Visual Algebra

Lecture 2.11: Groups of matrices

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Groups of matrices

Definition

A group G is linear if it is isomorphic to a group of matrices.

We also say that G is represented by matrices.

The branch of mathematics that studys this is representation theory.

By Cayley's theorem, every finite group can be represented with permutation matrices.

We've seen how to represent a number of groups with 2×2 matrices:

- the Klein 4-group
- cyclic groups
- dihedral groups
- quaternion groups

- dicyclic groups
- diquaternion groups
- semidihedral groups
- semiabelian groups

$$\underbrace{\begin{bmatrix} \zeta_n & 0 \\ 0 & \overline{\zeta}_n \end{bmatrix}}_{R_n}, \underbrace{\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}}_{F}, \underbrace{\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}}_{J},$$

The group $\langle a, b \mid ab^2a^{-1} = b^3 \rangle$ is not linear.

Braid groups

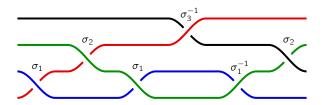
Definition

The braid group is defined by the presentation

$$\mathsf{Braid}_n = \big\langle \sigma_1, \dots, \sigma_{n-1} \mid \underbrace{\sigma_i \sigma_j = \sigma_j \sigma_i \text{ if } |i-j| \geq 2}_{\textit{Type I relation}}, \quad \underbrace{\sigma_i \sigma_{i+1} \sigma_i = \sigma_{i+1} \sigma_i \sigma_{i+1}}_{\textit{Type II relation}} \big\rangle.$$

Here is the element

$$\sigma_1\sigma_2\sigma_1\sigma_3^{-1}\sigma_1^{-1}\sigma_2=\sigma_1\sigma_2\sigma_3^{-1}\sigma_2\in\mathsf{Braid}_4=\langle\sigma_1,\sigma_2,\sigma_3\rangle$$



Braid groups

The braid relations come from the following easy-to-verify properties of physical braids:

$$\sigma_{3} = \sigma_{j}\sigma_{i}$$

$$\sigma_{1} = \sigma_{1} \quad (\text{if } |i-j| \ge 2)$$

$$\sigma_{1} = \sigma_{2} \quad \sigma_{2}$$

$$\sigma_{1} = \sigma_{2} \quad \sigma_{2}$$

$$\sigma_{1} = \sigma_{2} \quad \sigma_{3} \quad \sigma_{4} \quad \sigma_{5} = \sigma_{5} \quad \sigma_$$

For 70 years, it was unknown if braid groups were linear.

Theorem (Bigelow, 2000; Krammer, 2002)

Braid groups are linear.

Groups of matrices

Matrices are a rich source of groups in their own right.

Let's define a few terms so we can better speak of certain sets of matrices.

Square matrices are objects that we can add, subtract, and multiply, but not always divide.

Definition

A ring is an abelian group R that is additionally

- closed under multiplication, and
- satisfies the distributive property.

If we can also divide by any nonzero element, it is a field, \mathbb{F} .

Some rings contain zero divisors: two nonzero x, y such that xy = 0.

For example, $2 \cdot 3 = 0$ in \mathbb{Z}_6 .

In other rings, multiplication does not commute.

Henceforth, we will usually assume that our matrix coefficients m_{ii} come from a field \mathbb{F} .

Basically, we're intersted in examples like \mathbb{Q} , \mathbb{R} , \mathbb{C} , \mathbb{Z}_p , etc.

Groups of matrices

The set $\mathsf{Mat}_{n,m}(\mathbb{F})$ of $n \times m$ matrices is a group under addition, but a very boring one.

It is isomorphic to the direct product $\mathbb{F}^{mn} := \mathbb{F} \times \cdots \times \mathbb{F}$ of nm copies of \mathbb{F} .

It is more interesting to look at groups of square matrices under multiplication.

Definition

Let $\mathsf{Mat}_n(\mathbb{F})$ be the set of $n \times n$ matrices with coefficients from \mathbb{F} .

Since matrices represent linear transformation, many standard matrix groups have "linear" in their names.

