1. If  $y_f(t)$  is a solution of

$$y'' + py' + qy = f(t)$$

and  $y_q(t)$  is a solution of

$$y'' + py' + qy = g(t),$$

show that  $z(t) = \alpha y_f(t) + \beta y_g(t)$  is a solution of

$$y'' + py' + qy = \alpha f(t) + \beta g(t),$$

where  $\alpha$  and  $\beta$  are any real numbers, by plugging it into the ODE.

- 2. Find the general solution to the following 2<sup>nd</sup> order linear inhomogeneous ODEs.
  - (a)  $y'' + 2y' + 2y = 2 + \cos 2t$
  - (b)  $y'' + 25y = 2 + 3t + 4\cos 2t$
  - (c)  $y'' y = t e^{-t}$ .
- 3. (a) Find the general solution of  $y'' + 3y' + 2y = te^{-4t}$ . (Look for a particular solution of the form  $y_p = (at + b)e^{-4t}$ .)
  - (b) Use a similar approach as above to find a solution to the differential equation  $y'' + 2y' + y = t^2e^{-2t}$ .
- 4. Find the general solution of  $y'' + 2y' + 2y = e^{-2t} \sin t$ . (Look for a particular solution of the form  $y_p = e^{-2t} (a \cos t + b \sin t)$ .)
- 5. For the following exercises, rewrite the given function in the form

$$y = A\cos(\omega t - \phi) = A\cos\left(\omega\left(t - \frac{\phi}{\omega}\right)\right)$$
,

and then plot the graph of this function.

- (a)  $y = \cos 2t + \sin 2t$
- (b)  $y = \cos t \sin t$
- (c)  $y = \cos 4t + \sqrt{3} \sin 4t$
- (d)  $y = -\sqrt{3}\cos 2t + \sin 2t$ .
- 6. Consider the undamped oscillator

$$mx'' + kx = 0,$$
  $x(0) = x_0,$   $x'(0) = v_0.$ 

- (a) Write the general solution of this initial value problem in the form  $x(t) = a \cos \omega t + b \sin \omega t$  (i.e., determine a, b, and  $\omega$ .).
- (b) Write your solution in the form  $x(t) = A\cos(\omega t \phi)$  (i.e., determine A).

- 7. A 0.1-kg mass is attached to a spring having a spring constant 3.6  $kg/s^2$ . The system is allowed to come to rest. Then the mass is given a sharp tap, imparting an instantaneous downward velocity of 0.4 m/s. If there is no damping present, find the amplitude A and frequency  $\omega$  of the resulting motion.
  - (a) Let x = 0 be the position of the spring before the mass was hung from it. Find x(0).
  - (b) Solve this initial value problem and plot the solution.
- 8. A spring-mass system is modeled by the equation

$$x'' + \mu x' + 4x = 0$$
.

- (a) Show that the system is critically damped when  $\mu = 4 \ kg/s$ .
- (b) Suppose that the mass is displaced upward 2 m and given an initial velocity of 1 m/s. Use a computer (i.e., WolframAlpha) to comute the solution for  $\mu = 4, 4.2, 4.4, 4.6, 4.8, 5$ . Plot all of the solution curves on one figure. What is special about the critically damped solution in comparison to the other solutions?
- (c) On a new set of axes, repeat part (b) using  $\mu = 4, 3.9, \text{ and } 3.$
- (d) Explain why would you want to adjust the spring on a screen door so that it was critically damped.
- 9. The function  $x(t) = \cos 6t \cos 7t$  has mean frequency  $\bar{\omega} = 13/2$  and half difference  $\delta = 1/2$ . Thus,

$$\cos 6t - \cos 7t = \cos \left(\frac{13}{2} - \frac{1}{2}\right)t - \cos \left(\frac{13}{2} + \frac{1}{2}\right)t = 2\sin \frac{1}{2}t \sin \frac{13}{2}t.$$

Plot the graph of x(t), and superimpose the "envelope" of the beats, which is the slow frequency oscillation  $y(t) = \pm 2\sin(1/2)t$ . Use different line styles or colors to differentiate the curves.

