

7. Euclidean structure:

Goal: Abstract the concept of Euclidean distance.

Let's review basic Euclidean structure.

Let X be a real n -dimensional Euclidean space (e.g., from vector calculus), with 0 the zero vector.

The length of $x \in X$, denoted $\|x\|$ = distance from x to 0 .

By the Pythagorean theorem, $\|x\| = \sqrt{x_1^2 + \dots + x_n^2}$.

The dot product of $x, y \in X$ is $(x, y) = \sum_{i=1}^n x_i y_i$.

Clearly, $\|x\|^2 = (x, x)$.

Since the dot product is symmetric & bilinear,

$$\begin{aligned} (x+y, x+y) &= (x, x) + 2(x, y) + (y, y) \\ &= \|x\|^2 + 2(x, y) + \|y\|^2 = \|x+y\|^2 \end{aligned}$$

$$(x-y, x-y) = \|x\|^2 - 2(x, y) + \|y\|^2 = \|x-y\|^2 \quad (*)$$

Note that this is independent of choice of coordinate system.

Geometrically, we understand $\|x\|$, $\|y\|$, and $\|x-y\|$.

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To understand (x, y) , we'll pick a "special" x & y .

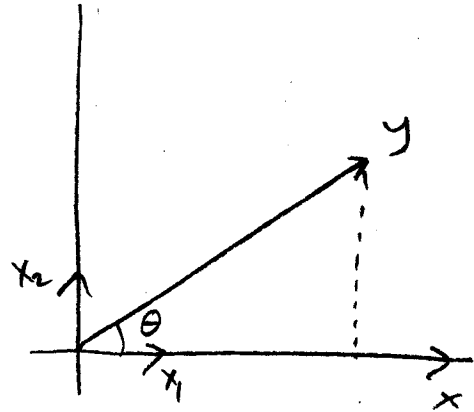
Given any coordinate system (orthogonal basis);

Pick x to be a scalar of x_1

Pick $y \in \text{Span}(x_1, x_2)$.

$$x = (\|x\|, 0, \dots, 0)$$

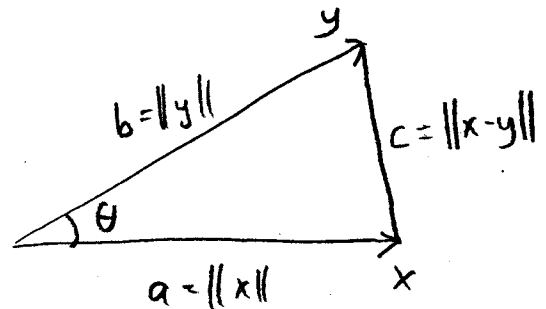
$$y = (\|y\| \cos \theta, \|y\| \sin \theta, 0, \dots, 0)$$



$$\Rightarrow (x, y) = \|x\| \|y\| \cos \theta \Rightarrow \boxed{\cos \theta = \frac{(x, y)}{\|x\| \cdot \|y\|}}$$

We can derive the law of cosines

$$\text{from } (*): \quad c^2 = a^2 + b^2 - 2ab \cos \theta.$$



The dot product gives us a notion of geometry (lengths and angles). We can abstract this

Def: A Euclidean structure in a real vector space is endowed by an inner product, which is a symmetric bilinear form with the additional property that $(x, x) \geq 0$ with equality iff $x = 0$ ("positivity").

We'll show that all of Euclidean geometry follows from having an inner product.

* Throughout, assume that X is an n -dimensional real inner product space.

Def: The norm of $x \in X$ is $\|x\| = (x, x)^{1/2}$, and the distance between $x, y \in X$ is $\|x - y\|$.

Theorem 7.1 (Cauchy-Schwarz). For all $x, y \in X$, $|(x, y)| \leq \|x\| \cdot \|y\|$.

Proof: Define a function $g: \mathbb{R} \rightarrow \mathbb{R}$ as $g(t) = \|x + ty\|^2 \geq 0$.

Write $g(t) = \|x\|^2 + 2t(x, y) + t^2\|y\|^2$.

Assume $y \neq 0$ (result is trivial in this case).