Definition

The general linear group of degree n over R is the set of invertible matrices with coefficients from R:

$$GL_n(R) = \{A \in Mat_n(R) \mid \det A \neq 0\}.$$

The special linear group is the subgroup of matrices with determinant 1:

$$\mathsf{SL}_n(R) = \big\{ A \in \mathsf{GL}_n(R) \mid \det A = 1 \big\}.$$

An interesting group of order 24

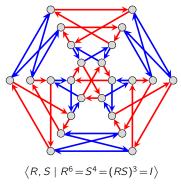
Some interesting finite groups arise as special or general linear groups over \mathbb{Z}_q . For example,

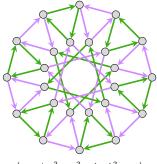
$$\mathsf{SL}_2(\mathbb{Z}_3) = \left\langle A, B \mid A^3 = B^3 = (AB)^2 \right\rangle = \left\langle A, B, C \mid A^3 = B^3 = C^2 = CAB \right\rangle \cong Q_8 \rtimes \mathbb{Z}_3,$$

and the matrices A and B can be taken to be

$$A = \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 0 & -1 \end{bmatrix}, \qquad B = \begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 1 & -1 \end{bmatrix}.$$

Here are Cayley graphs for different generating sets:





$$\langle x, y \mid x^3 = y^3 = (xy)^3 = 1 \rangle$$

The Hamiltonians

The group $SL_2(\mathbb{Z}_3)$ can be represented with quaternions. The Hamiltonians are the ring

$$\mathbb{H} = \left\{ a + bi + cj + dk \mid a, b, c, d \in \mathbb{R} \right\}.$$

One way to represent these is with 2×2 matrices over \mathbb{C} :

$$\mathbb{H}\cong\left\{\begin{bmatrix}z&w\\-\overline{w}&\overline{z}\end{bmatrix}:z,w\in\mathbb{C}\right\}=\left\{\begin{bmatrix}a+bi&c+di\\-c+di&a-bi\end{bmatrix}:a,b,c,d\in\mathbb{R}\right\}.$$

Yet another way involves 4×4 matrices over \mathbb{R} :

$$\mathbb{H} \cong \left\{ \begin{bmatrix} a & b & -d & -c \\ -b & a & -c & d \\ d & c & a & b \\ c & -d & -b & a \end{bmatrix} : a, b, c, d \in \mathbb{R} \right\}.$$

Removing 0 from $\mathbb H$ defines a multiplicative group $\mathbb H^*$ with lots of interesting subgroups.

One of them is the unit quaternions, which physicists assoiciate with points in a 3-sphere:

$$S^3 := \{ a + bi + cj + dk \mid a^2 + b^2 + c^2 + d^2 = 1 \}.$$

The group $SL_2(\mathbb{Z}_3)$ is isomorphic to a subgroup called the binary tetrahedral group,

$$SL_2(\mathbb{Z}_3) \cong 2T := \{ \pm 1, \pm i, \pm j, \pm k, \frac{1}{2} (\pm 1 \pm i \pm j \pm k) \} \le S^3.$$

Finite subgroups of $SL_2(\mathbb{C})$

The binary triangle group with parameters (p, q, r) is

$$\Gamma(p,q,r) = \langle a,b,c \mid a^p = b^q = c^r = abc \rangle.$$

Theorem

Every finite subgroup of $SL_2(\mathbb{C})$ is isomorphic to one of the following:

- **v** cyclic group of order n: $C_n = \langle \zeta_n \rangle$
- binary dihedral group $\Gamma(2,2,n)$ of order 4n: $\langle \zeta_{2n},j\rangle\cong \mathrm{Dic}_{2n}$
- binary tetrahedral group $\Gamma(2,3,3)$ of order 24:

$$2T = \left\langle i, j, \frac{1}{2}(1+i-j+k) \right\rangle \cong \mathsf{SL}_2(\mathbb{Z}_3)$$

■ binary octahedral group $\Gamma(2, 3, 4)$ of order 48:

$$20 = \left\langle \frac{1+i}{\sqrt{2}}, j, \frac{1}{2} (1+i-j+k) \right\rangle$$

■ binary icosahedral group $\Gamma(2, 3, 5)$ of order 120:

$$2I = \left\langle j, \frac{1}{2}(1+i+j+k), \frac{1}{2}(\phi+\phi^{-1}i+j) \right\rangle \cong SL_2(\mathbb{Z}_5).$$

Matrix groups over other finite fields

The group $GL_n(\mathbb{Z}_p)$ consists of the linear maps of the vector space \mathbb{Z}_p^n to itself.

Each one is determined by an ordered basis v_1, \ldots, v_n of \mathbb{Z}_p^n .

Let's count these. There are:

- 1. $p^n 1$ choices for v_1 , then
- 2. $p^n p$ choices for v_2 , then
- 3. $p^n p^2$ choices for v_3 , and so on...
- n. $p^n p^{n-1}$ choices for v_n .

