

Read: Strang, Section 6.4, 6.5.

Suggested short conceptual exercises: Strang, Section 6.4, #2, 7–10, 13–15, 18, 20–22, 25, 26. Section 6.5, #1, 6, 10, 14–20, 27–31, 33.

1. Diagonalize the following matrices into $\mathbf{Q}\mathbf{\Lambda}\mathbf{Q}^T$, where \mathbf{Q} is an *orthogonal* matrix.

$$\mathbf{A} = \begin{bmatrix} 7 & 6 \\ 6 & -2 \end{bmatrix} \quad \mathbf{B} = \begin{bmatrix} 0 & -2 & 2 \\ -2 & -1 & 0 \\ 2 & 0 & 1 \end{bmatrix}.$$

Find *all* orthogonal matrices that diagonalize \mathbf{A} . How many will diagonalize \mathbf{B} ?

2. Which of these classes of matrices do \mathbf{A} and \mathbf{B} belong to: Invertible, orthogonal, projection, permutation, diagonalizable, Markov?

$$\mathbf{A} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad \mathbf{B} = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}.$$

Which of these factorizations are possible for \mathbf{A} and \mathbf{B} : \mathbf{LU} , \mathbf{QR} , $\mathbf{S}\mathbf{\Lambda}\mathbf{S}^{-1}$, $\mathbf{Q}\mathbf{\Lambda}\mathbf{Q}^T$?

3. Let \mathbf{A} be an $n \times n$ *Hermitian* matrix (also called *self-adjoint*), which means that $\overline{\mathbf{A}}^T = \mathbf{A}$. Note that \mathbf{A} may have complex-valued entries.

- Which Hermitian matrices are also symmetric?
- Prove that all eigenvalues of \mathbf{A} are real.
- Prove that if $\mathbf{A}\mathbf{v} = \lambda\mathbf{v}$ and $\mathbf{A}\mathbf{w} = \mu\mathbf{w}$ for $\lambda \neq \mu$, then \mathbf{v} and \mathbf{w} are orthogonal.

These two proofs can be done by modifying the arguments in class that proved these statements for real symmetric matrices.

4. An real-valued $n \times n$ matrix is *skew-symmetric* if $\mathbf{A}^T = -\mathbf{A}$.

- What must be true about the diagonal entries of a skew-symmetric matrix?
- Prove that every non-zero eigenvalue of a skew-symmetric matrix is purely imaginary. [Hint: Note that a complex eigenvalue $\lambda = a + bi$ is real if $\lambda = \bar{\lambda}$, whereas it is purely imaginary if $\lambda = -\bar{\lambda}$.]
- Prove that if n is odd and \mathbf{A} is skew-symmetric, then \mathbf{A} must be singular. [Hint: complex eigenvalues come in pairs, because $\mathbf{A}\mathbf{v} = \lambda\mathbf{v}$ implies $\overline{\mathbf{A}\mathbf{v}} = \mathbf{A}\bar{\mathbf{v}} = \bar{\lambda}\bar{\mathbf{v}}$.]
- Write $\mathbf{A} = \mathbf{M} + \mathbf{N}$, the sum of a *symmetric* and a *skew-symmetric* matrix:

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 5 \\ 4 & 3 & 0 \\ 7 & 6 & 5 \end{bmatrix} = \mathbf{M} + \mathbf{N} \quad (\mathbf{M}^T = \mathbf{M}, \quad \mathbf{N}^T = -\mathbf{N}).$$

Hint: For any square matrix, $\mathbf{M} = \frac{1}{2}(\mathbf{A} + \mathbf{A}^T)$. What does this force \mathbf{N} to be?

5. Consider the following two quadratic forms:

$$f(x_1, x_2) = 2x_1^2 - 4x_1x_2 + 5x_2^2, \quad f(x_1, x_2) = 2x_1^2 + 6x_1x_2 + 2x_2^2.$$

Carry out the following steps for each of these functions.

- Write $f(x_1, x_2) = \mathbf{x}^T \mathbf{A} \mathbf{x}$ for some \mathbf{A} .
 - Diagonalize \mathbf{A} by writing $\mathbf{A} = \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^T$ for an orthogonal matrix \mathbf{Q} that additionally has $\det \mathbf{Q} = +1$. [*Hint:* Every 2×2 orthogonal matrix with determinant 1 is a *rotation matrix* $\mathbf{Q} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ for some $0 \leq \theta < 2\pi$. Find θ .]
 - Introduce new coordinates by setting $\mathbf{x} = \mathbf{Q} \mathbf{y}$, and substitute $\mathbf{y} = \mathbf{Q}^T \mathbf{x}$ into the quadratic form $\mathbf{x}^T \mathbf{A} \mathbf{x}$. Write the result both as an equation $f(y_1, y_2)$, and in matrix form, $\mathbf{y}^T \mathbf{\Lambda} \mathbf{y}$.
 - Sketch the conic section $\mathbf{x}^T \mathbf{A} \mathbf{x} = 1$ on the x_1x_2 -plane, and sketch $\mathbf{y}^T \mathbf{\Lambda} \mathbf{y} = 1$ on the y_1y_2 -plane (okay to use a computer).
 - Write $f(x_1, x_2)$ as either the sum or the difference of two squares. (Only one will be possible.)
6. Consider the following quadratic form:

$$\mathbf{x}^T \mathbf{A} \mathbf{x} = \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} & & \\ & \mathbf{A} & \\ & & \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 4(x_1 - x_2 + 2x_3)^2.$$

Find the 3×3 matrix \mathbf{A} and its pivots, rank, eigenvalues, and three (upper-left) subdeterminants: