

⑧ Solving $Ax=b$

Example: $x_1 + 2x_2 + 2x_3 + 2x_4 = b_1$

$$2x_1 + 4x_2 + 6x_3 + 8x_4 = b_2$$

$$3x_1 + 6x_2 + 8x_3 + 10x_4 = b_3$$

Note: Row 1 + Row 2 = Row 3 $\Rightarrow b_1 + b_2 = b_3$.

$$\left[\begin{array}{cccc|c} 1 & 2 & 2 & 2 & b_1 \\ 2 & 4 & 6 & 8 & b_2 \\ 3 & 6 & 8 & 10 & b_3 \end{array} \right] \rightarrow \left[\begin{array}{cccc|c} \textcircled{1} & 2 & 2 & 2 & b_1 \\ 0 & 0 & \textcircled{2} & 4 & b_2 - 2b_1 \\ 0 & 0 & 2 & 4 & b_3 - 3b_1 \end{array} \right]$$

"Augmented matrix" $[A \ b]$

↖ ↗
pivot cols

$$\rightarrow \left[\begin{array}{cccc|c} 1 & 2 & 2 & 2 & b_1 \\ 0 & 0 & 2 & 4 & b_2 - 2b_1 \\ 0 & 0 & 0 & 0 & b_3 - b_2 - b_1 \end{array} \right] \Rightarrow 0 = b_3 - b_2 - b_1 \quad \left(\text{e.g., } b = \begin{bmatrix} 1 \\ 5 \\ 6 \end{bmatrix} \right)$$

Solvability $Ax=b$ solvable when $b \in C(A)$.

If a combination of rows of A gives the zero row, then the same combin. of entries of b must give 0.

To find complete solution of $Ax=b$ (also called general sol'n).

① $x_{\text{particular}}$: - Set all free variables to zero

↑
"any sol'n" - Solve $Ax=b$ for pivot variables.

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Ex: Free vars $x_2 = x_4 = 0$:

$$x_1 + 2x_3 = 1$$

$$2x_3 = 3$$

, say $b = \begin{bmatrix} 1 \\ 5 \\ 6 \end{bmatrix} \Rightarrow x_3 = \frac{3}{2}, x_1 = -2.$

Thus, $x_p = \begin{bmatrix} -2 \\ 0 \\ 3/2 \\ 0 \end{bmatrix}$ is a sol'n.

Ex:

(2) $x_{nullspace}$: Find nullspace, x_n of A :

$$x_n = c \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + d \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

(3) Add x_{part} & x_{null} :

$$x = x_p + x_n$$

↑
particular
sol'n

↑
Set of all sol'n
to $Ax=0$.

Why this works: $Ax_p = b$

$$+ Ax_n = 0$$

$$\hline A(x_p + x_n) = b$$

Ex: $x = \begin{bmatrix} -2 \\ 0 \\ 3/2 \\ 0 \end{bmatrix} + c \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + d \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix}$

Overview of $Ax=b$ sol'n

of pivots.

Let A be an $m \times n$ matrix of rank r .

Note: $r \leq m$ (at most 1 pivot per row)

$r \leq n$ (at most 1 pivot per column)

(i) Full column rank: $\boxed{r=n}$. "every column has a pivot"

No free variables $\Rightarrow N(A) = \{\vec{0}\}$.

Sol'n to $Ax=b$ is $x=x_p$ (unique sol'n, if it exists)

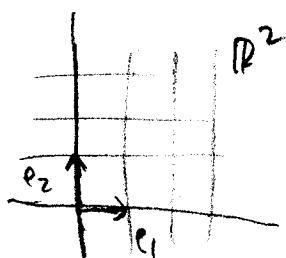
Ex: $A = \begin{bmatrix} 1 & 3 \\ 2 & 1 \\ 6 & 1 \end{bmatrix}$

Map $\mathbb{R}^2 \rightarrow \mathbb{R}^3$

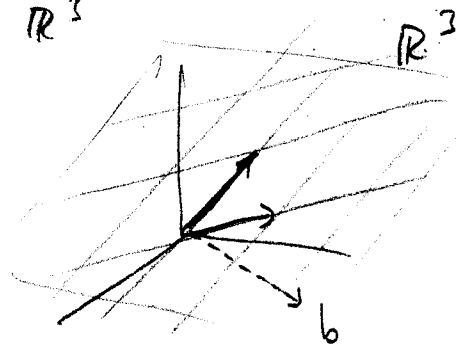
$$\begin{bmatrix} 1 & 3 \\ 2 & 1 \\ 6 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 2 \\ 6 \end{bmatrix} + x_2 \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}$$

\uparrow
in \mathbb{R}^2 in \mathbb{R}^3

RREF: $R = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$



\xrightarrow{A}



(ii) Full row rank: $\boxed{r=m}$ "every row has a pivot"

No zero rows in RREF \Rightarrow no requirements on b .

