### Lecture 3.3: Alternating multilinear forms

#### Matthew Macauley

School of Mathematical & Statistical Sciences Clemson University http://www.math.clemson.edu/~macaule/

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## Symmetric, skew-symmetric, and alternating forms

Recall that a k-linear form  $f: X \times \cdots \times X \to K$  is:

- symmetric if  $\pi f = f$  for all  $\pi \in S_k$ ,
- skew-symmetric if  $\tau f = -f$  for all transpositions  $\tau \in S_k$ .

#### Definition

A k-linear form is alternating if  $f(x_1, ..., x_k) = 0$  whenever  $x_i = x_j$  for some  $i \neq j$ .

It is easy to show that the set of alternating (respectively, symmetric or skew-symmetric) k-linear forms is a subspace of  $\mathcal{T}^k(X')$ .

# Alternating vs. skew-symmetric

### Proposition 3.1

Every alternating form is skew-symmetric.

### Corollary 3.2

If  $1+1 \neq 0\mbox{,}$  then every skew-symmetric form is alternating.

## Alternating forms and linear dependence

#### Proposition 3.3

If f is alternating and  $y_1, \ldots, y_k$  is linearly dependent, then  $f(y_1, \ldots, y_k) = 0$ .

## Alternating forms and linear independence

#### Proposition 3.4

If f is alternating and  $y_1, \ldots, y_n$  is a basis, then  $f(y_1, \ldots, y_n) \neq 0$ .