Read: Strang, Section 3.3, 3.4, 3.5.

Suggested short conceptual exercises: Strang, Section 3.3, #1, 8, 9, 11, 13, 16, 17–22. Section 3.4, #7, 13–17, 22, 24, 25, 27, 33. Section 3.5, #4, 9.

- 1. Find the reduced row echelon forms \boldsymbol{R} and the rank of these matrices:
 - (a) The 3×4 matrix with all entries equal to 2.
 - (b) The 3×4 matrix with $a_{ij} = i + j 1$.
 - (c) The 3×4 matrix with $a_{ij} = (-1)^j$.
 - (d) The transposes of each of the three matrices above.
- 2. What are the "special solutions" to $\mathbf{R}\mathbf{x} = \mathbf{0}$ for the matrices \mathbf{R} shown below, and what is their rank?

$$\boldsymbol{R} = \begin{bmatrix} 1 & 0 & 2 & 4 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} , \qquad \boldsymbol{R} = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} .$$

3. Consider the system Ax = b, where

$$\boldsymbol{A} = \begin{bmatrix} 2 & 4 & 6 & 4 \\ 2 & 5 & 7 & 6 \\ 2 & 3 & 5 & 2 \end{bmatrix}, \qquad \boldsymbol{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 3 \\ 5 \end{bmatrix}.$$

Solve this system by carrying out the following steps.

- (a) Reduce $[A \ b]$ to $[U \ c]$, turning the system Ax = b into an upper triangular one, Ux = c.
- (b) Find condition(s) on b_1 , b_2 , and b_3 for Ax = b to have a solution. Each "zero row" of U will give you a condition.
- (c) Describe the *column space* $C(\mathbf{A})$ of \mathbf{A} as a subspace of \mathbf{R}^3 . Express it as a linear combination of a *minimal* number of vectors.
- (d) Describe the nullspace $\boldsymbol{x}_n := N(\boldsymbol{A})$ and find a basis for it (the special solutions).
- (e) Find any particular solution to Ax = b and then the general solution, which will have the form $x = x_p + x_n$.
- (f) Reduce $\begin{bmatrix} U & c \end{bmatrix}$ to $\begin{bmatrix} R & d \end{bmatrix}$, where **R** is the row-reduced echelon form and **d** is a particular solution.
- 4. Suppose we have a system Ax = b with particular solution $x_p = (2, 4, 0)$ and whose "homogeneous" solution x_n (i.e., the nullspace of A) is the set of scalar multiples of (1, 1, 1).
 - (a) Construct such a 2×3 system. Sketch the "grid picture."
 - (b) Why can't there be a 1×3 system satisfying these conditions? Sketch the "grid picture" and show how it fails.

5. Consider the following 3×3 matrices.

$$\boldsymbol{A} = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 6 & 3 \\ 0 & 2 & 5 \end{bmatrix}, \qquad \boldsymbol{B} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 2 & 4 & 8 \end{bmatrix}$$

Carry out the following steps for both A and B.

- (a) Determine which vectors (b_1, b_2, b_3) are in the column space. [*Hint*: Each "zero row" should give you a condition on b_1, b_2, b_3 .]
- (b) What combination of the rows give the zero row?
- (c) What is the relationship between Parts (a) and (b)?
- 6. Find matrices A and B with the given property or explain why there is none. [*Hint*: Recall that $x = x_p + x_n$. Sketching the "grid picture" isn't necessary, but it may help.]

(a) The only solution of
$$\boldsymbol{A}\boldsymbol{x} = \begin{bmatrix} 1\\ 2\\ 3 \end{bmatrix}$$
 is $\boldsymbol{x} = \begin{bmatrix} 1\\ 0 \end{bmatrix}$.
(b) The only solution of $\boldsymbol{B}\boldsymbol{x} = \begin{bmatrix} 1\\ 0 \end{bmatrix}$ is $\boldsymbol{x} = \begin{bmatrix} 1\\ 2\\ 3 \end{bmatrix}$.

7. Consider the following four vectors:

$$\boldsymbol{v}_1 = \begin{bmatrix} 1\\0\\0 \end{bmatrix}, \quad \boldsymbol{v}_2 = \begin{bmatrix} 1\\1\\0 \end{bmatrix}, \quad \boldsymbol{v}_3 = \begin{bmatrix} 1\\1\\1 \end{bmatrix}, \quad \boldsymbol{v}_4 = \begin{bmatrix} 2\\3\\4 \end{bmatrix}.$$

- (a) Show that v_1 , v_2 , v_3 are linearly independent but v_1 , v_2 , v_3 , v_4 are linearly dependent.
- (b) Solve $c_1 v_1 + c_2 v_2 + c_3 v_3 + c_4 v_4 = 0$, or alternatively, Ax = 0 where the v_i 's are the columns of A.
- 8. Let P be the hyperplane x + 2y 3z t = 0 in \mathbb{R}^4 .
 - (a) Find two linearly independent vectors on P.
 - (b) Find three linearly independent vectors on P.
 - (c) Why can you not find four linearly independent vectors on P?
 - (d) Find a matrix A whose column space is P, and a matrix B whose nullspace is P.