MthSc 311: Linear Algebra (Fall 2012) Midterm 1 October 5, 2012

NAME:

Instructions

- Exam time is 50 minutes
- You may *not* use notes or books.
- Calculators are *not* allowed.
- Show your work. Partial credit will be given.

Question	Points Earned	Maximum Points
1		6
2		6
3		10
4		18
5		10
Total		50

Student to your left:

Student to your right:

1. Compute the inverse of the following matrix:

$$\boldsymbol{A} = \begin{bmatrix} 1 & 3 & 4 \\ 2 & 5 & 6 \\ -2 & -7 & -9 \end{bmatrix}$$

2. Suppose you want to perform elimination on the following matrix

$$oldsymbol{A} = egin{bmatrix} 0 & 1 & 2 & 3 \ 1 & 0 & 4 & -1 \ 1 & 3 & 2 & -2 \ 3 & 9 & 6 & -6 \end{bmatrix}$$

As a first step, you want to swap rows 1 and 2, and also subtract 3 times row 3 from row 4. Let E be the matrix that does this. What is E, and do you want to compute EA or AE? What would happen to A if you multiplied E on the "wrong side" of it? (You can either write down the explicit matrix or just describe it in words.)

- 3. For each statement below, circle the option that makes it correct.
 - (a) Suppose v_1, \ldots, v_6 are six vectors in \mathbb{R}^4 .
 - i. Those vectors (do)(do not)(might not) span \mathbf{R}^4 .
 - ii. Those vectors (are)(are not)(might be) linearly independent.
 - iii. Any four of those vectors (are)(are not)(might be) a basis for \mathbf{R}^4 .
 - (b) Suppose v_1, \ldots, v_4 are four vectors in \mathbb{R}^6 .
 - i. Those vectors (do)(do not)(night not) span a subspace of \mathbf{R}^6 .
 - ii. Those vectors (are)(are not)(might be) linearly independent.
 - iii. Those four vectors (are)(are not)(might be) a basis for a subspace of \mathbf{R}^6 .
 - (c) The column vectors of an $n \times n$ matrix (do)(do not)(might not) span the column space.
 - (d) The column vectors of an $n \times n$ matrix (are)(are not)(might be) a basis for the column space.
 - (e) The column vectors of an $n \times n$ invertible matrix (do)(do not)(might) span \mathbb{R}^n .
 - (f) The column vectors of an $n \times n$ invertible matrix (are)(are not)(might be) a basis for \mathbb{R}^n .

- 4. Consider the 3 × 4 system Ax = b, where $A = \begin{bmatrix} 1 & 1 & -2 & 1 \\ -1 & -1 & 4 & 3 \\ 0 & 0 & 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$.
 - (a) Use elimination to reduce A down to its *reduced-row echelon form*. That is, all pivots should be 1, and with zeros below *and* above them.

- (b) Describe in words the condition that guarantees when there is a solution to Ax = b. Your answer should not be more than one sentence, and should mention one of the "4 fundamental subspaces" of A.
- (c) Give an explicit condition involving b_1 , b_2 , and b_3 that guarantees when there is a solution to Ax = b.

(d) For each of the "the 4 fundamental subspaces" associated with \boldsymbol{A} (the column space $C(\boldsymbol{A})$, row space $C(\boldsymbol{A}^T)$, nullspace $N(\boldsymbol{A})$, and left nullspace $N(\boldsymbol{A}^T)$), find a basis and compute its dimension. A basis for the subspace consisting of just the zero vector is the emptyset, \emptyset . [*Remark*: At this point, you may be able to determine some of these by inspection. If so, great! You do *not* need to show your work.]

(e) Find all solutions to
$$Ax = b$$
 when $b = \begin{bmatrix} 0 \\ 2 \\ 8 \end{bmatrix}$.

- 5. Suppose A is a 2×3 matrix (2 rows and 3 columns) with rank r = 2.
 - (a) Correctly complete the following sentence: The equation Ax = b (always)(not always) has (a unique solution)(many solutions)(no solution).
 - (b) Describe the four fundamental subspaces of A as best you can. Do not just state the definition of these spaces. [Descriptions like "all of \mathbf{R}^{n} ", or "just the zero vector", or "a line in \mathbf{R}^{n} ", or "a plane in \mathbf{R}^{m} " are fine, but use actual numbers, not just m or n.]
 - i. The column space, $C(\mathbf{A})$.

ii. The row space, $C(\mathbf{A}^T)$.

iii. The nullspace, $N(\mathbf{A})$.

iv. The left nullspace, $N(\mathbf{A}^T)$.