Therefore,

$$\left| \mathsf{GL}_n(\mathbb{Z}_p) \right| = (p^n - 1)(p^n - p) \cdots (p^n - p^{n-1}).$$

These groups have many subgroups, and they often happen to coincide with familiar groups that we have seen.

For example, by "dumb luck",

$$\mathcal{D}_9 \cong \left\langle \begin{bmatrix} 16 & 10 \\ 7 & 14 \end{bmatrix}, \begin{bmatrix} 14 & 6 \\ 10 & 3 \end{bmatrix} \right\rangle \leq \mathsf{GL}_2(\mathbb{Z}_{17}), \qquad \mathsf{Dic}_{12} \cong \left\langle \begin{bmatrix} 2 & 7 \\ 7 & 3 \end{bmatrix}, \begin{bmatrix} 0 & 10 \\ 1 & 0 \end{bmatrix} \right\rangle \leq \mathsf{GL}_2(\mathbb{Z}_{11}).$$

GroupNames online database

metacyclic, supersoluble, monomial, Z-group, 2-hyperelementary

Aliases: Do. Co:Co. Co.So. sometimes denoted Dos or Diho or Dihos. SmallGroup(18.1)

Series: Derived - Chief - Lower central - Upper central

Derived series $C_1 - C_9 - D_9$

Generators and relations for D₉ $G = \langle a | b | a^9 = b^2 = 1 | bab = a^{-1} \rangle$

Subgroups: 16 in 6 conjugacy classes, 4 normal (all characteristic)



Character table of Do

class size	1	2 9	3 2	9A 2	9B 2	9C 2	
Ρ1	1	1	1	1	1	1	trivial
ρ ₂	1	-1	1	1	1	1	linear of order 2
ρ3	2	0	2	-1	-1	-1	orthogonal lifted from S
P4	2	0	-1	ζ3+ζ4	ζ2+ζ2	ζ8+ζ9	orthogonal faithful
ρ5	2	0	-1	ζ\$+ζο	₹2+₹4	77+72	orthogonal faithful
0-				77.72			orthogonal faithful

Permutation representations of D₉

On 9 points - transitive group 9T3
Regular action on 18 points - transitive group 18T5

 D_9 is a maximal subgroup of

C₉:C₆ C₉:S₃ C₃.S₄ C₅²:D₉ D_{9p}: D₂₇ D₄₅ D₆₃ D₉₉ D₁₁₇ D₁₅₃ D₁₇₁ D₂₀₇ ...

Do is a maximal quotient of

D₉ is a maximal quotient of C₀:S₁ C₁:S₄ C²:D₉

C_{3p}.S₃: Dic₉ D₂₇ D₄₅ D₆₃ D₉₉ D₁₁₇ D₁₅₃ D₁₇₁ ... Polynomial with Galois group D₉ over Q

olynomial with Galois group D₉ over Q action f(x) Disc(f) 973 x⁹+3x⁸-67x⁷-226x⁶+699x⁵+1211x⁴-3137x³+940x²+904x-392 2²²-7⁴-13²-19⁶-29²-229⁴-547²

Matrix representation of D_9 -in $GL_2(\mathbb{F}_{17})$ generated by

16 10 14 6 10 3

metacyclic, supersoluble, monomial, 2-hyperelementary

Aliases: Dic₆, C₃×Q₈, C₄,S₃, C₂,D₆, C₁₂,C₂, Dic₃,C₂, C₆,C₇, SmallGroup(24,4)

Series: Derived -Chief -Lower central -Upper central

Derived series C₁ - C₆ - Dic₆

Generators and relations for Dic₆ $G = \langle a, b | a^{12} = 1, b^2 = a^6, bab^{-1} = a^{-1} \rangle$

Subgroups: 18 in 12 conjugacy classes. 9 normal (7 characteristic)

Quotients: C₁, C₂, C₇, S₃, Q₈, D₆, Dic₆



Character table of Dic6

	class	11	2	3	44	AD	40	6	12A	120	
	size	i	1	2	2	6	6	2	2	2	
ľ	ρ1	1	1	1	1	1	1	1	1	1	trivial
	ρ2	1	1	1	1	-1	-1	1	1	1	linear of order 2
	ρ3	1	1	1	-1	-1	1	1	-1	-1	linear of order 2
	ρ4	1	1	1	-1	1	-1	1	-1	-1	linear of order 2
	ρ ₅	2	2	-1	2	0	0	-1	-1	-1	orthogonal lifted from S ₃
	ρ ₆	2	2	-1	-2	0	0	-1	1	1	orthogonal lifted from D ₆
	P7	2	-2	2	0	0	0	-2	0	0	symplectic lifted from Q8, Schur index
	P8	2	-2	-1	0	0	0	1	√3	-√3	symplectic faithful. Schur index 2
	On	2	-2	-1	0	0	0	1	-/3	/3	symplectic faithful Schur index 2

