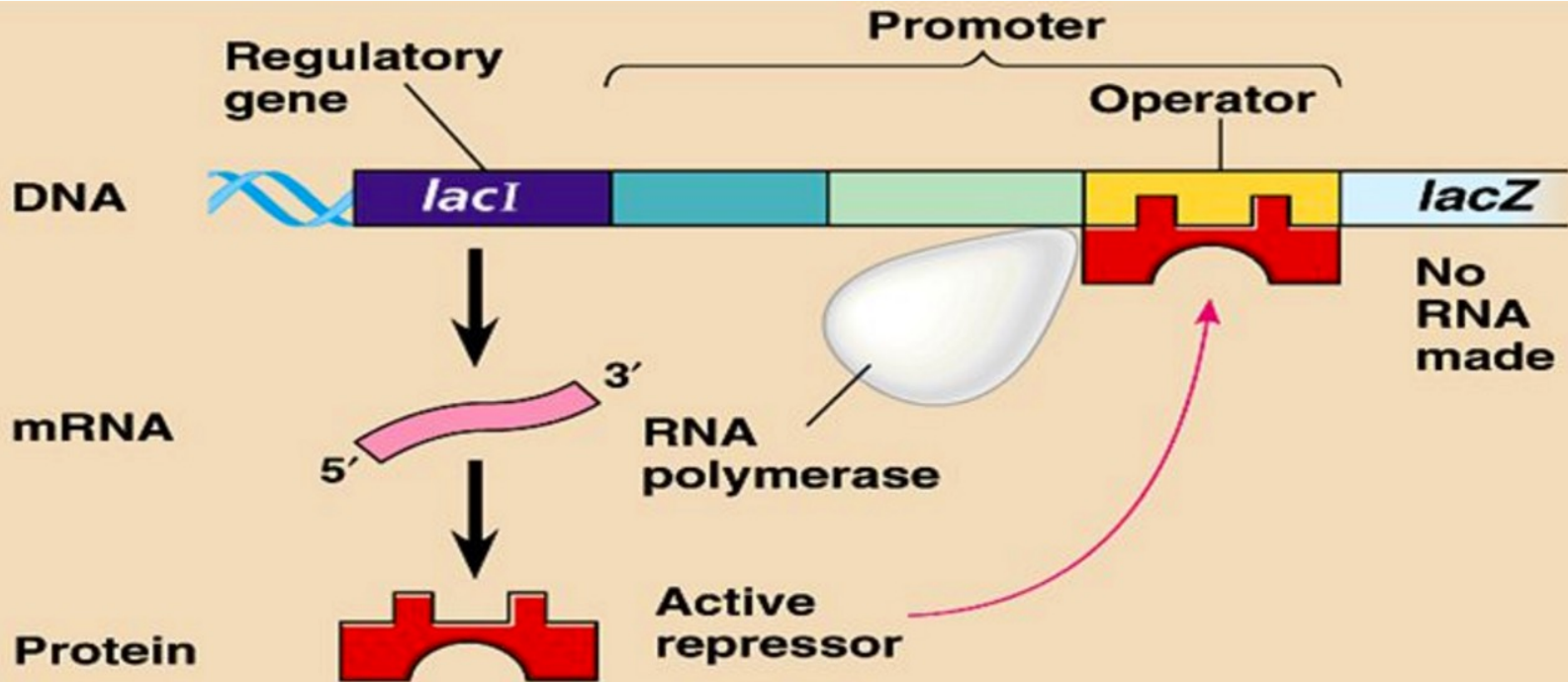


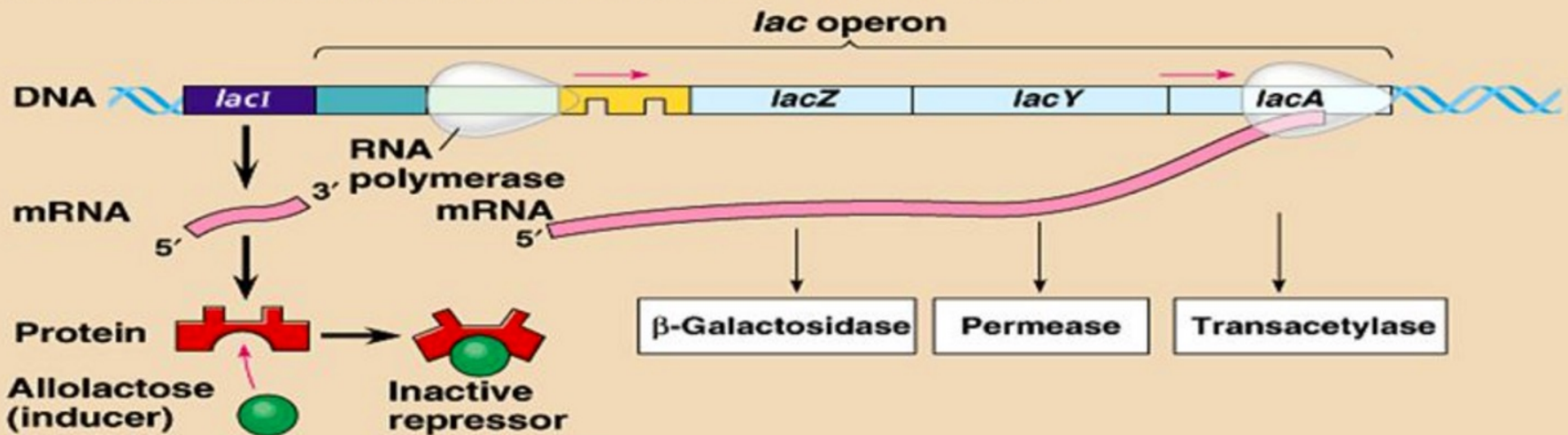
Advanced Boolean models of the *lac* operon

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The *lac* operon



(a) Lactose absent, repressor active, operon off

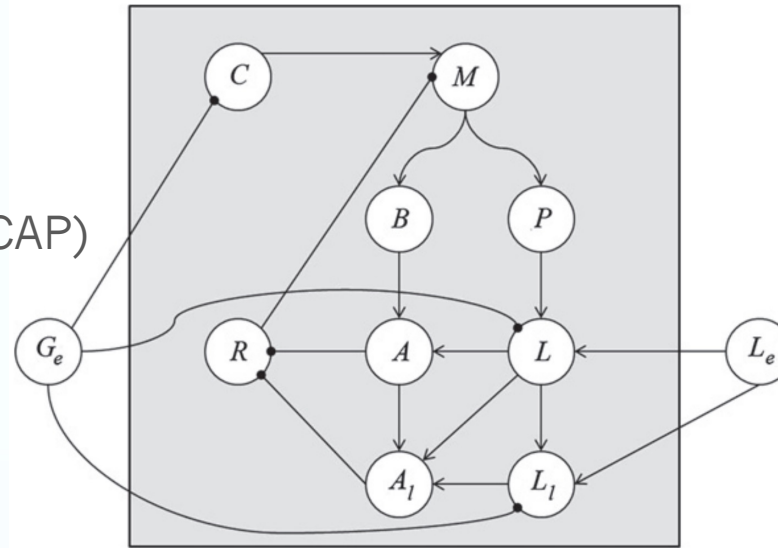


(b) Lactose present, repressor inactive, operon on

A 9-variable model

- Variables:

- M: mRNA
- P: *lac* permease
- B: β -galactosidase
- C: catabolite activator protein (CAP)
- R: repressor protein (LacI)
- A: high allolactose
- A_m : at least med. allolactose
- L: high (intracellular) lactose
- L_m : at least med. levels of lactose



$$f_M = \bar{R} \wedge C$$

$$f_P = M$$

$$f_B = M$$

$$f_C = \bar{G}_e$$

$$f_R = \bar{A} \wedge \bar{A}_m$$

$$f_A = L \wedge B$$

$$f_{A_m} = A \vee L \vee L_m$$

$$f_L = \bar{G}_e \wedge P \wedge L_e$$

$$f_{L_m} = \bar{G}_e \wedge (L \vee L_e)$$

- Assumptions:

- Transcription and translation require 1 unit of time.
- Degradation of all mRNA and proteins occur in 1 time-step.
- High levels of lactose or allolactose at any time t imply (at least) medium levels for the next time-step $t+1$.