Put $t = \frac{-(x, y)}{\|y\|^2}$:

$$g(t) = \|x\|^2 - \frac{2(x, y)^2}{\|y\|^2} + \frac{(x, y)^2}{\|y\|^2} = \|x\|^2 - \frac{(x, y)^2}{\|y\|^2} \geq 0 \quad \square$$

Cor: For any $x, y \in X$, $-1 \leq \frac{(x, y)}{\|x\| \cdot \|y\|} \leq 1 \quad \square$

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Def: The angle θ between $x, y \in X$ is $\theta = \cos^{-1} \frac{(x, y)}{\|x\| \cdot \|y\|}$.

Theorem 7.2: $\|x\| = \max \{ (x, y) : \|y\| = 1 \}$.

Proof: Exercise (Hw).

Theorem 7.3 (Triangle inequality): For all $x, y \in X$, $\|x+y\| \leq \|x\| + \|y\|$.

Proof: Note that $\|x+y\|^2 = \|x\|^2 + 2(x, y) + \|y\|^2$
 $\leq \|x\|^2 + 2\|x\| \cdot \|y\| + \|y\|^2$ (Cauchy-Schwarz)
 $= (\|x\| + \|y\|)^2$.

□

Def: Two vectors $x, y \in X$ are orthogonal if $(x, y) = 0$. We write this as $x \perp y$.

Remark: If $x \perp y$, then $\|x+y\|^2 = \|x\|^2 + \|y\|^2$. (Pythagorean theorem.)

Def: A basis x_1, \dots, x_n for X is orthonormal (w.r.t. a Euclidean structure) if $(x_i, x_j) = \delta_{ij} = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$.

Theorem 7.4 (Gram-Schmidt): Given an arbitrary basis x_1, \dots, x_n , there is a related orthonormal basis u_1, \dots, u_n for which $u_k \in \text{Span}(x_1, \dots, x_k)$.

Proof: Just construct it.

If $\|u\|=1$, define $\text{proj}_u(x) = (x, u)u$.

Put $y_1 = x_1$

$$u_1 = \frac{y_1}{\|y_1\|}$$

$$y_2 = x_2 - \text{proj}_{u_1} x_2$$

$$u_2 = \frac{y_2}{\|y_2\|}$$

$$y_3 = x_3 - \text{proj}_{u_1} x_3 - \text{proj}_{u_2} x_3$$

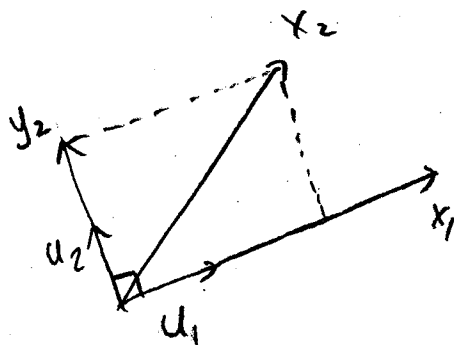
$$u_3 = \frac{y_3}{\|y_3\|}$$

$$\vdots$$

$$y_k = x_k - \sum_{i=1}^{k-1} \text{proj}_{u_i} x_k$$

$$\vdots$$

$$u_k = \frac{y_k}{\|y_k\|}$$



It is easy to check that this works. \square

Remark: When put in matrix form, the matrix $A := [x_1 \ x_2 \ \dots \ x_n]$

can be factored as

$$\begin{bmatrix} | & | & & | \\ x_1 & x_2 & \dots & x_n \\ | & | & & | \end{bmatrix} = \begin{bmatrix} | & | & & | \\ u_1 & u_2 & \dots & u_n \\ | & | & & | \end{bmatrix} \begin{bmatrix} (x_1, u_1) & (x_2, u_1) & (x_3, u_1) & \dots \\ 0 & (x_2, u_2) & (x_3, u_2) & \dots \\ \vdots & 0 & (x_3, u_3) & \dots \\ & \vdots & 0 & \dots \\ & & & \ddots \end{bmatrix}$$

$$A = Q \cdot R$$

This is called the QR-factorization of A .

R is upper-triangular because $u_k \in \text{Span}(x_1, \dots, x_k)$.

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If x_1, \dots, x_n is an orthonormal basis, then for any $x \in X$,

$$x = \sum_{j=1}^n a_j x_j \quad \text{where } a_j = (x, x_j).$$

Moreover, if $y = \sum_{k=1}^n b_k x_k$, then

$$(x, y) = \left(\sum a_j x_j, \sum b_k x_k \right) = \sum_{j=1}^n (a_j x_j, b_j x_j) = \sum_{j=1}^n a_j b_j.$$

In particular, if $y = x$, then $\|x\|^2 = \sum_{j=1}^n a_j^2$.

