

## 5 Nonlinear models of interactions

### Predator-prey model

Let  $P_t$  = size of prey,  $Q_t$  = size of predator.

$$\Delta P = F(P, Q), \quad \Delta Q = G(P, Q).$$

Prey, without predators:  $\Delta P = rP(1 - P/k)$

Predators, without prey:  $\Delta Q = -uQ$        $u$  = per capita death rate,  
so  $0 < u < 1$ .

One model: 
$$\begin{cases} \Delta P = rP(1 - P/k) - sPQ \\ \Delta Q = -uQ + vPQ \end{cases}$$
 "mass-action terms"

$$\Rightarrow \begin{cases} P_{t+1} = P_t(1 + r(1 - P_t/k)) - sP_tQ_t \\ Q_{t+1} = (1 - u)Q_t + vP_tQ_t \end{cases} \quad r, s, u, v, k > 0, \quad u < 1.$$

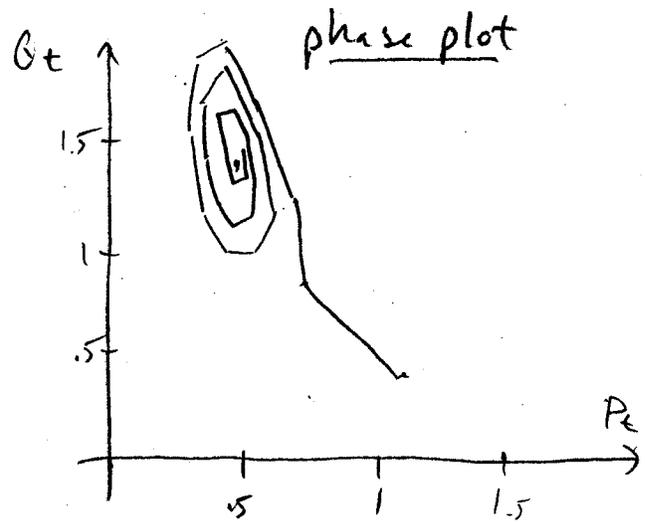
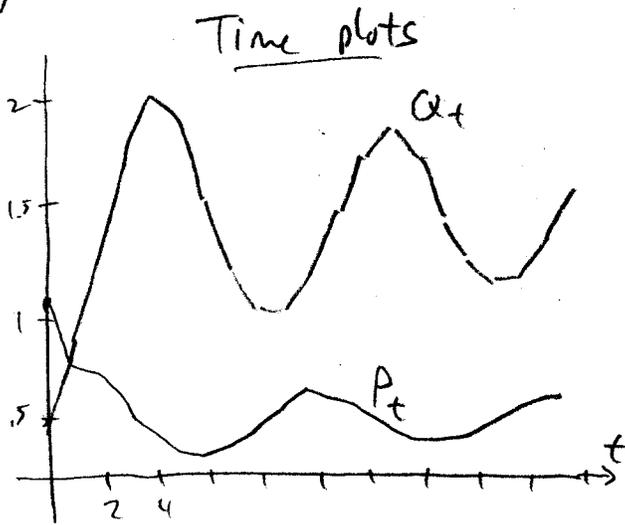
Hard: Estimate parameters.

Qualitatively, larger  $s, v \Rightarrow$  stronger predator-prey interaction.

We can plot the solutions several ways:

- Time plots:  $P_t, Q_t$ , vs.  $t$ .
- Phase plots:  $Q_t$  vs.  $P_t$ .

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Equilibria: Set  $P_{t+1} = P_t = P^*$ ,  $Q_{t+1} = Q_t = Q^*$ .

Example: Same as above, but let  $K=1$ ,  $r=1.3$ ,  $s=.5$   
 $u=.7$   $v=1.6$

$$P^* = P^*(1 + 1.3(1 - P^*)) - .5P^*Q^*$$

$$Q^* = .7Q^* + 1.6P^*Q^*$$

$$\Rightarrow \begin{cases} 0 = P^* 1.3(1 - P^*) - .5P^*Q^* = P^*(1.3 - 1.3P^* - .5Q^*) \\ 0 = .7Q^* + 1.6P^*Q^* = Q^*(.7 + 1.6P^*) \end{cases}$$

$$\Rightarrow Q^* = 0 \text{ or } P^* = .7/1.6 = .4375 \text{ (for Eq 2 to hold)}$$

IF  $Q^* = 0$ , then  $P^* = 0$  or  $P^* = 1$

IF  $P^* = .4375$ , then  $Q^* = 1.4625$ .

\* 3 equilibria:  $(P^*, Q^*) = (0, 0), (0, 1), (.4375, 1.4625)$ .

For general predator-prey: 
$$\begin{cases} P_{t+1} = P_t(1+r(1-P_t)) - sP_tQ_t \\ Q_{t+1} = (1-u)Q_t + vP_tQ_t \end{cases}$$

equilibrium equations are  $0 = P^*(r(1-P^*)) - sP^*Q^* = P^*(r(1-P^*) - sQ^*)$

$$0 = -uQ^* + vP^*Q^* = Q^*(-u + vP^*)$$

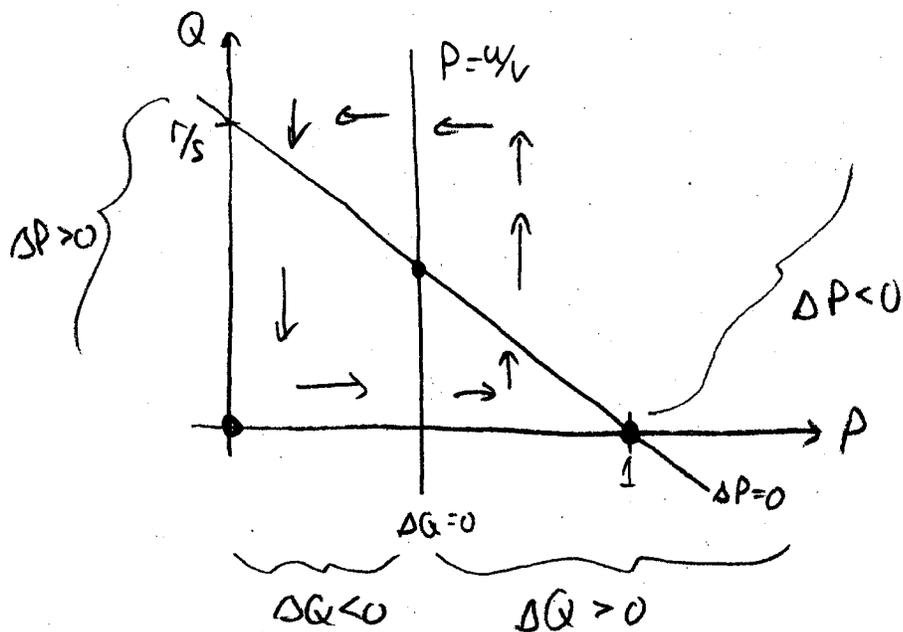
$\Rightarrow Q^* = 0$  or  $-u + vP^* = 0$  for Eq'n 2 to be satisfied

$P^* = 0$  or  $r(1-P^*) - sQ^* = 0$  for Eq'n 1.

Graph these 4 lines:  $P=0$ ,  $Q = \frac{r}{s}(1-P)$ ,  $Q=0$ ,  $P = \frac{u}{v}$   
(nullclines)

### Steady-states

- $(0, 0)$
- $(1, 0)$
- $(\frac{u}{v}, \frac{r}{s}(1 - \frac{u}{v}))$



Remark: Changing  $r$  or  $s$  doesn't affect the  $Q$ -nullcline.

Example: Prey: Agricultural crop

Predator: Insect.

Idea: Introduce a new crop variety with higher  $r$ , to try to "outgrow" the predator.

(4)

Reality:  $P^*$  unchanged,  $Q^*$  increases.

Remark:  $\Delta P$  &  $\Delta Q$  don't change sign w/in regions.

We can deduce that the phase portrait spirals counterclockwise, but can't tell if inward or outward.

Linearization: (how to determine stability)

Plug in  $P_t = P^* + p_t$ ,  $P_{t+1} = P_{t+1}^* + p_{t+1}$

$Q_t = Q^* + q_t$ ,  $Q_{t+1} = Q_{t+1}^* + q_{t+1}$

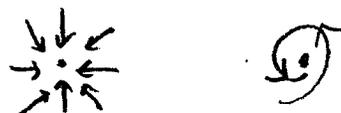
messy algebra  $\rightarrow$   $p_{t+1} = .43125 p_t - .21875 q_t - 1.3 p_t^2 - .5 p_t q_t$   
 $q_{t+1} = 2.39 p_t + q_t + 1.6 p_t q_t$

$\Rightarrow \begin{pmatrix} p_{t+1} \\ q_{t+1} \end{pmatrix} \approx \begin{pmatrix} .43125 & -.21875 \\ 2.39 & 1 \end{pmatrix} \begin{pmatrix} p_t \\ q_t \end{pmatrix}$

$\lambda = .7156 \pm .6565i$ ,  $|\lambda| = \sqrt{(.7156)^2 + (.6565)^2} = .9711 < 1$

\* Types of equilibrium points

•  $|\lambda_1| < 1$ ,  $|\lambda_2| < 1$  stable



•  $|\lambda_1| > 1$ ,  $|\lambda_2| > 1$  unstable



•  $|\lambda_1| < 1$ ,  $|\lambda_2| > 1$  saddle



## Other interaction models

Competition: 2 species fill the same niche in an environment.

$$\begin{cases} \Delta P = rP(1 - (P+Q)/K) \\ \Delta Q = uQ(1 - (P+Q)/K) \end{cases}$$

Question: Does one species "win"? Or can they co-exist?

More general: Now, suppose one preys on the other (e.g., wolf, deer).

$$\begin{cases} \Delta P = rP(1 - (P+Q)/K) - sPQ \\ \Delta Q = uQ(1 - (P+Q)/K) - vPQ \end{cases}$$

## Immune system vs. infective agent

P: immune cells

Q: level of infection

$$\begin{cases} \Delta P = rQ - sPQ \\ \Delta Q = uQ - vPQ \end{cases}$$

-sPQ: neg. effect on immune system from fighting

-vPQ: limited effect of immune system in fighting

rQ: Immune response is proportional to infection level.

## Mutualism

P = sharks

Q = feeder fish

$$\begin{cases} \Delta P = rP(1 - P/K) + sPQ \\ \Delta Q = -uQ + vPQ \end{cases}$$