A 9-variable model

- This 9-variable model is about as big of a state space that can be rendered.
- Here's a sample piece of the state space:

$$f_M = \bar{R} \wedge C$$

$$f_P = M$$

$$f_B = M$$

$$f_C = \bar{G}_e$$

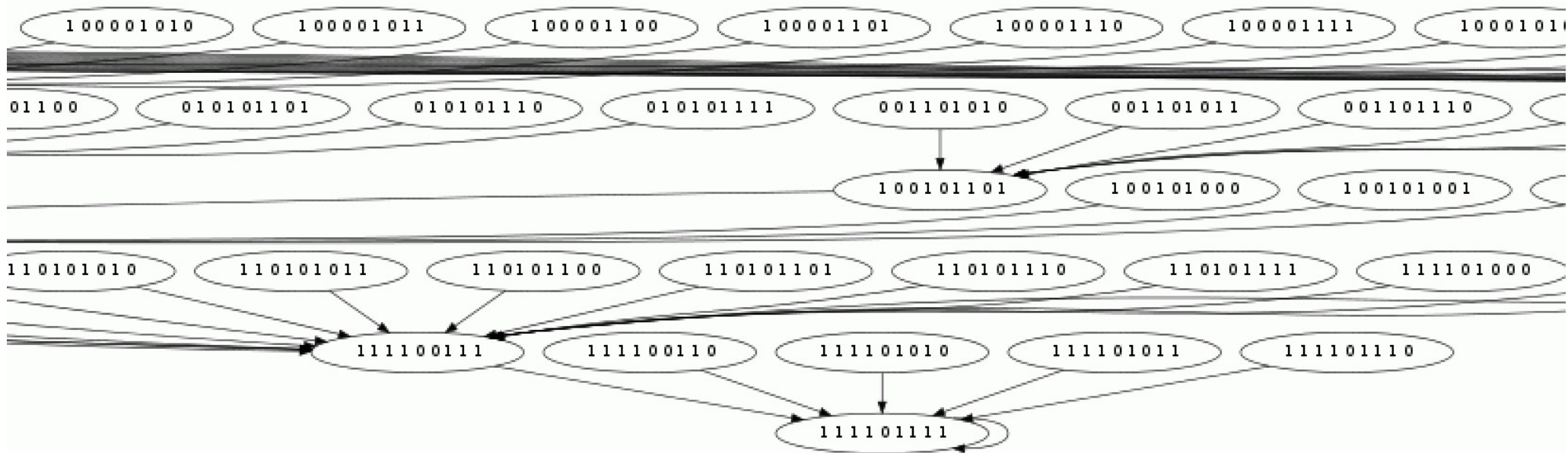
$$f_R = \bar{A} \wedge \bar{A}_m$$

$$f_A = L \wedge B$$

$$f_{A_m} = A \vee L \vee L_m$$

$$f_L = \bar{G}_e \wedge P \wedge L_e$$

$$f_{L_m} = \bar{G}_e \wedge (L \vee L_e)$$



What if the state space is too big?

- The previous 9-variable model is about as big as Cyclone can handle.
- However, many gene regulatory networks are much bigger.
 - A Boolean network model (2006) of T helper cell differentiation has 23 nodes, and thus a state space of size $2^{23} = 8,388,608$.
 - A Boolean network model (2003) of the segment polarity genes in *Drosophila melanogaster* (fruit fly) has 60 nodes, and a state space of size $2^{60} \approx 1.15 \times 10^{18}$.
 - There are many more examples...
- For these systems, we need to be able to analyze them without constructing the entire state space.
- Our first goal is to find the fixed points. This amounts to solving a system of equations:

$$\begin{cases} f_{x_1} = x_1 \\ f_{x_2} = x_2 \\ \vdots \\ f_{x_n} = x_n \end{cases}$$

$$f_M = \bar{R} \wedge C$$

$$f_P = M$$

$$f_B = M$$

$$f_C = \bar{G}_e$$

$$f_R = \bar{A} \wedge \bar{A}_m$$

$$f_A = L \wedge B$$

$$f_{A_m} = A \vee L \vee L_m$$

$$f_L = \bar{G}_e \wedge P \wedge L_e$$

$$f_{L_m} = \bar{G}_e \wedge (L \vee L_e)$$

How to find the fixed points

- Let's rename variables: $(M, P, B, C, R, A, A_m, L, L_m) = (x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9)$
- Writing each function in polynomial form, and then $f_{x_i} = x_i$ for each $i=1, \dots, 9$ yields the following system:

$$\begin{array}{l}
 f_M = \bar{R} \wedge C = M \\
 f_P = M = P \\
 f_B = M = B \\
 f_C = \bar{G}_e = C \\
 f_R = \bar{A} \wedge \bar{A}_m = R \\
 f_A = L \wedge B = A \\
 f_{A_m} = A \vee L \vee L_m = A_m \\
 f_L = \bar{G}_e \wedge P \wedge L_e = L \\
 f_{L_m} = \bar{G}_e \wedge (L \vee L_e) = L_m
 \end{array}
 \left\{ \begin{array}{l}
 x_1 + x_4 x_5 + x_4 = 0 \\
 x_1 + x_2 = 0 \\
 x_1 + x_3 = 0 \\
 x_4 + (G_e + 1) = 0 \\
 x_5 + x_6 x_7 + x_6 + x_7 + 1 = 0 \\
 x_6 + x_3 x_8 = 0 \\
 x_6 + x_7 + x_8 + x_9 + x_8 x_9 + x_6 x_8 + x_6 x_9 + x_6 x_8 x_9 = 0 \\
 x_8 + x_2 L_e (G_e + 1) = 0 \\
 x_9 + (G_e + 1)(x_8 + x_8 L_e + L_e) = 0
 \end{array} \right.$$

- We need to solve this for all 4 combinations: $(G_e, L_e) = (0, 0), (0, 1), (1, 0), (1, 1)$

How to find the fixed points with Macaulay2

- Let's first consider the case when $(G_e, L_e) = (0,1)$
- We can solve the system by typing the following commands into **Macaulay2** an open-source software package for computational algebraic geometry:

```
-- Define a ring of polynomials in 9 variables.
R = ZZ/2[x1,x2,x3,x4,x5,x6,x7,x8,x9];

-- Define a quotient ring, where each x_i^2 = x_i.
I = ideal(x1^2-x1, x2^2-x2, x3^2-x3, x4^2-x4, x5^2-x5, x6^2-x6, x7^2-x7, x8^2-x8, x9^2-x9);
Q = R / I;

-- Shortcut for AND and OR functions.
RingElement | RingElement :=(x,y)->x+y+x*y;
RingElement & RingElement :=(x,y)->x*y;

-- Set the parameters (constants).
Ge = 0_Q
Le = 1_Q

-- This is the 9-variable lac operon model.
f1 = (1+x5) & x4;
f2 = x1;
f3 = x1;
f4 = 1+Ge;
f5 = (1+x6) & (1+x7);
f6 = x8 & x3;
f7 = x6 | x8 | x9;
f8 = (1+Ge) & x2 & Le;
f9 = (1+Ge) & (x8 | Le);

-- Compute the ideal to find the fixed point(s).
I = ideal(f1+x1, f2+x2, f3+x3, f4+x4, f5+x5, f6+x6, f7+x7, f8+x8, f9+x9)

-- Compute a Groebner basis.
G = gens gb I
```

What does this code mean?

The output of `G = Gens gb I;` is the following:

$$|x_9+1, x_8+1, x_7+1, x_6+1, x_5, x_4+1, x_3+1, x_2+1, x_1+1|$$

This is short-hand for the following system of equations:

$$x_9 + 1 = 0, x_8 + 1 = 0, \dots, x_4 + 1 = 0, x_5 = 0, x_3 + 1 = 0, \dots, x_1 + 1 = 0$$

This simple system has the **same set of solutions** as the much more complicated system we started with:

$$\left\{ \begin{array}{l} x_1 + x_4 x_5 + x_4 = 0 \\ x_1 + x_2 = 0 \\ x_1 + x_3 = 0 \\ x_4 + (G_e + 1) = 0 \\ x_5 + x_6 x_7 + x_6 + x_7 + 1 = 0 \\ x_6 + x_3 x_8 = 0 \\ x_6 + x_7 + x_8 + x_9 + x_8 x_9 + x_6 x_8 + x_6 x_9 + x_6 x_8 x_9 = 0 \\ x_8 + x_2 L_e (G_e + 1) = 0 \\ x_9 + (G_e + 1)(x_8 + x_8 L_e + L_e) = 0 \end{array} \right.$$

What does a Gröbner basis tell us?

The output of `G = Gens gb I;` is the following:

$$|x_9+1, x_8+1, x_7+1, x_6+1, x_5, x_4+1, x_3+1, x_2+1, x_1+1|$$

This is short-hand for the following system of equations:

$$x_9 + 1 = 0, x_8 + 1 = 0, \dots, x_4 + 1 = 0, x_5 = 0, x_3 + 1 = 0, \dots, x_1 + 1 = 0$$

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Gröbner bases vs. Gaussian elimination

✧ Gröbner bases are a generalization of Gaussian elimination, but for systems of polynomials (instead of systems of linear equations)

✧ In both cases:

- The input is a complicated system that we wish to solve.
- The output is a simple system that we can easily solve by inspection.

✧ Consider the following example:

- Input: The 2x2 system of linear equations
$$\begin{cases} x + 2y = 1 \\ 3x + 8y = 1 \end{cases}$$
- Gaussian elimination yields the following:

$$\left[\begin{array}{cc|c} 1 & 2 & 1 \\ 3 & 8 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 1 & 2 & 1 \\ 0 & 2 & -2 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 1 & 0 & 3 \\ 0 & 2 & -2 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 1 & 0 & 3 \\ 0 & 1 & -1 \end{array} \right]$$

- This is just the much simpler system with the same solution!
$$\begin{cases} x + 0y = 3 \\ 0x + y = -1 \end{cases}$$

Back-substitution & Gaussian elimination

- ✧ We don't necessarily need to do Gaussian elimination until the matrix is the identity. As long as it is **upper-triangular**, we can back-substitute and solve by hand.

- ✧ For example:

$$\begin{cases} x + z = 2 \\ y - z = 8 \\ 0 = 0 \end{cases}$$

- ✧ Similarly, when Sage outputs a Gröbner basis, it will be in “upper-triangular form”, and we can solve the system easily by back-substituting.
- ✧ We'll do an example right away. For this part of the class, you can think of Gröbner bases as a mysterious “**black box**” that does what we want.
- ✧ We'll study them in more detail shortly, and understand what's going on behind the scenes.

Gröbner bases: an example

✧ Let's use Sage to solve the following system:

$$\begin{cases} x^2 + y^2 + z^2 = 1 \\ x^2 - y + z^2 = 0 \\ x - z = 0 \end{cases}$$

```
17 P.<x,y,z>=PolynomialRing(RR,3,order='lex'); P
18     Multivariate Polynomial Ring in x, y, z over Real Field with 53 bits of precision
19
20 I = ideal(x^2+y^2+z^2-1, x^2-y+z^2, x-z); I
21     Ideal (x^2 + y^2 + z^2 - 1.000000000000000, x^2 - y + z^2, x - z) of Multivariate Polynomial
    Ring in x, y, z over Real Field with 53 bits of precision
22
23 B = I.groebner_basis(); B
24     [x - z, y - 2.000000000000000*z^2, z^4 + 0.500000000000000*z^2 - 0.250000000000000]
```

✧ From this, we get an “upper-triangular” system:

✧ This is something we can solve by hand.

$$\begin{cases} x - z = 0 \\ y - 2z^2 = 0 \\ z^4 + .5z^2 - .25 = 0 \end{cases}$$

Gröbner bases: an example (cont.)

✧ To solve the reduced system:

$$\begin{cases} x - z = 0 \\ y - 2z^2 = 0 \\ z^4 + .5z^2 - .25 = 0 \end{cases}$$

▪ Solve for z in Eq. 3: $z = \pm \sqrt{\frac{-1 + \sqrt{5}}{4}}$

▪ Plug z into Eq. 2 and solve for y : $y = 2z^2 = \frac{-1 + \sqrt{5}}{2}$

▪ Plug y & z into Eq. 1 and solve for x : $x = z = \pm \sqrt{\frac{-1 + \sqrt{5}}{4}}$

