

Homework 6, due: 03/10

MATH 9830, Spring 2015

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1. Write a program using MPI that sends a token around in a ring pattern from one processor to the next:
 - The token is of type integer starting with the value 0 on rank 0.
 - The token is send from the process with rank i to the process with rank $1 + i$ (wrapping around to 0). Before every send, the value of the token is incremented by one.
 - The process is repeated for three rounds and process 0 announces the current round.
 - Each process prints to the screen when a message is received (include the rank and the token value). Finally, process 0 outputs the final value before exiting.
 - Use `MPI_Barrier` to ensure the output appears in order.

Example output (try to match this):

```
$ mpirun -n 3 ./main
We are having a party with 3 processes!
ROUND 0
process 1 got token = 1 from rank 0
process 2 got token = 2 from rank 1
process 0 got token = 3 from rank 2
ROUND 1
process 1 got token = 4 from rank 0
process 2 got token = 5 from rank 1
process 0 got token = 6 from rank 2
ROUND 2
process 1 got token = 7 from rank 0
process 2 got token = 8 from rank 1
process 0 got token = 9 from rank 2
final answer: 9
```

2. Manufactured solutions in step-5:
 - (a) Make yourself familiar with the concepts in step-5 (documentation, video lectures, read the code).
 - (b) Change the output to vtk and visualize the solutions (submit two images on different mesh levels that elevate the 2d solution and also show the grid – similar to the images in the tutorial).
 - (c) The method of manufactured solutions allows us to check our code for correctness by solving a PDE where we know the answer. We construct this problem by making up the correct solution

$$u_{ref} = \sin(2\pi x) \cos(4\pi y)$$

and computing a function f such that u_{ref} fulfills the PDE. We will choose $a = 0.1$ for the diffusion coefficient everywhere. Show me your f .

- (d) Now change to the diffusion coefficient in the code, change the starting mesh to a `hyper_cube` with 3 initial refinements, and implement a class `Solution` (derived from `Function<dim>` like `Coefficient`) with the answer above. Change the boundary conditions to use the `Solution` class (we obviously need the correct boundary conditions!). Check your results visually.

- (e) deal.II allows you to compute the error $\|u - u_{ref}\|_0$ between a given reference and the computed solution:

```
Vector<float> difference_per_cell ( triangulation.n_active_cells ());
VectorTools::integrate_difference ( dof_handler ,
                                  solution ,
                                  Solution<dim>(),
                                  difference_per_cell ,
                                  QGauss<dim>(3),
                                  VectorTools::L2_norm);
double L2_error = difference_per_cell.l2_norm ();
```

You will need to include `<deal.II/numerics/error_estimator.h>`.

Create a table with the refinement level (1-5) and the L2 error and check that the convergence order is consistent with the finite element theory.