\Rightarrow Can solve $Ax=b$ for every b .

We're left with $n-r$ free variables \Rightarrow Infinitely many sol'n.

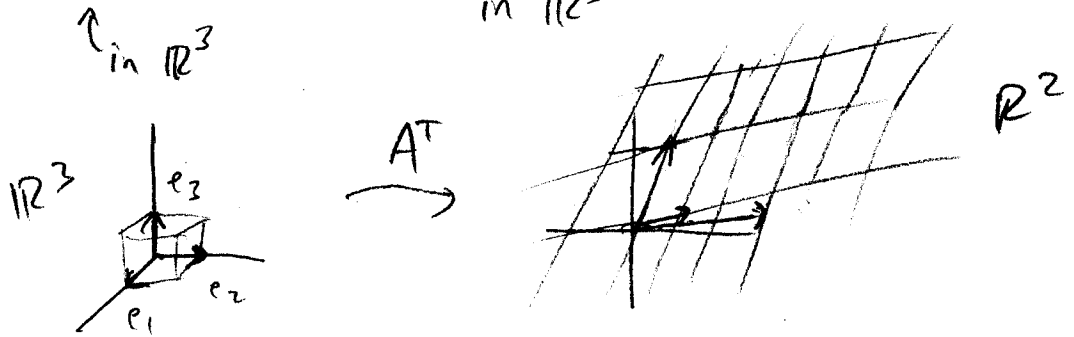
Ex: $A^T = \begin{bmatrix} 1 & 2 & 6 \\ 3 & 1 & 1 \end{bmatrix}$

RREF = $\begin{bmatrix} 1 & 0 & - \\ 0 & 1 & - \end{bmatrix}$

Map $\mathbb{R}^3 \rightarrow \mathbb{R}^2$

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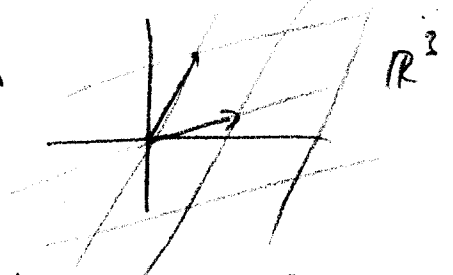
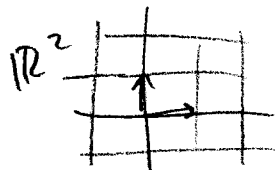
$$\begin{bmatrix} 1 & 2 & 6 \\ 3 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + x_3 \begin{bmatrix} 6 \\ 1 \end{bmatrix}$$



(iii) Full rank: $r = n = m$ (A is invertible)

Ex: $A = \begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix}$ Map $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ (bijection)

RREF: $R = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

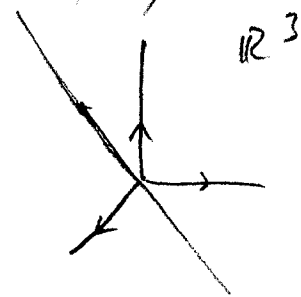
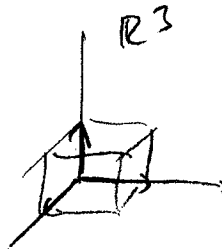


* $Ax = b$ has a unique solution!

(iv) $r < m, r < n$

$$R = \begin{bmatrix} I & F \\ 0 & 0 \end{bmatrix}$$

Ex:



* $Ax = b$ has 0 or ∞ solns.

Summary:

$r = m = n$

$R = I$

Unique sol'n to $Ax = b$

$r = n < m$

$R = \begin{bmatrix} I \\ 0 \end{bmatrix}$

0 or 1 sol'n to $Ax = b$

$r = m < n$

$R = \begin{bmatrix} I & F \end{bmatrix}$

∞ solns to $Ax = b$

up to perm. of cols.

$r < m, r < n$

$R = \begin{bmatrix} I & F \\ 0 & 0 \end{bmatrix}$

0 or ∞ solns to $Ax = b$