✧ Thus, we get 2 solutions to the original system:

$$\begin{cases} x^2 + y^2 + z^2 = 1 \\ x^2 - y + z^2 = 0 \\ x - z = 0 \end{cases}$$

$$(x_1, y_1, z_1) = \left(\sqrt{\frac{-1 + \sqrt{5}}{4}}, \frac{-1 + \sqrt{5}}{2}, \sqrt{\frac{-1 + \sqrt{5}}{4}} \right)$$

$$(x_2, y_2, z_2) = \left(-\sqrt{\frac{-1 + \sqrt{5}}{4}}, \frac{-1 + \sqrt{5}}{2}, -\sqrt{\frac{-1 + \sqrt{5}}{4}} \right)$$

Returning to the *lac* operon

- We have 9 variables: $(M, P, B, C, R, A, A_m, L, L_m) = (x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9)$
- Writing each function in polynomial form, we need to solve the system $f_{x_i} = x_i$ for each $i=1, \dots, 9$, which is the following:

$$\begin{array}{l}
 f_M = \bar{R} \wedge C = M \\
 f_P = M = P \\
 f_B = M = B \\
 f_C = \bar{G}_e = C \\
 f_R = \bar{A} \wedge \bar{A}_m = R \\
 f_A = L \wedge B = A \\
 f_{A_m} = A \vee L \vee L_m = A_m \\
 f_L = \bar{G}_e \wedge P \wedge L_e = A_m \\
 f_{L_m} = \bar{G}_e \wedge (L \vee L_e) = L_m
 \end{array}
 \left\{
 \begin{array}{l}
 x_1 + x_4 x_5 + x_4 = 0 \\
 x_1 + x_2 = 0 \\
 x_1 + x_3 = 0 \\
 x_4 + (G_e + 1) = 0 \\
 x_5 + x_6 x_7 + x_6 + x_7 + 1 = 0 \\
 x_6 + x_3 x_8 = 0 \\
 x_6 + x_7 + x_8 + x_9 + x_8 x_9 + x_6 x_8 + x_6 x_9 + x_6 x_8 x_9 = 0 \\
 x_8 + x_2 L_e (G_e + 1) = 0 \\
 x_9 + (G_e + 1)(x_8 + x_8 L_e + L_e) = 0
 \end{array}
 \right.$$

- We need to solve this for all 4 combinations: $(G_e, L_e) = (0, 0), (0, 1), (1, 0), (1, 1)$ (we already did (1,1)).

Returning to the *lac* operon

- Again, we use variables $(M, P, B, C, R, A, A_m, L, L_m) = (x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9)$ and parameters $(G_e, L_e) = (0, 0)$
- Here is the output from Sage:

```
1
2 P.<x1,x2,x3,x4,x5,x6,x7,x8,x9> = PolynomialRing(GF(2), 9, order = 'lex'); P
3   Multivariate Polynomial Ring in x1, x2, x3, x4, x5, x6, x7, x8, x9 over Finite Field of size 2
4
5 Le=0;
6 Ge=0;
7 print "Le =", Le;
8 print "Ge =", Ge;
9
9   Le = 0
   Ge = 0
10
11 I = ideal(x1+x4*x5+x4, x1+x2, x1+x3, x4+(Ge+1), x5+x6*x7+x6+x7+1, x6+x3*x8,
12 x6+x7+x8+x9+x8*x9+x6*x8+x6*x9+x6*x8*x9, x8+Le*(Ge+1)*x2, x9+(Ge+1)*(Le+x8+Le*x8)); I
13
13   Ideal (x1 + x4*x5 + x4, x1 + x2, x1 + x3, x4 + 1, x5 + x6*x7 + x6 + x7 + 1, x3*x8 + x6, x6*x8*x9 +
14 x6*x8 + x6*x9 + x6 + x7 + x8*x9 + x8 + x9, x8, x8 + x9) of Multivariate Polynomial Ring in x1, x2
15 , x3, x4, x5, x6, x7, x8, x9 over Finite Field of size 2
16
17 B = I.groebner_basis(); B
18
18   [x1, x2, x3, x4 + 1, x5 + 1, x6, x7, x8, x9]
```

- $(M, P, B, C, R, A, A_m, L, L_m) = (x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9) = (0, 0, 0, 1, 1, 0, 0, 0, 0)$

Returning to the *lac* operon

- Again, we use variables $(M, P, B, C, R, A, A_m, L, L_m) = (x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9)$ and parameters $(G_e, L_e) = (1, 0)$

