

Read: Strang, Section 4.1, 4.2.

Suggested short conceptual exercises: Strang, Section 4.1, #1, 2, 4, 5, 8–10, 13, 15, 18,–21, 24–29. Section 4.2, #13, 18, 21–28.

1. Construct a nonzero matrix \mathbf{A} with the required property or say why it is impossible:

(a) The column space contains $\begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix}$ and $\begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix}$, and the nullspace contains $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$.

(b) The row space contains $\begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix}$ and $\begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix}$, and the nullspace contains $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$.

(c) $\mathbf{Ax} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ has a solution and $\mathbf{A}^T \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

(d) Every row is orthogonal to every column.

(e) The sum of the columns is the zero vector, and the sum of the rows is a vector with all 1's.

2. Consider the following system of equations $\mathbf{Ax} = \mathbf{b}$:

$$\begin{aligned} x + 2y + 2z &= b_1 \\ 2x + 2y + 3z &= b_2 \\ 3x + 4y + 5z &= b_3. \end{aligned}$$

(a) Find numbers y_1, y_2, y_3 to multiply the left-hand sides of the equations so they add to 0. You have found a vector \mathbf{y} in which subspace? Write $\mathbf{y}^T \mathbf{b} = 0$ in terms of b_1, b_2 , and b_3 ?

(b) Using orthogonality of subspaces, what must be the case about \mathbf{y} and $\mathbf{b} = (b_1, b_2, b_3)$ for there to be a solution to $\mathbf{Ax} = \mathbf{b}$? Does this condition hold for $\mathbf{b} = (5, 5, 9)$?

(c) What happens when we left-multiply both sides of the equation $\mathbf{Ax} = (5, 5, 9)$ by \mathbf{y}^T , where \mathbf{y} is from Part (a)?

3. For each matrix, accurately sketch the four fundamental subspaces on two \mathbb{R}^2 plots so that orthogonal pairs of subspaces are plotted together. This is the “grid picture.”

$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix} \qquad \mathbf{B} = \begin{bmatrix} 1 & 0 \\ 3 & 0 \end{bmatrix}.$$

4. For a set S , let S^\perp denote the *orthogonal complement* of S , i.e., the set of vectors orthogonal to all vectors in S . Note that even if S is not a subspace, S^\perp is.

(a) If S is the subspace of \mathbb{R}^3 containing only the zero vector, what is S^\perp ? (Find a basis.)

- (b) If S is spanned by $(1, 1, 1)$, what is S^\perp ? (Find a basis.)
- (c) If S is spanned by $(1, 1, 1)$ and $(1, 1, -1)$, what is a basis for S^\perp ? (Find a basis.)
- (d) Now, suppose S is not a subspace, but rather just the set containing the two vectors $(1, 1, 1)$ and $(1, 1, -1)$. What is S^\perp ? It is the nullspace of what matrix?
- (e) Suppose S is a set of vectors (not necessarily a subspace). Describe as concisely as possible what subspace $(S^\perp)^\perp$ is. What is the relation between S and $(S^\perp)^\perp$ when S actually is a subspace.

5. Let $\mathbf{b} = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$ and $\mathbf{a} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$.

- (a) Project \mathbf{b} onto the line through \mathbf{a} . Check that $\mathbf{e} = \mathbf{b} - \mathbf{p}$ is orthogonal to \mathbf{a} .
- (b) Find the projection matrix $\mathbf{P} = \frac{\mathbf{a}\mathbf{a}^T}{\mathbf{a}^T\mathbf{a}}$ onto the line through \mathbf{a} . Verify that $\mathbf{P}^2 = \mathbf{P}$. Multiply $\mathbf{P}\mathbf{b}$ to compute the projection \mathbf{p} .

6. Let $\mathbf{a}_1 = \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix}$, $\mathbf{a}_2 = \begin{bmatrix} 2 \\ 2 \\ -1 \end{bmatrix}$, $\mathbf{a}_3 = \begin{bmatrix} 2 \\ -1 \\ 2 \end{bmatrix}$, and $\mathbf{b} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$.

- (a) Compute the projection matrices \mathbf{P}_1 and \mathbf{P}_2 onto the lines through \mathbf{a}_1 and \mathbf{a}_2 . Multiply those matrices and explain geometrically why $\mathbf{P}_1\mathbf{P}_2$ is what it is.
- (b) Project $\mathbf{b} = (1, 0, 0)$ onto the lines through \mathbf{a}_1 and \mathbf{a}_2 and also onto \mathbf{a}_3 . Add up the three projections $\mathbf{p}_1 + \mathbf{p}_2 + \mathbf{p}_3$.
- (c) Find the projection matrix \mathbf{P}_3 onto \mathbf{a}_3 . Verify that $\mathbf{P}_1 + \mathbf{P}_2 + \mathbf{P}_3 = \mathbf{I}$. This means that the basis $\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3$ is orthogonal! (Think about why.)

7. Suppose \mathbf{P} is a projection matrix onto the column space of \mathbf{A} .

- (a) Show that the matrix $\mathbf{I} - \mathbf{P}$ is also a projection matrix by verifying that $(\mathbf{I} - \mathbf{P})^T = \mathbf{I} - \mathbf{P}$ and $(\mathbf{I} - \mathbf{P})^2 = \mathbf{I} - \mathbf{P}$ both hold.
- (b) What subspace does the matrix $\mathbf{I} - \mathbf{P}$ project onto? [*Hint*: Note that $\mathbf{b} = \mathbf{P}\mathbf{b} + (\mathbf{I} - \mathbf{P})\mathbf{b}$ holds for any vector \mathbf{b} !]

8. Consider the plane \mathcal{P} in \mathbb{R}^3 given by $x - y - 2z = 0$.

- (a) Find a matrix whose columns are a basis for \mathcal{P} .
- (b) Compute $\mathbf{P} = \mathbf{A}(\mathbf{A}^T\mathbf{A})^{-1}\mathbf{A}^T$, which is the projection matrix onto \mathcal{P} .
- (c) Find a vector \mathbf{e} that is orthogonal to \mathcal{P} . Compute the projection matrix $\mathbf{Q} = \mathbf{e}\mathbf{e}^T/\mathbf{e}^T\mathbf{e}$ and $\mathbf{I} - \mathbf{Q}$. How are \mathbf{P} and \mathbf{Q} related?