Thus, the mapping $X \rightarrow \mathbb{R}^n$, $x \mapsto (a_1, \dots, a_n)$, $a_j = (x, x_j)$

is an isomorphism that carries the inner product of X to the standard dot product of \mathbb{R}^n .

Theorem 7.5: Every linear function $l \in X'$ can be written as

$$l(x) = (x, y) \quad \text{for some } y \in X.$$

Proof: Let x_1, \dots, x_n be an orthonormal basis, and let $b_k = l(x_k)$.

$$\text{Put } y = \sum_{k=1}^n b_k x_k.$$

Claim: This works. (Easy to check). □

Corollary: The mapping $R_y: X \rightarrow X'$, $y \mapsto (-, y)$ is an isomorphism.

Remark: There is an analogous map $L_x: X \rightarrow X'$, $x \mapsto (x, -)$.

Def: Let Y be a subspace of X . The orthogonal complement of Y is the set $\{x \in X : (x, y) = 0 \ \forall y \in Y\}$.

Remark: In Section 2, we defined $Y^\perp = \{l \in X' : (l, y) = 0 \ \forall y \in Y\}$.

Under the natural identification $x \xrightarrow{L_x} (x, -)$, these two sets are the same, thus we will also denote the orthogonal complement of Y by Y^\perp .

Theorem 7.6: For any subspace Y of X , $X = Y \oplus Y^\perp$.

Proof: We must show that for any $x \in X$, we can uniquely write $x = y + y^\perp$, where $y \in Y$, $y^\perp \in Y^\perp$.

Uniqueness: Suppose $x = y + y^\perp = z + z^\perp$, $y, z \in Y$, $y^\perp, z^\perp \in Y^\perp$.

$$\text{Then } y - z = z^\perp - y^\perp \in Y \cap Y^\perp \Rightarrow y - z \perp y - z$$

$$\Rightarrow 0 = (y - z, y - z) = \|y - z\|^2 \Rightarrow y = z.$$

Existence: Let x_1, \dots, x_k be an orthonormal basis of Y .

Extend to an orthonormal basis x_1, \dots, x_n of X .

$$\text{We get } x = \sum_{j=1}^{\hat{n}} a_j x_j = \sum_{i=1}^k a_i x_i + \sum_{j=k+1}^{\hat{n}} a_j x_j = y + y^\perp. \quad \square$$

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Def: The map $P_Y: X \rightarrow X$, $x = y + y^\perp \mapsto y$ is called the orthogonal projection of x into Y .

Theorem 7.7: P_Y is linear and idempotent (i.e., $P_Y^2 = P_Y$).

Proof: Exercise.

Theorem 7.8: Let $Y \subseteq X$ be a subspace. Then $P_Y(x) = z$,

where $\|x - z\| = \min\{\|x - y\| : y \in Y\}$.

Proof: Let $y = P_Y(x)$, and

write $x - z = (y - z) + y^\perp$.

By Pythagorean theorem, $\|x - z\|^2 = \|y - z\|^2 + \|y^\perp\|^2$ is minimized

when $z = y$. □

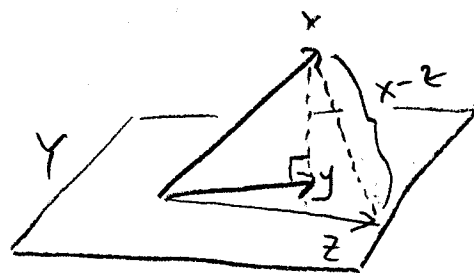
Now, let X, U be Euclidean spaces and $A: X \rightarrow U$ linear.

We can identify X with X' and U with U' , and under

this identification, the transpose of A maps $U \rightarrow X$.

We call the transpose of A the adjoint of A ,

denoted A^* .



