & 3 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$

* Now, let's change both input & output bases: $v_1=w_1=\begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $v_2=w_2=\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ 3

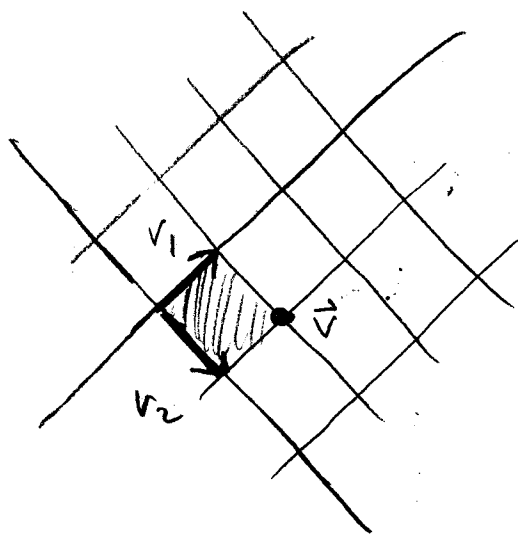


A
→

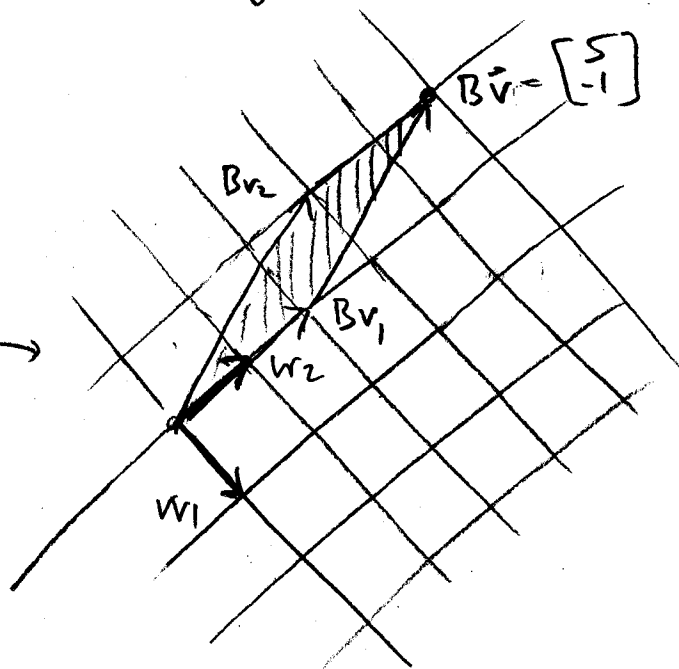


M
↓

M
↓



B
→



We have $A = M^{-1} B M$

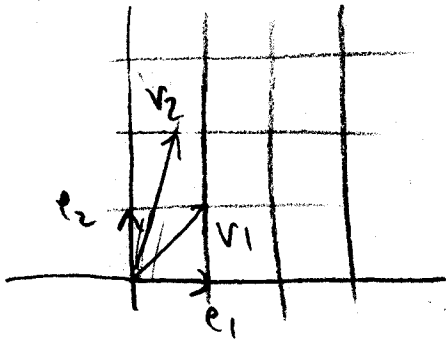
or $B = M A M^{-1}$

4

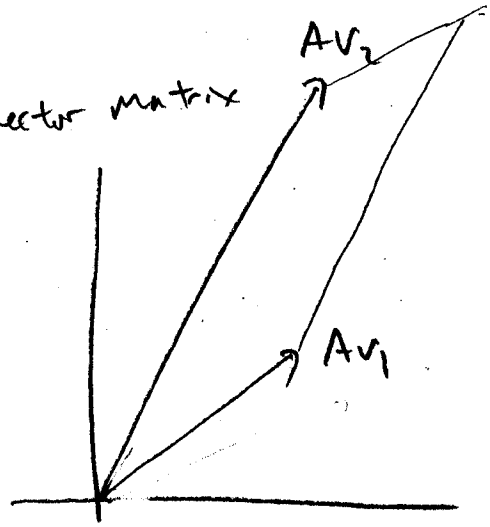
Special case:

$$\Lambda = S^{-1}AS$$

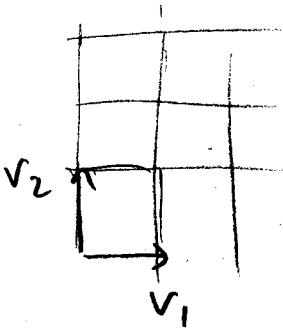
e-vector matrix



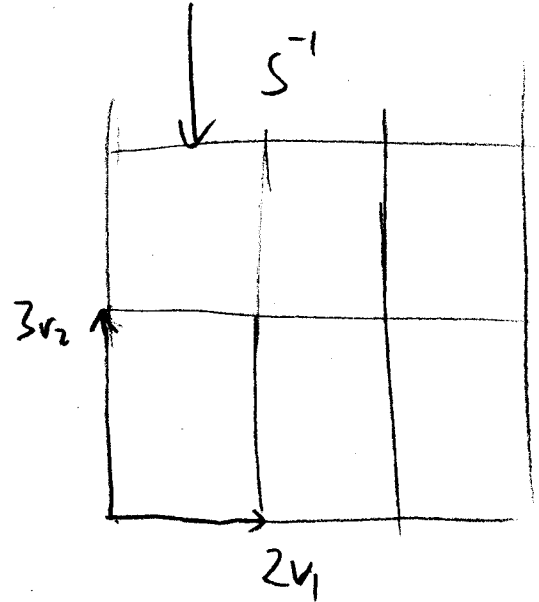
A



S⁻¹



$$\Lambda = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$$



$$S^{-1}: v_1 \mapsto e_1$$

$$v_2 \mapsto e_2$$