- Here is the output from Sage:

```
1 |
2 P.<x1,x2,x3,x4,x5,x6,x7,x8,x9> = PolynomialRing(GF(2), 9, order='lex'); P
3 | Multivariate Polynomial Ring in x1, x2, x3, x4, x5, x6, x7, x8, x9 over Finite Field of size 2
4 |
5 Le=0;
6 Ge=1;
7 print "Le =", Le;
8 print "Ge =", Ge;
9 |
9 | Le = 0
9 | Ge = 1
10 |
11 I = ideal(x1+x4*x5+x4, x1+x2, x1+x3, x4+(Ge+1), x5+x6*x7+x6+x7+1, x6+x3*x8,
12 | x6+x7+x8+x9+x8*x9+x6*x8+x6*x9+x6*x8*x9, x8+Le*(Ge+1)*x2, x9+(Ge+1)*(Le+x8+Le*x8)); I
12 | Ideal (x1 + x4*x5 + x4, x1 + x2, x1 + x3, x4, x5 + x6*x7 + x6 + x7 + 1, x3*x8 + x6, x6*x8*x9 +
12 | x6*x8 + x6*x9 + x6 + x7 + x8*x9 + x8 + x9, x8, x9) of Multivariate Polynomial Ring in x1, x2,
12 | x3, x4, x5, x6, x7, x8, x9 over Finite Field of size 2
13 |
14 B = I.groebner_basis(); B
15 | [x1, x2, x3, x4, x5 + 1, x6, x7, x8, x9]
```

- $(M, P, B, C, R, A, A_m, L, L_m) = (x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9) = (0, 0, 0, 0, 1, 0, 0, 0, 0)$

Returning to the *lac* operon

- Again, we use variables $(M, P, B, C, R, A, A_m, L, L_m) = (x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9)$ and parameters $(G_e, L_e) = (0, 1)$
- Here is the output from Sage:

```
1
2 P.<x1,x2,x3,x4,x5,x6,x7,x8,x9> = PolynomialRing(GF(2), 9, order = 'lex'); P
3   Multivariate Polynomial Ring in x1, x2, x3, x4, x5, x6, x7, x8, x9 over Finite Field of size 2
4
5 Le=0;
6 Ge=1;
7 print "Le =", Le;
8 print "Ge =", Ge;
9
10   Le = 0
11   Ge = 1
12
13 I = ideal(x1+x4*x5+x4, x1+x2, x1+x3, x4+(Ge+1), x5+x6*x7+x6+x7+1, x6+x3*x8,
14 x6+x7+x8+x9+x8*x9+x6*x8+x6*x9+x6*x8*x9, x8+Le*(Ge+1)*x2, x9+(Ge+1)*(Le+x8+Le*x8)); I
15
16   Ideal (x1 + x4*x5 + x4, x1 + x2, x1 + x3, x4, x5 + x6*x7 + x6 + x7 + 1, x3*x8 + x6, x6*x8*x9 +
17   x6*x8 + x6*x9 + x6 + x7 + x8*x9 + x8 + x9, x8, x9) of Multivariate Polynomial Ring in x1, x2,
18   x3, x4, x5, x6, x7, x8, x9 over Finite Field of size 2
19
20 B = I.groebner_basis(); B
21
22   [x1, x2, x3, x4, x5 + 1, x6, x7, x8, x9]
```

$$(M, P, B, C, R, A, A_m, L, L_m) = (x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9) = (1, 1, 1, 1, 0, 1, 1, 1, 1)$$

Fixed point analysis of the *lac* operon

Using the variables $(M, P, B, C, R, A, A_m, L, L_m) = (x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9)$

we got the following fixed points for each choice of parameters (G_e, L_e)

- Input: $(G_e, L_e) = (0, 0)$

Fixed point: $(x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9) = (0, 0, 0, 1, 1, 0, 0, 0, 0)$

- Input: $(G_e, L_e) = (1, 0)$

Fixed point: $(x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9) = (0, 0, 0, 0, 1, 0, 0, 0, 0)$

- Input: $(G_e, L_e) = (1, 1)$

Fixed point: $(x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9) = (0, 0, 0, 0, 1, 0, 0, 0, 0)$

- Input: $(G_e, L_e) = (0, 1)$

Fixed point: $(x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9) = (1, 1, 1, 1, 0, 1, 1, 1, 1)$

All of these fixed points make biological sense!