Full definition: Let $A: X \rightarrow U$ be a linear map between

Euclidean spaces. For any $u \in U$, $l(x) = (Ax, u)$ is a

linear function $X \rightarrow \mathbb{R}$. By Theorem 7.5, for some $y \in X$,

$$l(x) = (x, y) = (Ax, u).$$

The vector $y \in X$ depends (linearly) on $u \in U$, i.e., for some

$$\text{function } A^*: U \rightarrow X, \quad y = A^*u.$$

Thus, we have $(x, A^*u) = (Ax, u)$

\uparrow scalar product in X \nwarrow scalar product in U .

Theorem 7.9:

(i) If $A, B: X \rightarrow U$ are linear, then $(A+B)^* = A^* + B^*$.

(ii) If $A: X \rightarrow U$, $C: U \rightarrow V$ are linear, then $(CA)^* = A^*C^*$.

(iii) If $A: X \rightarrow X$ is 1-1, then $(A^{-1})^* = (A^*)^{-1}$.

(iv) $(A^*)^* = A$.

Proof: Let $x \in X$, $u \in U$, $v \in V$.

$$(i) \quad ((A+B)x, u) = (Ax, u) + (Bx, u) = (x, A^*u) + (x, B^*u) = (x, (A^* + B^*)u). \quad \checkmark$$

$$(ii) \quad (CAx, v) = (Ax, C^*v) = (x, A^*C^*v) \quad \checkmark$$

$$(iii) \quad \text{By (ii) \& the easy fact that } I^* = I: \quad I = (A^{-1}A)^* = A^*(A^*)^{-1}. \quad \checkmark$$

$$(iv) \quad (Ax, u) = (u, Ax) = (A^*u, x) = (u, A^{**}x) = (A^{**}x, u). \quad \checkmark$$

□

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As before, the matrix representations of A & A^* are transposes of each other.

Application: "least squares."

Example: Consider 3 data points in \mathbb{R}^2 : $(1,1)$, $(2,2)$, $(3,2)$.

Goal: Find the "best fit" line

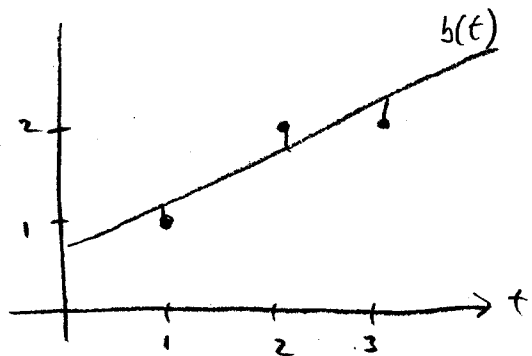
$$b(t) = C + Dt.$$

A "perfect solution" would solve the

following:

$$\begin{cases} C + D = 1 \\ C + 2D = 2 \\ C + 3D = 2 \end{cases} \Rightarrow \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$A \quad x = b.$

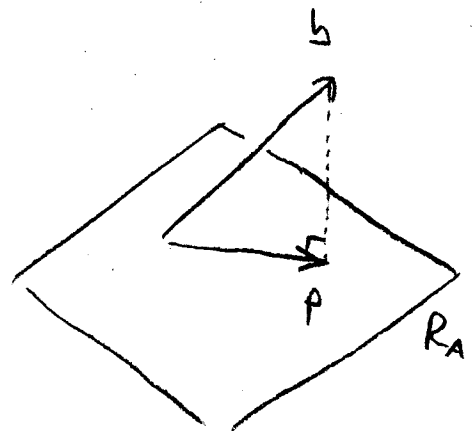


Clearly, $Ax = b$ has no soln.

Next best thing: Solve $Az = p$,

where $p = \text{proj}_{R_A}(b)$.

= "closest vector in R_A to b ."



How: Solve $A^*Az = A^*b$ instead - this works!

This minimizes $\|Az - b\|^2$ too!

Least squares.

Given: Over-determined system $Ax=b$, where A is $m \times n$, $m > n$.

Remark: A solution to $Ax=b$ (if one exists) is unique iff

$$Ay=0 \Rightarrow y=0. \quad [\text{Reason: All solns} = X_p + N_A.]$$

Theorem 7.10: Let A be $m \times n$, $m > n$, and $N_A = \{\vec{0}\}$.

The (unique) vector x that minimizes $\|Ax-b\|^2$ is the solution to $A^*Az = A^*b$.

