Lecture 1.1: Vector spaces

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Motivation

A (real-valued) function f is linear if

$$f(ax + by) = af(x) + bf(y).$$

In other words, if you can "break apart sums and pull out constants".

Many common structures and operations have this property. For example:

a derivatives:
$$\frac{d}{dx}(au+bv) = a\frac{du}{dx} + b\frac{dv}{dx}$$
integrals: $\int (au+bv) dx = a \int u dx + b \int v dx$

• matrices and vectors: M(ax + by) = aMx + bMy

- Laplace transforms: $\mathcal{L}(af + bg) = a\mathcal{L}(f) + b\mathcal{L}(g)$
- Solutions of certain ODEs: If y_1 and y_2 solve $y'' + k^2y = 0$, then so does $C_1y_1 + C_2y_2$.

We encounter this type of linear structure all the time without realizing it.

A beginning linear algebra class usually focuses on systems of equations and matrix algebra.

An $m \times n$ matrix encodes a linear map from \mathbb{R}^n to \mathbb{R}^m . Elements in these sets are "vectors".

But this is just a special case of the "bigger picture". We'll begin this course by peeking at this structure, which underlies nearly every aspect of the mathematics in this class.

Vector spaces

Definition

A vector space consists of a set V (of "vectors") and a set F (of "scalars"; usually \mathbb{R} or \mathbb{C}) that is:

- closed under addition: $v, w \in V \implies v + w \in V$
- closed under scalar multiplication: $v \in V$, $c \in \mathbb{F} \implies cv \in V$

Remark

We can deduce some easy consequences:

- **0** ∈ *V*
- $v \in V \Longrightarrow -v \in V$

If $\mathbb{F} = \mathbb{R}$, we say V is a "real vector space", an " \mathbb{R} -vector space", or a "vector space over \mathbb{R} ".

A "complex vector space" is defined similarly (i.e., if $\mathbb{F} = \mathbb{C}$).

Blanket assumption

Unless specified otherwise, we will assume by default that $\mathbb{F} = \mathbb{R}$.

Vector spaces

Examples

1.
$$V = \mathbb{R}^n = \{(x_1, \dots, x_n) \mid x_i \in \mathbb{R}\}.$$

"+": $(x_1, \dots, x_n) + (y_1, \dots, y_n) = (x_1 + y_1, \dots, x_n + y_n) \in \mathbb{R}^n$
".": $c \cdot (x_1, \dots, x_n) = (cx_1, \dots, cx_n) \in \mathbb{R}^n$
2. $V = \mathbb{C}^n = \{(z_1, \dots, z_n) \mid z_i \in \mathbb{C}\}.$
3. $V = \mathbb{R}_n[x] = \{a_0 + a_1x + \dots + a_nx^n \mid a_i \in \mathbb{R}\}.$ "polynomials of degree $\leq n$ "
4. $V = \mathbb{R}[x] = \{a_0 + a_1x + \dots + a_kx^k \mid a_i \in \mathbb{R}\}.$ "polynomials of arbitrary degree"
5. $V = \mathbb{R}[[x]] = \{a_0 + a_1x + a_2x^2 + \dots + a_i \in \mathbb{R}\}.$ "power series"
6. $V = \mathcal{C}^1(\mathbb{R}) = (\text{once})$ differentiable real-valued functions s.t. $f'(x)$ is continuous.
7. $V = \mathcal{C}^{\infty}(\mathbb{R}) = \text{infinitely differentiable functions; } f^{(k)}(x) \text{ continuous for all } k.$
8. $V = \operatorname{Per}_{2\pi} = \operatorname{piecewise continuous functions with } f(x) = f(x + 2\pi), \text{ i.e., period}$
 $T = 2\pi/n \text{ for some } n \in \mathbb{N}$

Non-examples

- 1. Polynomials with degree n. $[e.g., (x^n + 1) + (2 x^n) = 3]$
- 2. The upper half-plane in \mathbb{R}^2 . [e.g., $-1 \cdot (0, 1) = (0, -1)$]
- 3. A line (or plane) not through the origin. [e.g., $0 \cdot v = 0$]

Subspaces

Definition

If V is a vector space (over \mathbb{F}), then a subspace is a subset $W \subseteq V$ that is also a vector space (over \mathbb{F}). We write $W \leq V$.

Examples

- 1. V and $\{\mathbf{0}\}$ are always subspaces of V.
- 2. Let $V = \{(x, y, z) \mid x, y, z \in \mathbb{R}\} = \mathbb{R}^3$ and $W = \{(x, y, 0) \mid x, y \in \mathbb{R}\} \cong \mathbb{R}^2$. Then W is a subspace of V.
- 3. Clearly, $\mathbb{R}_n[x] \subsetneq \mathbb{R}[x] \subsetneq \mathbb{R}[[x]]$ as subsets.
 - $\mathbb{R}_n[x]$ is a subspace of $\mathbb{R}[x]$ and $\mathbb{R}[[x]]$.
 - $\mathbb{R}[x]$ is a subspace of $\mathbb{R}[[x]]$.
- 4. $\mathcal{C}^{\infty}(\mathbb{R})$ is a subspace of $\mathcal{C}^{1}(\mathbb{R})$. Also, note that

$$\mathcal{C}^1(\mathbb{R}) \supseteq \mathcal{C}^2(\mathbb{R}) \supseteq \mathcal{C}^3(\mathbb{R}) \supseteq \cdots \supseteq \mathcal{C}^\infty(\mathbb{R}).$$

Remark

Subspaces in \mathbb{R}^n "look like" hyperplanes (lines, planes, etc.) through the origin.

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Subspaces

Definition

If V is a vector space (over \mathbb{F}), then a subspace is a subset $W \subseteq V$ that is also a vector space (over \mathbb{F}). We write $W \leq V$.

Non-examples

- 1. The unit circle in \mathbb{R}^2 ($\subseteq \mathbb{R}^2$)
- 2. Polynomials of degree $n \quad (\subseteq \mathbb{R}_n[x])$
- 3. Upper half-plane ($\subseteq \mathbb{R}^2$)
- 4. The line y = 2x + 3 ($\subseteq \mathbb{R}^2$)
- 5. The plane $\{(x, y, 1) \mid x, y \in \mathbb{R}\} \quad (\subseteq \mathbb{R}^3)$
- 6. Piecewise continuous functions with period exactly 2π ($\subseteq \operatorname{Per}_{2\pi}$)

How to determine whether W is a subspace of V

Given a collection of "vectors" $W \subseteq V$, ask:

- Is it closed under addition?
- Is it closed under scalar multiplication?