

## II) Other vector spaces

Let  $M_{3 \times 3}$  = set of all  $3 \times 3$  matrices.

This is a vector space:  $A+B, cA$  are  $3 \times 3$  matrices if  $A, B$  are.

(ignore  $AB$  for now.)

Basis:  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ .

Subspaces of  $M_{3 \times 3}$ :

-  $U$  = Upper triangular matrices  $\begin{bmatrix} a & b & c \\ 0 & d & e \\ 0 & 0 & f \end{bmatrix}$   $\dim U = 6$

-  $S$  = Symmetric matrices:  $\begin{bmatrix} a & b & c \\ b & d & e \\ c & e & f \end{bmatrix}$   $\dim S = 6$

-  $S \cap U$  = diagonal matrices:  $\begin{bmatrix} a & 0 & 0 \\ 0 & d & 0 \\ 0 & 0 & f \end{bmatrix}$   $\dim S \cap U = 3$

Note:  $S \cup U$  is not a subspace. (why?)

But the sum  $S + U = \{s+u : s \in S, u \in U\}$  is a subspace.

= all  $3 \times 3$  matrices. (why?)

$$\neq \dim(S+U) = \dim S + \dim U - \dim(S \cap U).$$

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Def: A linear map between vector spaces satisfies

$$\boxed{f(cv+dw) = cf(v) + df(w)} \text{ for all } c, d, v, w$$

An  $m \times n$  matrix is a linear map  $A: \mathbb{R}^n \rightarrow \mathbb{R}^m$

Indeed:  $A(cv+dw) = cAv + dAw$ .

Ex:  $\mathcal{C}^\infty$  is the vector space of smooth functions. ( $\infty$  diff'ble).

Consider the equation  $\boxed{\frac{d^2 y}{dx^2} + y = 0}$  (\*)

Which can be written as  $\underbrace{\left(\frac{d^2}{dx^2} + 1\right)}_{\text{"linear map"}} y = 0$ .

The set of solutions to (\*) is the nullspace of the

"linear differential operator"  $D := \frac{d^2}{dx^2} + 1$ . (2<sup>nd</sup> order).

Fact: The nullspace,  $y_n(x)$ , is 2-dimensional

Note:  $y_1(x) = \cos x$  and  $y_2(x) = \sin x$  are solutions. (i.e., in  $N(D)$ ).

So  $\{\cos x, \sin x\}$  is a basis for the solution space.

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i.e.,  $y_h(x) = C_1 \cos x + C_2 \sin x$  is the "general solution".

Ex 2: Now consider  $y'' + y = 10$

$$\text{i.e., } \underbrace{\left( \frac{d^2}{dx^2} + 1 \right)}_A y = 10$$

$$\vec{x} = \vec{b}$$

Sol'n:  $y = y_p + y_h$

↳  $y_p(x) = 10$ , by inspection!

General sol'n:  $y(x) = C_1 \cos x + C_2 \sin x + 10$ .

### Rank-one matrices

Ex:  $A = \begin{bmatrix} 1 & 4 & 5 \\ 2 & 8 & 10 \end{bmatrix}$       Basis for row space:  $\begin{bmatrix} 1 \\ 4 \\ 5 \end{bmatrix}$

Basis for col. space  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ .

Recall:  $\dim C(A) = \text{rank } A = \dim C(A^T)$ .

$$A = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 4 & 5 \end{bmatrix}$$

↳ pivot col

† Every rank-1 matrix has the form  $A = u v^T$ .

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Rank-1 matrices are the "building blocks"

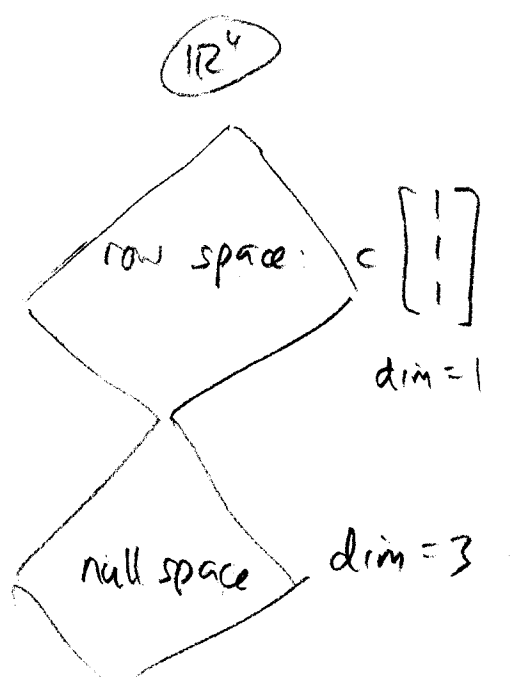
Rank- $k$  matrices are sums of at least  $k$  rank-1 matrices.

Ex: In  $\mathbb{R}^4$ ,  $S = \{ \vec{v} : v_1 + v_2 + v_3 + v_4 = 0 \}$   
 $=$  nullspace of  $A = [1 \ 1 \ 1 \ 1]$

rank  $A = 1 = r$

dim  $N(A) = n - r = n - 1$

Fundamental subspaces of  $A$ :



Basis:  $\left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