Proof: Step 1: Show $A^*Az = A^*b$ has a unique solution

Need to show that A^*A has nullspace $\{\vec{0}\}$.

$$\text{If } A^*Ay = 0 \text{ then } 0 = (A^*Ay, y) = (Ay, Ay) = \|Ay\|^2 = 0$$

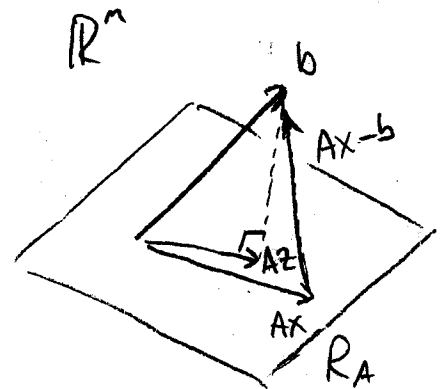
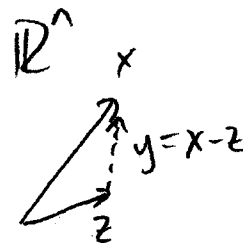
$$\text{Thus, } Ay=0 \Rightarrow y=0.$$

Step 2: Claim: If $z \in \mathbb{R}^n$ has the property that $Az-b \perp R_A$, then z minimizes $\|Ax-b\|$.

Proof: Pick $x \in \mathbb{R}^n$.

$$\text{Let } y = x - z.$$

Goal: Show $\|Ax-b\|$ is minimized when $y=0$.



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$$Ax - b = A(y+z) - b = (Az - b) + Ay \quad \text{and} \quad Az - b \perp Ay.$$

$$\text{Pythagorean theorem} \Rightarrow \|Ax - b\|^2 = \|Az - b\|^2 + \|Ay\|^2$$

Clearly, this is minimized if $\|Ay\| = 0 \Rightarrow y = 0 \Rightarrow x = z.$ ✓

Step 3: Show that this particular z satisfies $A^*Az = A^*b.$

We showed that $(Az - b, Ay) = 0$ for all $y \in X.$

$$\Rightarrow (A^*(Az - b), y) = 0 \quad \text{for all } y \in X$$

By assumption, $\text{rank } A = n \Rightarrow \text{rank } A^* = n$

$$\Rightarrow A^*(Az - b) = 0 \Rightarrow A^*Az = A^*b. \quad \square$$

Theorem 7.11: If P_Y is the orthogonal projection onto $Y,$
then $P_Y^* = P_Y.$

Proof: Exercise

Def: A function $M: X \rightarrow X$ is an isometry if for all
 $x, y \in X, \|Mx - My\| = \|x - y\|.$ ("Distance-preserving.")

Example: Any translation $Mx = x + a$ is an isometry.

Remark: Given any isometry, one can compose it with a translation to get an isometry that fixes 0. Conversely, any isometry can be decomposed into one that fixes 0, followed by a translation.

Theorem 7.12: Let $M: X \rightarrow X$ be an isometry fixing 0.

Then: (i) M is linear

(ii) $M^*M = I$ (and conversely, this implies M is an isom.)

(iii) M is invertible, and M^{-1} is an isometry.

(iv) $\det M = \pm 1$.

Proof: Pick $x, y, z \in X$ and say $Mx = x'$, $My = y'$, $Mz = z'$.

Note that $\|Mx\| = \|x\|$. (Take $y=0$).

(i) We have $\|x'\| = \|x\|$, $\|y'\| = \|y\|$, and $\|x'-y'\| = \|x-y\|$.

$$\text{Thus, } \|x'\|^2 - 2(x', y') + \|y'\|^2 = \|x'-y'\|^2 = \|x-y\|^2 = \|x\|^2 - 2(x, y) + \|y\|^2$$

This shows $(x, y) = (x', y')$, i.e., M preserves inner products.

Next, suppose $z = x+y$. We'll show $z' = x'+y'$.

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$$\|z' - x' - y'\|^2 = \|z'\|^2 + \|y'\|^2 + \|x'\|^2 - 2(z', x') - 2(z', y') + 2(x', y')$$

$$\|z - x - y\|^2 = \|z\|^2 + \|y\|^2 + \|x\|^2 - 2(z, x) - 2(z, y) + 2(x, y).$$

Since M preserves norms & inner products:

$$\|z' - x' - y'\|^2 = \|z - x - y\|^2 = 0 \Rightarrow z' - x' - y' = 0. \quad \checkmark$$

$$(ii) (x, y) = (Mx, My) = (x, M^*My)$$

$$\text{Bilinearity} \Rightarrow (x, y) - (x, M^*My) = (x, M^*My - y) = 0$$

Since this holds for all $x \in X$, $M^*My - y = 0$.