- 10. Plot the given function on an appropriate time interval. Use the technique of the previous exercise to superimpose the plot of the envelope of the beats in a different line style and/or color.
  - (a)  $\cos 9t \cos 10t$
  - (b)  $\sin 11t \sin 10t$
- 11. Let  $\omega_0 = 11$ . Use a computer to plot the graph of the solution

$$x(t) = \frac{\cos \omega t - \cos \omega_0 t}{\omega_0^2 - \omega^2}$$

for  $\omega = 9$ , 10, 10.5, 10.9, and 10.99 on the time interval [0, 24]. (Okay to just print this out and attach it). Explain how these solutions approach the resonance solution as  $\omega \to \omega_0$ . [Hint: Put the equation above in the form  $x(t) = A \sin \delta t \sin \bar{\omega} t$ , and use this result to justify your conclusion.]

- 12. For each system below, write it as Ax = b. Find all solutions, and sketch the graph of the lines in each system on the same axis. Are the resulting lines intersecting, parallel, or coincident?
  - (a)  $x_1 + 3x_2 = 0$ ,  $2x_1 x_2 = 0$
  - (b)  $-x_1 + 2x_2 = 4$ ,  $2x_1 4x_2 = -6$
  - (c)  $2x_1 3x_2 = 4$ ,  $x_1 + 2x_2 = -5$
  - (d)  $3x_1 2x_2 = 0$ ,  $-6x_1 + 4x_2 = 0$
  - (e)  $2x_1 3x_2 = 6$ ,  $-4x_1 + 6x_2 = -12$
- 13. For each part, find the determinant, eigenvalues and eigenvectors of the given matrix. If the matrix is invertible, find its inverse.

- (a)  $\mathbf{A} = \begin{pmatrix} 3 & -2 \\ 2 & -2 \end{pmatrix}$  (b)  $\mathbf{A} = \begin{pmatrix} 3 & -2 \\ 4 & -1 \end{pmatrix}$  (c)  $\mathbf{A} = \begin{pmatrix} 3 & -4 \\ 1 & -1 \end{pmatrix}$  (d)  $\mathbf{A} = \begin{pmatrix} 1 & -2 \\ 3 & -4 \end{pmatrix}$  (e)  $\mathbf{A} = \begin{pmatrix} -1 & -4 \\ 1 & -1 \end{pmatrix}$  (f)  $\mathbf{A} = \begin{pmatrix} 5/4 & 3/4 \\ -3/4 & -1/4 \end{pmatrix}$
- 14. For each problem below, find the eigenvalues of the given matrix, and then describe how the nature of the eigenvalue (e.g., positive/negative, complex, repeated, etc.) depends on the parameter  $\alpha$ .
  - (a)  $\mathbf{A} = \begin{pmatrix} 1 & 2 \\ 3 & \alpha \end{pmatrix}$  (b)  $\mathbf{A} = \begin{pmatrix} 1 & -\alpha \\ 2\alpha & 3 \end{pmatrix}$
- 15. Let A be a  $2 \times 2$  matrix. In this problem we will show that  $\lambda = 0$  is an eigenvalue of a matrix **A** if and only if  $det(\mathbf{A}) = 0$ .
  - (a) Write the characteristic polynomial (i.e., the polynomial  $\det(\mathbf{A} \lambda I) = 0$  in terms of the determinant and trace of A.
  - (b) Show that if  $\lambda = 0$  is an eigenvalue of **A**, then  $\det(\mathbf{A}) = 0$ .
  - (c) Show that if  $det(\mathbf{A}) = 0$ , then  $\lambda = 0$  is an eigenvalue of  $\mathbf{A}$ .
  - (d) Now, make the same argument that  $\lambda = 0$  is an eigenvalue if and only if  $\det(\mathbf{A}) = 0$ , without reference to the characteristic polynomial. (Hint: If  $\lambda = 0$  is an eigenvalue, then  $A\mathbf{v} = 0\mathbf{v} = \mathbf{0}$  for some  $\mathbf{v} \neq \mathbf{0}$ . When does such a homogeneous system have a non-zero solution?)