Permutation representations of Dic₆

Regular action on 24 points - transitive group 24T5

Dic₆ is a maximal subgroup of

A₄×Q₈ C₄.S₄ C₃²×Q₈ CSU₂(F₅) Dic₆₀: Dic₁₂ Dic₁₈ Dic₃₀ Dic₄₂ Dic₆₆ Dic₇₈ Dic₁₀₂ Dic₁₁₄ ...

 $C_{2p}.D_{6}: C_{24} \times C_{2} D_{4}.S_{3} C_{3} \times Q_{16} C_{4} \cap D_{12} D_{4} \times S_{3} S_{3} \times Q_{8} C_{3}^{2} \times Q_{8} C_{3}^{2} \times Q_{8} \dots$ Dic₆ is a maximal quotient of

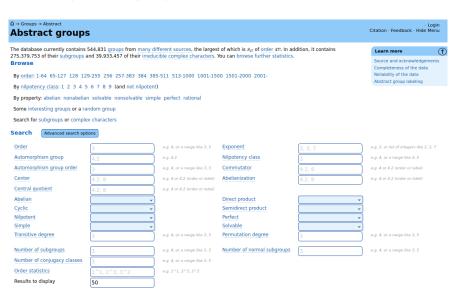
A4×Q8 C3×Q8

 $C_{6}.D_{2p};\; \mathsf{Dic}_{3} \!\!\times\!\! C_{4} \;\; \mathsf{C}_{4} \!\!\times\!\! \mathsf{Dic}_{3} \;\; \mathsf{Dic}_{18} \;\; \mathsf{C}_{3}^{2} \!\!\times_{_{2}} \!\! \mathsf{Q}_{8} \;\; \mathsf{C}_{3}^{2} \!\!\times_{_{4}} \!\! \mathsf{Q}_{8} \;\; \mathsf{C}_{15} \!\!\times\!\! \mathsf{Q}_{8} \;\; \mathsf{Dic}_{30} \;\; \mathsf{C}_{21} \!\!\times\!\! \mathsf{Q}_{8} \ldots$

Matrix representation of Dic_6 -in $GL_2(\mathbb{F}_{11})$ generated by

 $\begin{bmatrix} 2 & 7 \\ 7 & 3 \end{bmatrix} \begin{bmatrix} 0 & 10 \\ 1 & 0 \end{bmatrix}$

LMFDB: https://lmfdb.org/Groups/Abstract/



List of groups

Random group

Display:

Affine groups

Let V be a vector space over a \mathbb{F} . A map $L: V \to V$ is linear if

$$L(c\mathbf{x} + d\mathbf{y}) = cL\mathbf{x} + dL\mathbf{y}$$
, for all $x, y \in V$ and $c, d \in \mathbb{F}$.

If dim $V = n < \infty$, we can write this with an $n \times n$ matrix.

Key point

- A linear map $f: V \to V$ has the form f(x) = Ax.
- An affine map $f: V \to V$ has the form f(x) = Ax + b.

The 1-dimensional general affine group over a field $\mathbb F$ as

$$\mathsf{AGL}_1(\mathbb{F}) = \left\{ \begin{bmatrix} a & b \\ 0 & 1 \end{bmatrix} : a, b \in \mathbb{F}, \ a \neq 0 \right\}.$$

The 2-dimensional general affine group can be defined as

$$\mathsf{AGL}_2(\mathbb{F}) = \left\{ \begin{bmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \\ 0 & 0 & 1 \end{bmatrix} : a_{ij}, b_j \in \mathbb{F}, \ a_{11}a_{22} - a_{12}a_{21} \neq 0 \right\}.$$

We can encode an affine map of an *n*-dimensional space V as an $(n+1)\times(n+1)$ matrix:

$$\mathbf{y} = f(\mathbf{x}) = A\mathbf{x} + \mathbf{b},$$
 as $\begin{bmatrix} \mathbf{y} \\ 1 \end{bmatrix} = \begin{bmatrix} A & \mathbf{b} \\ \mathbf{0} & 1 \end{bmatrix} \begin{bmatrix} \mathbf{x} \\ 1 \end{bmatrix}.$