[Note: Reverse the steps for the converse.]

$$(iii) \text{ If } \|Mx\| = 0 \text{ then } \|x\| = 0 \Rightarrow M \text{ is invertible. } \checkmark$$

(M^{-1} is clearly an isometry.)

$$(iv) \text{ Since } M^*M = I, (\det M^*)(\det M) = 1$$

$$\text{Recall that } \det M^* = \det M \Rightarrow \det M = \pm 1. \quad \checkmark \quad \square$$

The geometric meaning of Theorem 7.12 is that any map that preserves distances is linear (i), and preserves both angles (see proof of (i)) and volume (iv).

Def: A matrix that maps \mathbb{R}^n to itself isometrically is orthogonal. The orthogonal matrices (fixed n) form a group under multiplication, called the orthogonal group, denoted $O(n)$. The subgroup of matrices with determinant 1 is called the special orthogonal group, denoted $SO(n)$.

Prop: A matrix M is orthogonal iff its columns vectors form an orthonormal set.

Proof: Exercise.

Recall that the determinant is one way to measure the "size" of a linear map from a space X to itself.

But how do we measure the size of a map $X \rightarrow U$?

Def: If $A: X \rightarrow U$ is a linear map between Euclidean spaces, then define the norm of A as $\|A\| := \sup\{\|Ax\| : \|x\|=1\}$.

(Recall that sup is the supremum, or least upper bound of a set.)

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Theorem 7.13: For any linear map $A: X \rightarrow U$,

(i) $\|Az\| \leq \|A\| \|z\|$ for all $z \in X$,

(ii) $\|A\| = \sup \{ (Ax, v) : \|x\|=1, \|v\|=1 \}$.

Proof: (i) By definition of $\|A\|$, $\|Az\| \leq \|A\| \cdot \|z\|$ for all unit vectors $z \in X$. In general, write $z = ke$, $\|e\|=1$.

Now, $\|Az\| = \|Ake\| = \|kAe\| = |k| \cdot \|Ae\| \leq |k| \cdot \|A\| \cdot \|e\| = \|A\| \cdot \|z\|$ —

(ii) By Theorem 7.2. ($u=Ax$), $\|Ax\| = \max \{ (Ax, v) : \|v\|=1 \}$.

By definition, $\|A\| = \sup \{ \|Ax\| : \|x\|=1 \}$
 $= \sup \{ \max \{ (Ax, v) : \|v\|=1, \|x\|=1 \} \}$
 $= \sup \{ (Ax, v) : \|v\|=\|x\|=1 \}$. \square

Theorem 7.14 Suppose we have linear maps $A, B: X \rightarrow U$, $C: U \rightarrow V$.

(i) $\|kA\| = |k| \cdot \|A\|$

(ii) $\|A+B\| \leq \|A\| + \|B\|$

(iii) $\|CA\| \leq \|C\| \cdot \|A\|$

(iv) $\|A^*\| = \|A\|$

Proof: (i) $\|kA\| = \sup \{ \|kAx\| : \|x\|=1 \} = |k| \cdot \sup \{ \|Ax\| : \|x\|=1 \}$ ✓

(ii) $\|(A+B)x\| = \|Ax+Bx\| \leq \|Ax\| + \|Bx\|$

$$\begin{aligned} \|A+B\| &= \sup \{ \|(A+B)x\| : \|x\|=1 \} \leq \sup \{ \|Ax\| + \|Bx\| : \|x\|=1 \} \\ &\leq \sup \{ \|Ax\| : \|x\|=1 \} + \sup \{ \|Bx\| : \|x\|=1 \} \\ &= \|A\| + \|B\|. \quad \checkmark \end{aligned}$$

(iii) By Theorem 7.13 (i), $\|CAx\| \leq \|C\| \cdot \|Ax\| \leq \|C\| \cdot \|A\| \cdot \|x\|$

Now, take the supremum of both sides, over all unit vectors. ✓

(iv) $\|A\| = \sup (Ax, v) = \sup (x, A^*v) = \sup (A^*v, x) = \|A^*\|,$

where supremums are taken over all unit vectors $x, v \in X$. ✓ □

Theorem 7.15: Let $A: X \rightarrow X$ be invertible. Suppose $B: X \rightarrow X$ has the property that $\|A-B\| < \frac{1}{\|A^{-1}\|}$. Then B is invertible.

