

**MthSc 311: Linear Algebra (Fall 2012)**  
**Midterm 2**  
**November 9, 2012**

**NAME:**

**Instructions**

- Exam time is 50 minutes
- You may *not* use notes or books.
- Calculators are *not* allowed.
- **Show your work.** Partial credit will be given.

Question	Points Earned	Maximum Points
1		7
2		9
3		8
4		4
5		5
6		8
7		9
<b>Total</b>		<b>50</b>

Student to your left:

Student to your right:

1. (7 pts) Give an example of each of the following:
  - (a) A set  $S$  of three nonzero vectors in  $\mathbb{R}^3$  for which  $S^\perp$  is a line.
  
  
  
  
  
  
  
  
  
  
  - (b) An *orthonormal basis* for  $\mathbb{R}^3$ , including the vector  $\mathbf{q}_1 = (1, 1, 1)/\sqrt{3}$ .
  
  
  
  
  
  
  
  
  
  
  - (c) A matrix that has no real-valued eigenvalues (that is, they are all complex numbers).
  
  
  
  
  
  
  
  
  
  
  - (d) A  $2 \times 2$  matrix with a repeated eigenvalue but only one (linearly independent) eigenvector.
  
  
  
  
  
  
  
  
  
  
  - (e) A  $2 \times 2$  matrix with a repeated eigenvalue but two (linearly independent) eigenvectors.
  
  
  
  
  
  
  
  
  
  
  - (f) A non-orthogonal matrix that has orthonormal columns.
  
  
  
  
  
  
  
  
  
  
  - (g) A non-zero matrix  $\mathbf{A}$  and an eigenvector  $\mathbf{v} \neq \mathbf{0}$  that is in its nullspace.

2. (9 pts) Fill in the blanks. No explanations needed, but think carefully before answering!

(a) If  $\mathbf{Ax} = \mathbf{b}$  has no solution, then the closest vector to  $\mathbf{b}$  in  $C(\mathbf{A})$  is \_\_\_\_\_.

(either a formula or a description in words is fine).

(b) If  $\mathbf{Ax} = \mathbf{b}$  has a solution  $\mathbf{x}$ , then the closest vector to  $\mathbf{b}$  in  $N(\mathbf{A}^T)$  is \_\_\_\_\_.

(c) Let  $\hat{\mathbf{x}}$  be the least-squares solution to  $\mathbf{Ax} = \mathbf{b}$ . Then  $\mathbf{b} - \mathbf{A}\hat{\mathbf{x}}$  is orthogonal to the

\_\_\_\_\_ of  $\mathbf{A}$ .

(d) The formula for the projection matrix  $\mathbf{P}$  onto the column space of a matrix  $\mathbf{A}$  is  $\mathbf{P} =$ \_\_\_\_\_.

assuming that  $\mathbf{A}$  has \_\_\_\_\_ columns. In this case,  $\mathbf{I} - \mathbf{P}$  is the projection

matrix onto the \_\_\_\_\_ of  $\mathbf{A}$ .

(e) If  $\mathbf{Q}$  is an orthogonal matrix, then \_\_\_\_\_ =  $\mathbf{I}$  and the formula for the projec-

tion matrix onto the column space of  $\mathbf{Q}$  in *simplified* form is  $\mathbf{P} =$ \_\_\_\_\_.

(f) If  $\mathbf{v}$  is an eigenvector of  $\mathbf{A}$  with eigenvalue  $\lambda$ , then  $\mathbf{v}$  is in the nullspace of \_\_\_\_\_.

3. (8 pts) Find the determinant of the following matrices:

$$\mathbf{A} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 1 & 0 & 1 \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} 1 & 1 & 0 \\ 2 & 1 & 1 \\ 2 & 3 & 0 \end{bmatrix}.$$

[*Hint*: Cofactor expansion will work to find  $\det \mathbf{A}$ , but it is certainly not necessary.]

4. (4 pts) Suppose a  $4 \times 4$  matrix  $\mathbf{A}$  has  $\det \mathbf{A} = -1$ . Find:

(a)  $\det(\frac{1}{2}\mathbf{A})$

(b)  $\det(-\mathbf{A})$

(c)  $\det(\mathbf{A}^2)$

(d)  $\det(\mathbf{A}^{-1})$

5. (5 pts) Use the Gram-Schmidt process to turn  $\mathbf{a} = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$  and  $\mathbf{b} = \begin{bmatrix} 1 \\ -2 \\ 2 \end{bmatrix}$  into an orthonormal set.

6. (8 pts) Find the eigenvalues and the eigenvectors of  $\mathbf{A} = \begin{bmatrix} 1 & 1 & 3 \\ 0 & 2 & 3 \\ 0 & 0 & 1 \end{bmatrix}$ .

7. (9 pts) Consider the plane  $x = y$  in  $\mathbb{R}^3$ . Note that this plane is the span of the set  $S = \{\mathbf{v}_1, \mathbf{v}_2\}$  that contains the vectors  $\mathbf{v}_1 = (1, 1, 0)$  and  $\mathbf{v}_2 = (0, 0, 1)$ .

(a) Find a basis for  $S^\perp$ , the *orthogonal complement* of the plane  $x = y$ .

(b) Project the vector  $\mathbf{b} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$  onto the plane  $x = y$ .

(c) Project the vector  $\mathbf{b} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$  onto  $S^\perp$ . [*Hint*: Look at Problem 2.]