

Lecture 1.3: Linear maps

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Linear maps

Definition

A **linear map** is a function $T: V \rightarrow W$ between vector spaces V and W satisfying

$$T(ax + by) = aT(x) + bT(y), \quad \text{for all } x, y \in V; \ a, b \in \mathbb{F}.$$

When the vector spaces consist of functions (e.g., $\mathcal{C}^\infty(\mathbb{R})$, $\mathbb{R}[x]$, or $\text{Per}_{2\pi}(\mathbb{R})$), we often use the term **linear operator**.

For example, $\frac{d}{dx}$ and \int are linear operators.

When our vector space is \mathbb{R}^n , we usually just say linear “map” or “function”.

For example, $f(x) = 3x$ and $f(x_1, x_2) = 8x_1 - 3x_2$ are linear functions.

Definition

The **kernel** (or **nullspace**) of a linear map $T: V \rightarrow W$, denoted $\ker(T)$ is the set of vectors such that $T(v) = 0$:

$$\ker(T) = \{v \in V \mid T(v) = 0\}.$$

The **image** (or **range**) of T is the set $T(V)$, i.e.,

$$\text{im}(T) = \{T(v) \mid v \in V\}.$$

Examples

From calculus

Let $V = W = C^\infty(\mathbb{R})$.

1. $T = \frac{d}{dx}$ is a linear operator:

$$T: f(x) \mapsto f'(x).$$

2. $T = \int$ is a linear operator:

$$T: f(x) \mapsto \int f(x) dx.$$

3. The Laplace transform \mathcal{L} is a linear operator:

$$\mathcal{L}: f(t) \mapsto \int_0^\infty f(t) e^{-st} dt.$$

Examples

Matrices

Any 2×2 matrix is a linear map $A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$.

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} a_{11}x_1 + a_{12}x_2 \\ a_{21}x_1 + a_{22}x_2 \end{bmatrix}.$$

Facts

- $|\det A|$ = scaling factor (=area of parallelogram); negative denotes reflection.
- A is **invertible** iff $\det A \neq 0$.
- In general, an $m \times n$ matrix is a linear map $A: \mathbb{R}^n \rightarrow \mathbb{R}^m$
- $\text{im } A$ and $\text{ker } A$ are both subspaces, and they satisfy

$$\dim(\text{im } A) + \dim(\text{ker } A) = n.$$

Intuitively, every “dimension” either gets collapsed or persists.

Connections between linear operators and ODEs

Preview!

Let $V = W = C^\infty(\mathbb{R})$.

- $T = \frac{d^2}{dx^2}$ is a linear operator: $y \mapsto y''$.

$$\ker(T) = \{y(x) \mid y''(x) = 0\} = \{C_1x + C_2 \mid C_1, C_2 \in \mathbb{R}\}.$$

- $T = \frac{d^2}{dt^2} + k^2$ is a linear operator: $y \mapsto y'' + k^2y$.

$$\ker(T) = \{y(t) \mid y'' + k^2y = 0\} = \{C_1 \cos kt + C_2 \sin kt \mid C_1, C_2 \in \mathbb{R}\}.$$

- $T = \frac{d^2}{dt^2} + t^2$ is a linear operator: $y \mapsto y'' + t^2y$.

$$\ker(T) = \{y(t) \mid y'' + t^2y = 0\}.$$

Connections between linear operators and ODEs

Big idea

The **kernel** (or nullspace) of these linear differential operators are solutions to **linear homogeneous differential equations**.

Since $\ker(T)$ is a vector space, the set of solutions (i.e., the **general solution**) to a linear homogeneous ODE is a **vector space**.