Proof: let $C = A - B$.

$$B = A - C = A(I - A^{-1}C) = A(I - S), \quad \text{where } S = A^{-1}C.$$

It suffices to show that $I - S$ is invertible.

Suppose not, and pick $0 \neq x \in N_{I-S}$.

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Now, $(I-S)x = 0 \Rightarrow Sx = x \Rightarrow \|S\| \geq 1$ (since $x \neq 0$).

But $\|S\| = \|A^{-1}C\| \leq \|A^{-1}\| \cdot \|C\| < 1$ (by assumption). $\Leftarrow \square$

Remark: This proof assumes $\dim X < \infty$, but it also holds for $\dim X = \infty$.

Basic real analysis (review)

Def: A sequence of numbers $\{a_n\}$ converges to a if

$|a_k - a| \rightarrow 0$. We say $\lim_{k \rightarrow \infty} a_k = a$.

A Cauchy sequence is any sequence $\{a_n\}$ for which

$|a_k - a_j| \rightarrow 0$ as $j, k \rightarrow \infty$.

The real numbers are complete, because every Cauchy sequence converges to a limit.

The real numbers are also locally compact, that is, every bounded sequence contains a convergent sequence.

Goal: Extend these properties from numbers to vectors in a finite-dimensional Euclidean space.

Def: A sequence $\{x_k\}$ of vectors in a Euclidean space converges to a limit x if $\|x_k - x\| \rightarrow 0$ as $k \rightarrow \infty$.

A sequence $\{x_k\}$ is a Cauchy sequence if $\|x_k - x_j\| \rightarrow 0$ as $j, k \rightarrow \infty$. It is bounded if for some $R > 0$, $\|x_k\| \leq R$ for all k .

Theorem 7.16: Let X be a finite-dimensional Euclidean space.

- (i) X is complete
- (ii) X is locally compact.

Proof: (i) For any $x = (a_1, \dots, a_n)$, $y = (b_1, \dots, b_n)$, we have

$$|a_j - b_j| \leq \|x - y\|.$$

Let $\{x_k\}$ be a Cauchy sequence: $x_k = (a_{k1}, \dots, a_{kn})$.

Then each $\{a_{kj}\}_{k=1}^{\infty}$ is a Cauchy sequence, say it converges

to $a_j \in \mathbb{R}$. Put $x = (a_1, \dots, a_n)$.

By definition, $\|x_k - x\|^2 = \sum_{i=1}^n |a_{ki} - a_i|^2 \rightarrow 0 \Rightarrow x_k \rightarrow x \checkmark$

(ii) Let $\{x_k\}$ be bounded, with $\|x_k\| \leq R$.

Then $|a_{kj}| \leq \|x_k\| \leq R$ for all k .

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\mathbb{R} locally compact $\Rightarrow \exists$ subsequence of $\{x_k\}$ s.t. $\{a_{k_1}\} \rightarrow a_1$.

This subsequence has a subsequence for which $\{a_{k_2}\} \rightarrow a_2$,
and so on.

Thus, we can continue to get a subsequence for which
each $\{a_{k_j}\} \rightarrow a_j$.

Put $x = (a_1, \dots, a_n)$.

$$\text{Now, } \|x_k - x\|^2 = \sum_{j=1}^n |a_{k_j} - a_j|^2 = 0 \Rightarrow x_k \rightarrow x. \quad \checkmark \quad \square$$

Remark: We defined $\|A\| = \sup \{\|Ax\| : \|x\| = 1\}$ but in this
case, it's just $\max \{\|Ax\| : \|x\| = 1\}$: Take a subsequence
 $\{x_k\}$ (say $\|x_k\| = 1$) for which $\|Ax_k\| \rightarrow \|A\|$. By
Theorem 7.16, this sequence has a subsequence $\{x_{k_i}\}$
that converges to some $x = (a_1, \dots, a_n)$.

Now, $\|Ae\| \leq \|Ax\|$ for all unit vectors $e \in X$. \checkmark

The converse of Theorem 7.16 holds:

Theorem 7.17: If a Euclidean space X is locally compact,
then $\dim X < \infty$.

Proof: Suppose $\dim X = \infty$ and let y_1, y_2, \dots be an infinite set of linearly independent vectors.

For each k , we can construct a sequence x_1, \dots, x_n of orthonormal vectors. Thus, we obtain an infinite sequence

$$x_1, x_2, \dots \text{ for which } \|x_i - x_j\|^2 = \|x_i\|^2 - 2(x_i, x_j) + \|x_j\|^2 = 2.$$

Thus $\{x_k\}$ contains no convergent subsequence.

Def: A sequence $\{A_n\}$ of maps $X \rightarrow U$ converges to a limit A if $\lim_{n \rightarrow \infty} \|A_n - A\| = 0$.

Prop: If $\dim X < \infty$, then $A_n \rightarrow A$ iff $A_n x \rightarrow Ax$ for all $x \in X$.

Proof: Exercise (Hw).

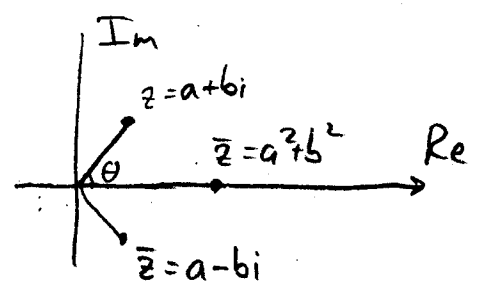
Remark: This does not hold if $\dim X = \infty$.

Complex Euclidean structure

Review of complex numbers:

Let $z = a + bi$.

$$|z|^2 = z \bar{z} = a^2 + b^2$$



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Now, consider $z = \begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix}$ in \mathbb{C}^n .

$$|z|^2 = \bar{z}^T z = [\bar{z}_1, \bar{z}_2, \dots, \bar{z}_n] \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{bmatrix} = |z_1|^2 + |z_2|^2 + \dots + |z_n|^2$$

If X is a finite-dimensional space over \mathbb{C} , then define

the inner product as $(z, w) = \bar{w}^T z$

↳ also written $\boxed{w^H z}$ "Hermitian product"

Compare to real case: $(x, y) = y^T x$.

Properties of the complex inner product:

(i) linear in x : $(kx, y) = k(x, y)$

skew-linear in y : $(x, ky) = \bar{k}(x, y)$

(ii) $\overline{(x, y)} = (y, x)$ (skew-symmetry)

(iii) $(x, x) > 0$ for all $x \neq 0$ (positivity)

In a complex Euclidean space,

$$\|x+y\|^2 = \|x\|^2 + (x, y) + (y, x) + \|y\|^2 = \|x\|^2 + 2 \operatorname{Re}(x, y) + \|y\|^2$$

However, most results for real spaces carry over to complex

spaces — just replace $(x, y) := y^T x$ with $(x, y) := y^H x$.

Define the adjoint of a linear map $A: X \rightarrow U$ to be

the map $A^*: U \rightarrow X$ such that $(x, A^*u) = (Ax, u) \quad \forall x \in X, u \in U$.

In a complex space: $(A^*u)^H x = u^H (A^*)^H x = u^H Ax$

$$\Rightarrow (A^*)^H = A \quad \Rightarrow \quad \boxed{A^* = A^H = \bar{A}^T} \quad \text{"Hermitian"}$$

Orthonormal vectors: $\delta_i^T \delta_j = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} \quad \text{over } \mathbb{R}$

$\delta_i^H \delta_j = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} \quad \text{over } \mathbb{C}$.

Def: An isometry of a complex space is a function $M: X \rightarrow X$ such that $\|Mx - My\| = \|x - y\|$ for all $x, y \in X$. An isometric map of a complex space is also called unitary.

Prop: If $M: X \rightarrow X$ is unitary, then

(i) $M^* M = I$

(ii) M^{-1} is unitary

(iii) The set of unitary maps of X forms a group.

(iv) $|\det M| = 1$.

The norm of a linear map between complex spaces is

defined just as for real spaces: $\|A\| := \sup \{ \|Ax\| : \|x\| = 1 \}$.